

PHYS 1441 – Section 002

Lecture #7

Wednesday, Feb. 6, 2008

Dr. Jaehoon Yu

- Motion in Two Dimension
 - Motion under constant acceleration
 - Vector recap
 - Projectile Motion
 - Maximum ranges and heights



Announcements

- 1st term exam on Wednesday, Feb. 20
 - Time: 1 – 2:20pm
 - Place: SH103
 - Covers: Appendices, CH 1 – what we learn till next Wednesday, Feb. 13
 - Class on Monday, Feb. 18: Jason will be here to go over the any problems you would like to review
- Colloquium
 - Today at 4pm in SH101, following the refreshment at 3:30pm in SH108
 - Please be sure to sign in the sign-in sheet



**Physics Department
The University of Texas at Arlington
COLLOQUIUM**

Gravitational Wave Astronomy: will it ever exist?

**Dr. Mario Diaz
University of Texas at Brownsville**

**4:00 pm Wednesday, February 6, 2007
Room 101 SH**

Abstract

In this talk I review the current status of the field of gravitational wave detection and its potential for utilization in astrophysics. I will report particularly on the results of observations with more than a year of LIGO interferometers operating at design sensitivity. I will discuss the meaning of the upper limit studies performed with these results and its impact on astronomical observations. I will also talk about the existing collaborations among different gravitational wave observatories throughout the world and how different interferometers are integrated to operate as a network. I will finally discuss plans for future detectors including Enhanced LIGO, Advanced LIGO and space based interferometers like LISA.

Refreshments will be served in the Physics Library at 3:30 pm

Kinematic Quantities in 1D and 2D

Quantities	1 Dimension	2 Dimension
Displacement	$\Delta x = x_f - x_i$	$\Delta \vec{r} = \vec{r}_f - \vec{r}_i$
Average Velocity	$v_x = \frac{\Delta x}{\Delta t} = \frac{x_f - x_i}{t_f - t_i}$	$\vec{v} \equiv \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}$
Inst. Velocity	$v_x \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$	$\vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t}$
Average Acc.	$a_x \equiv \frac{\Delta v_x}{\Delta t} = \frac{v_{xf} - v_{xi}}{t_f - t_i}$	$\vec{a} \equiv \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_f - \vec{v}_i}{t_f - t_i}$
Inst. Acc.	$a_x \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta v_x}{\Delta t}$	$\vec{a} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t}$

Kinematic Equations

$$v = v_o + at$$

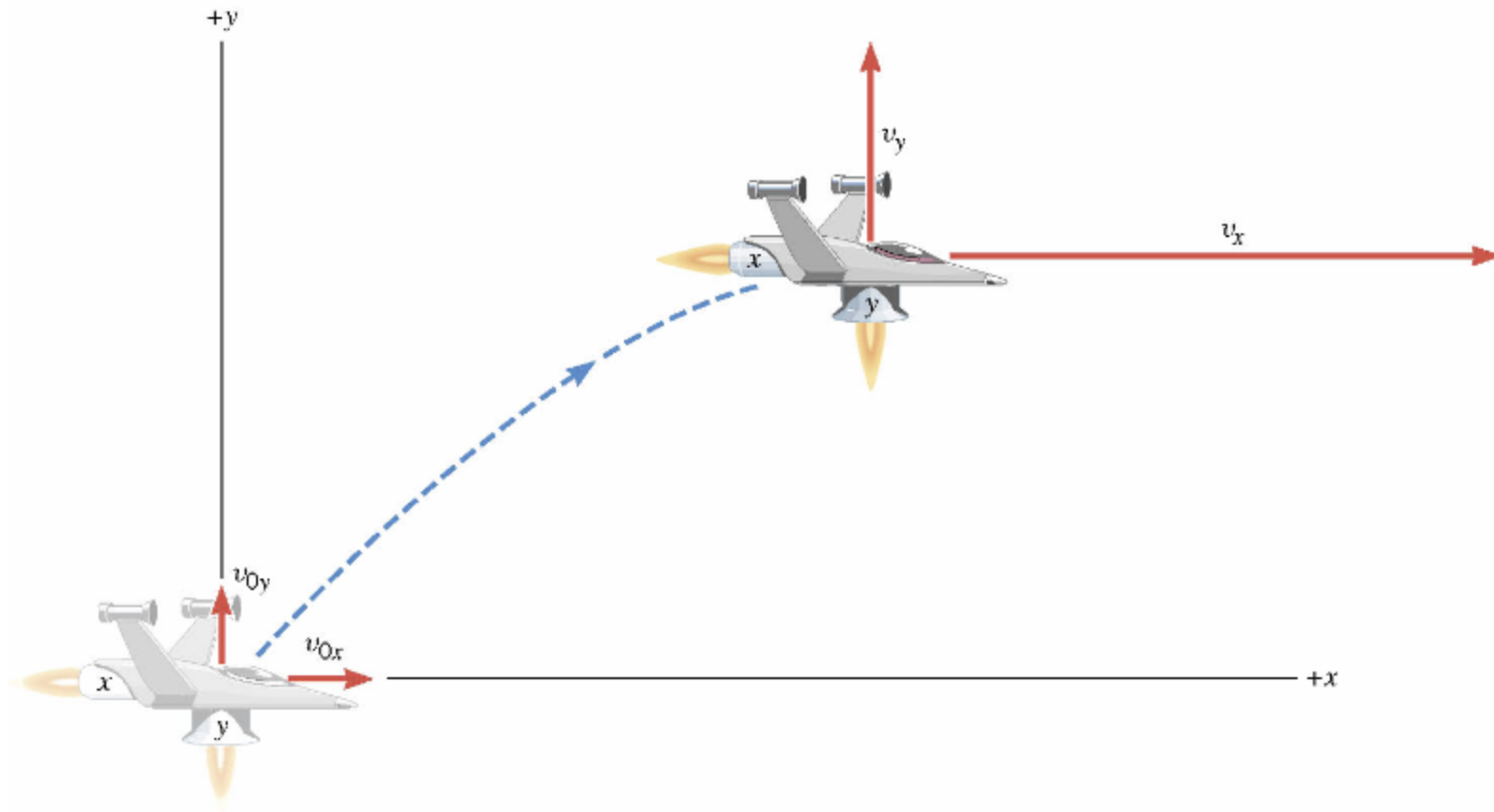
$$x = \frac{1}{2}(v_o + v)t$$

$$v^2 = v_o^2 + 2ax$$

$$x = v_o t + \frac{1}{2}at^2$$

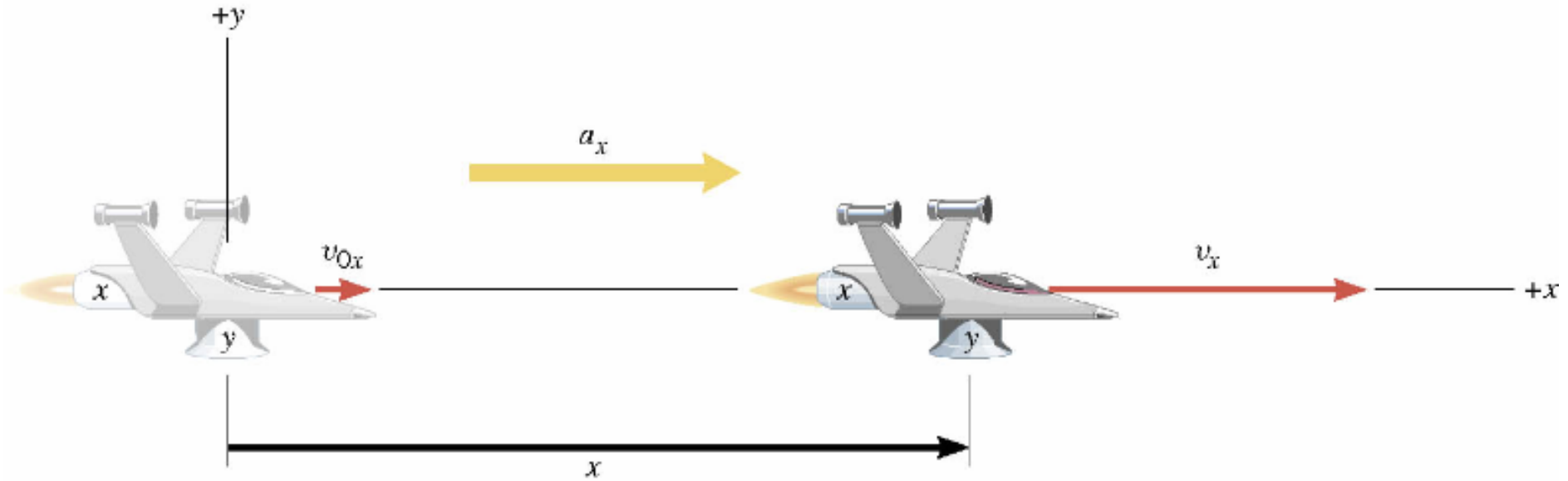


A Motion in 2 Dimension



This is a motion that could be viewed as two motions combined into one.

Motion in horizontal direction (x)



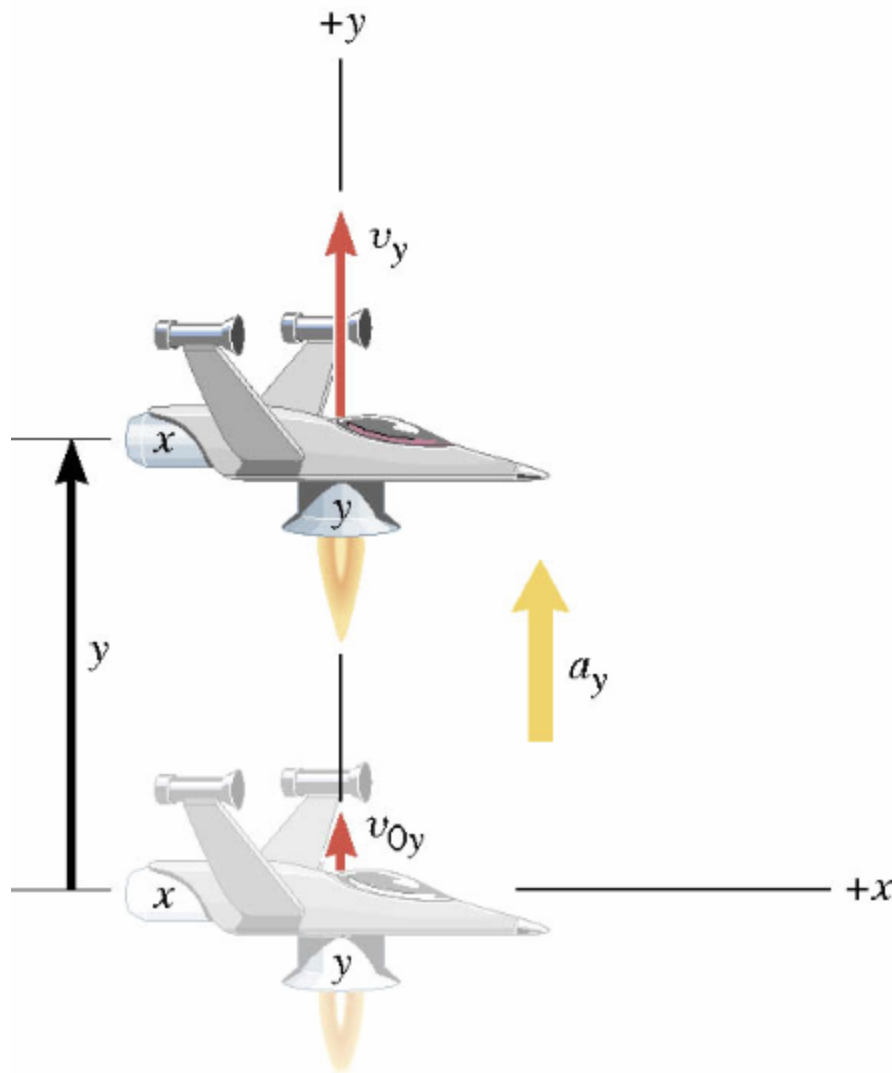
$$v_x = v_{x0} + a_x t$$

$$x = \frac{1}{2} (v_{x0} + v_x) t$$

$$v_x^2 = v_{x0}^2 + 2a_x x$$

$$x = v_{x0} t + \frac{1}{2} a_x t^2$$

Motion in vertical direction (y)



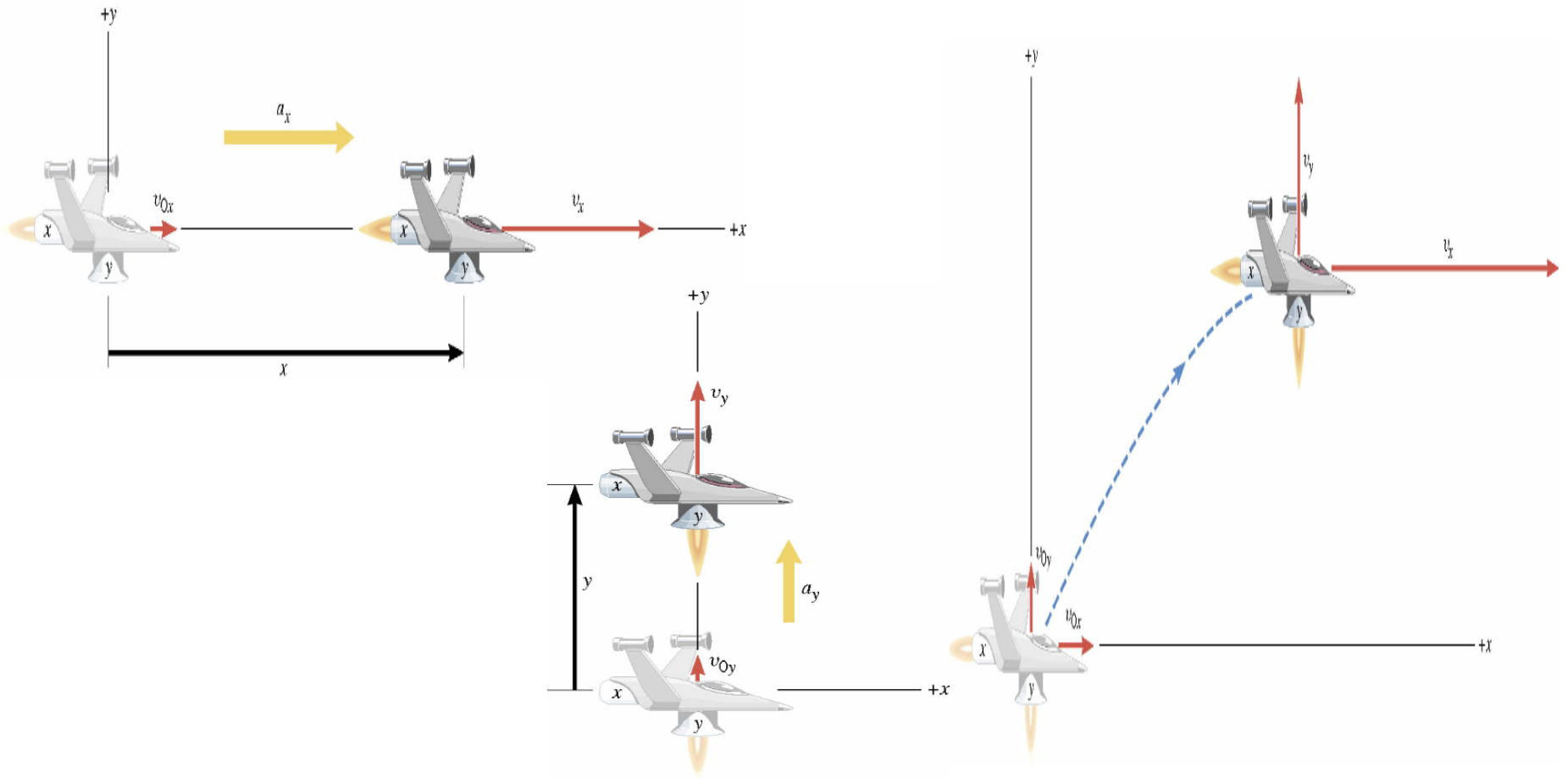
$$v_y = v_{y0} + a_y t$$

$$y = \frac{1}{2} (v_{y0} + v_y) t$$

$$v_y^2 = v_{y0}^2 + 2a_y y$$

$$y = v_{y0} t + \frac{1}{2} a_y t^2$$

A Motion in 2 Dimension



Imagine you add the two 1 dimensional motions on the left. It would make up a one 2 dimensional motion on the right.

Kinematic Equations in 2-Dim

x-component

$$v_x = v_{x0} + a_x t$$

$$x = \frac{1}{2} (v_{x0} + v_x) t$$

$$v_x^2 = v_{x0}^2 + 2a_x x$$

$$x = v_{x0} t + \frac{1}{2} a_x t^2$$

y-component

$$v_y = v_{y0} + a_y t$$

$$y = \frac{1}{2} (v_{y0} + v_y) t$$

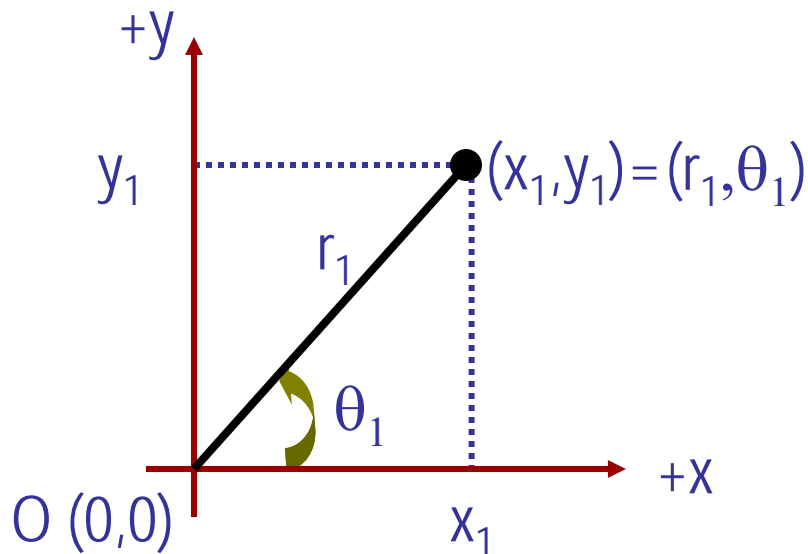
$$v_y^2 = v_{y0}^2 + 2a_y y$$

$$y = v_{y0} t + \frac{1}{2} a_y t^2$$



Coordinate Systems

- They make it easy and consistent to express locations or positions
- Two commonly used systems, depending on convenience, are
 - Cartesian (Rectangular) Coordinate System
 - Coordinates are expressed in (x,y)
 - Polar Coordinate System
 - Coordinates are expressed in distance from the origin $^{\circ}$ and the angle measured from the x-axis, θ (r,θ)
- Vectors become a lot easier to express and compute



How are Cartesian and Polar coordinates related?

$$x_1 = r_1 \cos \theta_1 \quad r_1 = \sqrt{(x_1^2 + y_1^2)}$$

$$y_1 = r_1 \sin \theta_1 \quad \tan \theta_1 = \frac{y_1}{x_1}$$

$$\theta_1 = \tan^{-1} \left(\frac{y_1}{x_1} \right) \quad 11$$

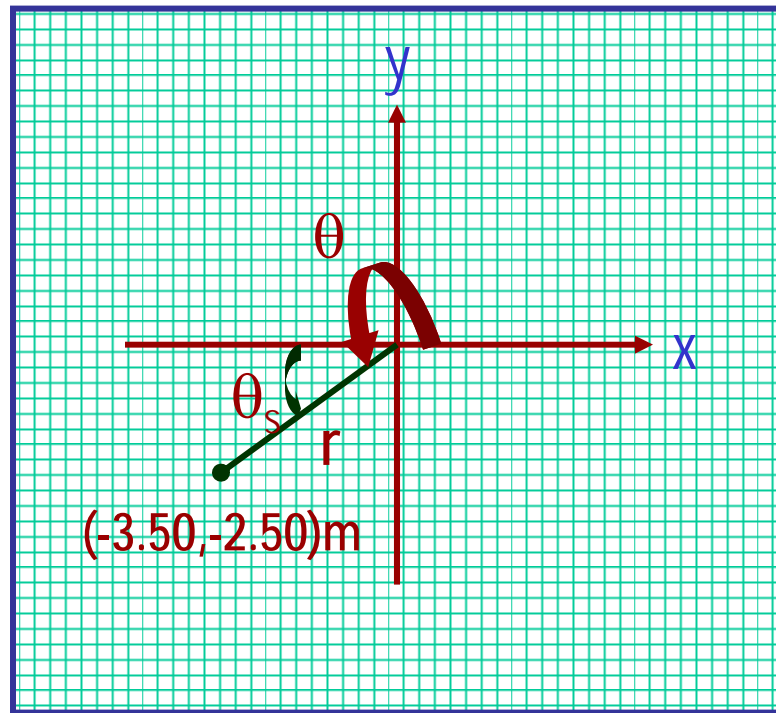
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Example

Cartesian Coordinate of a point in the xy plane are $(x,y) = (-3.50, -2.50)\text{m}$. Find the equivalent polar coordinates of this point.



$$\begin{aligned} r &= \sqrt{(x^2 + y^2)} \\ &= \sqrt{((-3.50)^2 + (-2.50)^2)} \\ &= \sqrt{18.5} = 4.30(m) \end{aligned}$$

$$\theta = 180 + \theta_s$$

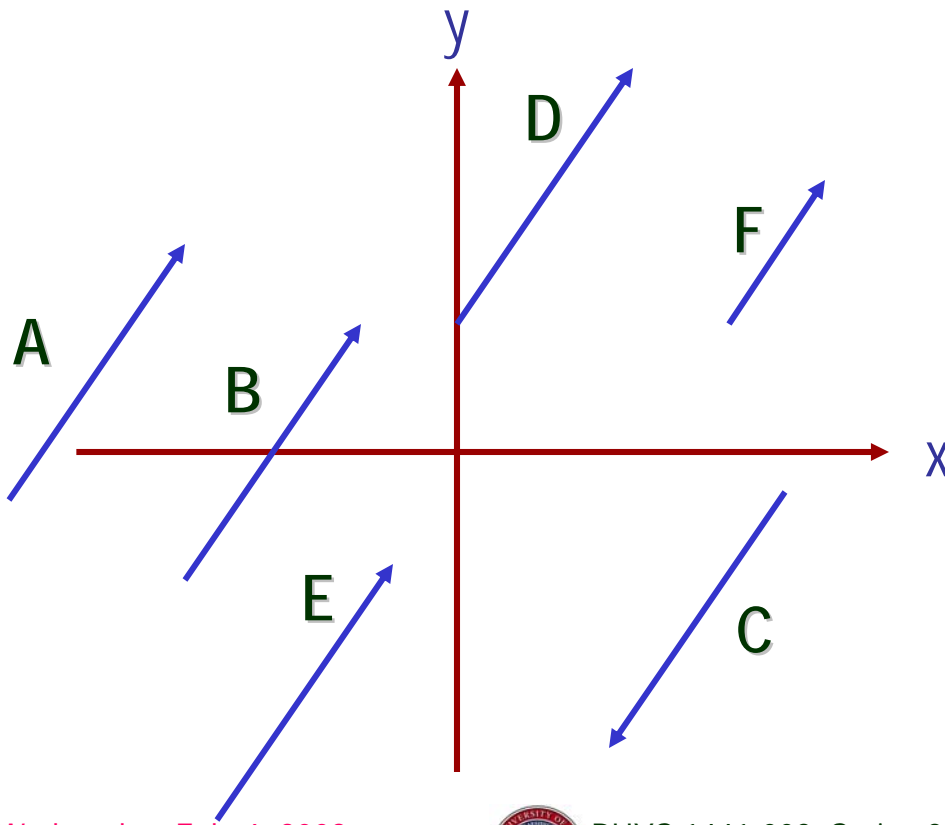
$$\tan \theta_s = \frac{-2.50}{-3.50} = \frac{5}{7}$$

$$\theta_s = \tan^{-1}\left(\frac{5}{7}\right) = 35.5^\circ$$

$$\therefore \theta = 180 + \theta_s = 180^\circ + 35.5^\circ = 216^\circ$$

Properties of Vectors

- Two vectors are the same if their sizes and the directions are the same, no matter where they are on a coordinate system!!



Which ones are the same vectors?

$A=B=E=D$

Why aren't the others?

C: The same magnitude but opposite direction:
 $C=-A$: A negative vector

F: The same direction but different magnitude

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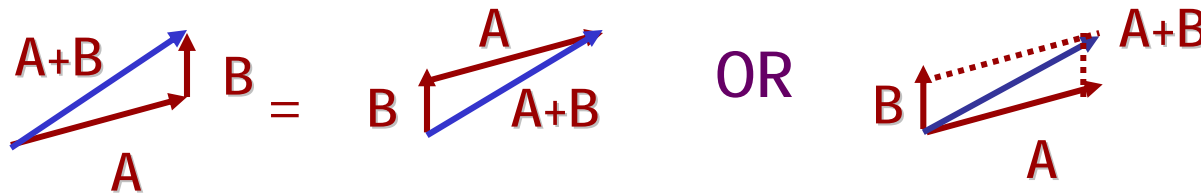


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Vector Operations

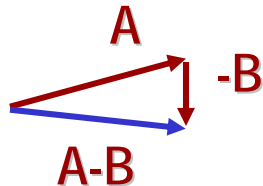
- Addition:

- Triangular Method: One can add vectors by connecting the head of one vector to the tail of the other (head-to-tail)
- Parallelogram method: Connect the tails of the two vectors and extend
- Addition is commutative: Changing order of operation does not affect the results
 $A+B=B+A$, $A+B+C+D+E=E+C+A+B+D$



- Subtraction:

- The same as adding a negative vector: $A - B = A + (-B)$



Since subtraction is the equivalent to adding a negative vector, subtraction is also commutative!!!

- Multiplication by a scalar is increasing the magnitude A , $B=2A$

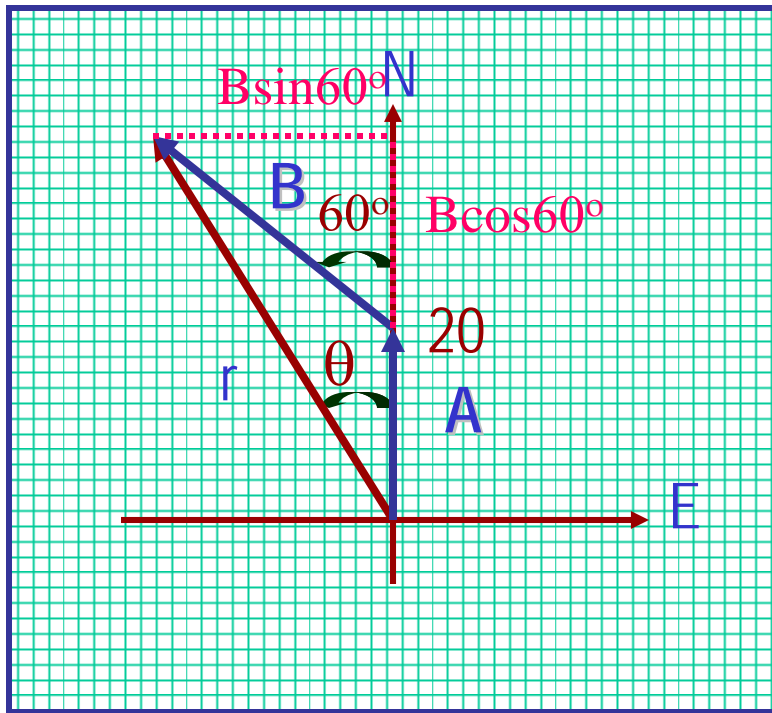


Wedne $|B| = 2|A|$



Example for Vector Addition

A car travels 20.0km due north followed by 35.0km in a direction 60.0° west of north. Find the magnitude and direction of resultant displacement.



$$\begin{aligned}
 r &= \sqrt{(A + B \cos \theta)^2 + (B \sin \theta)^2} \\
 &= \sqrt{A^2 + B^2 (\cos^2 \theta + \sin^2 \theta) + 2AB \cos \theta} \\
 &= \sqrt{A^2 + B^2 + 2AB \cos \theta} \\
 &= \sqrt{(20.0)^2 + (35.0)^2 + 2 \times 20.0 \times 35.0 \cos 60} \\
 &= \sqrt{2325} = 48.2(\text{km})
 \end{aligned}$$

$$\begin{aligned}
 \theta &= \tan^{-1} \frac{|\vec{B}| \sin 60}{|\vec{A}| + |\vec{B}| \cos 60} \\
 &= \tan^{-1} \frac{35.0 \sin 60}{20.0 + 35.0 \cos 60} \\
 &= \tan^{-1} \frac{30.3}{37.5} = 38.9^\circ \text{ to W wrt N}
 \end{aligned}$$

Find other ways to solve this problem...