PHYS 1443 – Section 001 Lecture #3

Thursday, June 1, 2006 Dr. Jaehoon Yu

- One Dimensional Motion:
 - Motion under constant acceleration
 - Free Fall
- Motion in Two Dimensions
 - Vector Properties and Operations
 - Motion under constant acceleration
 - Projectile Motion

Today's homework is HW #2, due 7pm, Monday, June 5!!

Announcements

- Reading assignment #2: Read section 2.8
- Ten of you have registered for the homework
 - Seven of you submitted #1
 - You MUST register and submit the homework to obtain 100% of the credit...
- The class e-mail distribution list is available as of yesterday
 - Please go ahead and subscribe to the list
 - Phys1443-001-summer06
 - Extra credit
 - 5 points if done by Tuesday, June 6
 - 3 points if done by Thursday, June 8

Acceleration

Change of velocity in time (what kind of quantity is this?)

•Average acceleration:

$$a_x \equiv \frac{v_{xf} - v_{xi}}{t_f - t_i} = \frac{\Delta v_x}{\Delta t}$$
 analogs to $v_x \equiv \frac{x_f - x_i}{t_f - t_i} = \frac{\Delta x}{\Delta t}$

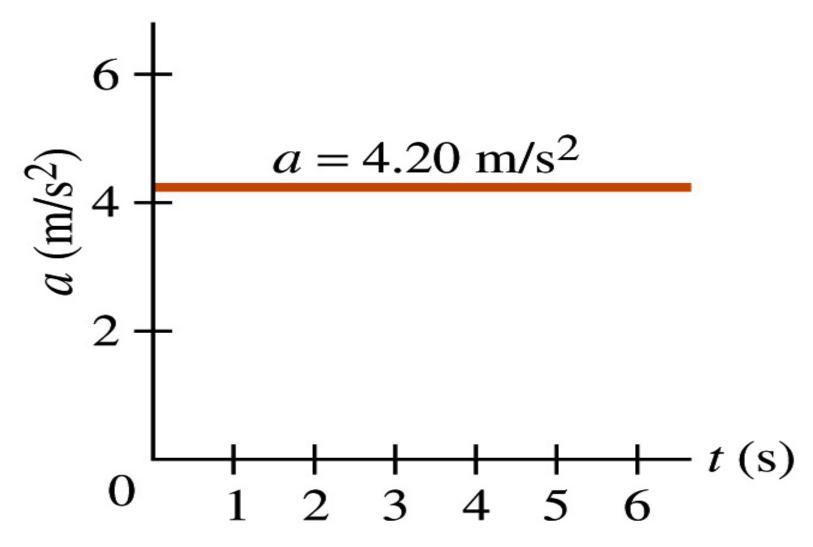
Instantaneous acceleration:

$$a_x = \lim_{\Delta t \to 0} \frac{\Delta v_x}{\Delta t} = \frac{dv_x}{dt} = \frac{d}{dt} \left(\frac{dx}{dt}\right) = \frac{d^2x}{dt^2}$$
 analogs to $v_x = \lim_{\Delta t \to 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$

$$v_x \equiv \lim_{\Delta t \to 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

 In calculus terms: The slope (derivative) of the velocity vector with respect to time or the change of slopes of position as a function of time

Acceleration vs Time Plot



Meanings of Acceleration

- When an object is moving in a constant velocity $(v=v_0)$, there is no acceleration (a=0)
 - Is there any acceleration when an object is not moving?
- When an object speeds up as time goes on, (v=v(t)), acceleration has the same sign as v.
- When an object slows down as time goes on, (v=v(t)), acceleration has the opposite sign as v.
- Is there acceleration if an object moves in a constant speed but changes direction? YES!!

One Dimensional Motion

- Let's start with the simplest case: acceleration is constant $(a=a_0)$
- Using definitions of average acceleration and velocity, we can draw equation of motion (description of motion, position wrt time)

$$a_x = \frac{v_{xf} - v_{xi}}{t_f - t_i} \quad \text{If } t_f = t \text{ and } t_i = 0 \qquad a_x = \frac{v_{xf} - v_{xi}}{t} \quad \text{Solve for } v_{xf} \qquad v_{xf} = v_{xi} + a_x t$$

For constant acceleration, simple numeric average

$$\overline{v_x} = \frac{v_{xi} + v_{xf}}{2} = \frac{2v_{xi} + a_x t}{2} = v_{xi} + \frac{1}{2}a_x t$$

$$\overline{v_x} = \frac{x_f - x_i}{t_f - t_i} = \frac{x_f - x_i}{t}$$
Solve for x_f

$$x_f = x_i + \overline{v_x}t$$

Resulting Equation of Motion becomes

$$x_f = x_{i} + \overline{v_x}t = x_{i} + v_{xi}t + \frac{1}{2}a_xt^2$$

Kinematic Equations of Motion on a Straight Line Under Constant Acceleration

$$v_{xf}(t) = v_{xi} + a_x t$$

Velocity as a function of time

$$x_f - x_i = \frac{1}{2} \overline{v}_x t = \frac{1}{2} (v_{xf} + v_{xi}) t$$

Displacement as a function of velocities and time

$$x_f = x_i + v_{xi}t + \frac{1}{2}a_xt^2$$

Displacement as a function of time, velocity, and acceleration

$$v_{xf}^2 = v_{xi}^2 + 2a_x(x_f - x_i)$$

Velocity as a function of Displacement and acceleration

You may use different forms of Kinetic equations, depending on the information given to you for specific physical problems!!

How do we solve a problem using a kinematic formula for constant acceleration?

- Identify what information is given in the problem.
 - Initial and final velocity?
 - Acceleration?
 - Distance?
 - Time?
- Convert the units of all quantities to SI units to be consistent.
- Identify what the problem wants.
- Identify which kinematic formula is appropriate and easiest to solve for what the problem wants.
 - Frequently multiple formulae can give you the answer for the quantity you are looking for. → Do not just use any formula but use the one that can be easiest to solve.
- Solve the equation for the quantity wanted.



Example 2.11

Suppose you want to design an air-bag system that can protect the driver in a headon collision at a speed 100km/hr (~60miles/hr). Estimate how fast the air-bag must inflate to effectively protect the driver. Assume the car crumples upon impact over a distance of about 1m. How does the use of a seat belt help the driver?

How long does it take for the car to come to a full stop? As long as it takes for it to crumple.

The initial speed of the car is
$$v_{xi} = 100km/h = \frac{100000m}{3600s} = 28m/s$$

We also know that
$$v_{xf} = 0m/s$$
 and $x_f - x_i = 1m$

Using the kinematic formula
$$|v_{xf}|^2 = |v_{xi}|^2 + 2a_x(x_f - x_i)$$

The acceleration is
$$a_x = \frac{v_{xf}^2 - v_{xi}^2}{2(x_f - x_i)} = \frac{0 - (28m/s)^2}{2 \times 1m} = -390m/s^2$$
Thus the time for air-bag to deploy is $t = \frac{v_{xf} - v_{xi}}{a} = \frac{0 - 28m/s}{-390m/s^2} = 0.07s$

$$t = \frac{v_{xf} - v_{xi}}{a} = \frac{0 - 28m/s}{-390m/s^2} = 0.07s$$

Free Fall

- Free fall is a motion under the influence of gravitational pull (gravity) only; Which direction is a freely falling object moving?
 - A motion under constant acceleration

Down to the center of the Earth!

- All kinematic formulae we learned can be used to solve for falling motions.
- Gravitational acceleration is inversely proportional to the distance between the object and the center of the earth
- The magnitude of the gravitational acceleration is
 |g|=9.80m/s² on the surface of the Earth, most of the time.
- The direction of gravitational acceleration is <u>ALWAYS</u> toward the center of the earth, which we normally call (-y); where up and down directions are indicated with the variable "y"
- Thus the correct denotation of gravitational acceleration on the surface of the earth is g₊(-)9.80m/s²

Example for Using 1D Kinematic Equations on a Falling object

Stone was thrown straight upward at t=0 with +20.0m/s initial velocity on the roof of a 50.0m high building,

What is the acceleration in this motion? $g=-9.80 \text{m/s}^2$

(a) Find the time the stone reaches at the maximum height. What is so special about the maximum height?

$$v_f = v_{yi} + a_y t = +20.0 - 9.80t = 0.00 m/s$$
 Solve for $t = \frac{20.0}{9.80} = 2.04s$

(b) Find the maximum height.

$$y_f = y_i + v_{yi}t + \frac{1}{2}a_yt^2 = 50.0 + 20 \times 2.04 + \frac{1}{2} \times (-9.80) \times (2.04)^2$$
$$= 50.0 + 20.4 = 70.4(m)$$

Example of a Falling Object cnt'd

(c) Find the time the stone reaches back to its original height.

$$t = 2.04 \times 2 = 4.08s$$

(d) Find the velocity of the stone when it reaches its original height.

$$v_{yf} = v_{yi} + a_y t = 20.0 + (-9.80) \times 4.08 = -20.0 (m/s)$$

(e) Find the velocity and position of the stone at t=5.00s.

Velocity

$$v_{yf} = v_{yi} + a_y t = 20.0 + (-9.80) \times 5.00 = -29.0 (m/s)$$

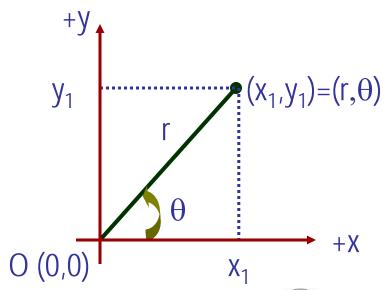
$$y_f = y_i + v_{yi}t + \frac{1}{2}a_yt^2$$

Position

=
$$50.0 + 20.0 \times 5.00 + \frac{1}{2} \times (-9.80) \times (5.00)^2 = +27.5(m)$$

Coordinate Systems

- They make it easy to express locations or positions
- Two commonly used systems, depending on convenience, are
 - Cartesian (Rectangular) Coordinate System
 - Coordinates are expressed in (x,y)
 - Polar Coordinate System
 - Coordinates are expressed in (r,θ)
- Vectors become a lot easier to express and compute



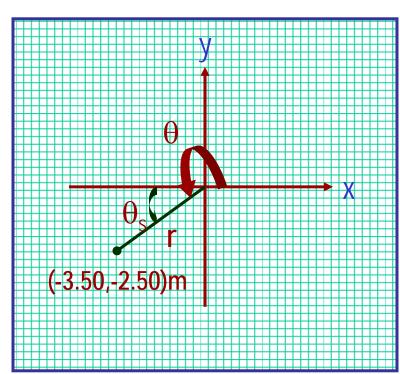
How are Cartesian and Polar coordinates related?

$$x_1 = r \cos \theta \qquad r = \sqrt{(x_1^2 + y_1^2)^2}$$

$$y_1 = r \sin \theta \qquad \tan \theta = \frac{y_1}{x_1}$$

Example

Cartesian Coordinate of a point in the xy plane are (x,y)=(-3.50,-2.50)m. Find the equivalent polar coordinates of this point.



$$r = \sqrt{(x^2 + y^2)}$$

$$= \sqrt{((-3.50)^2 + (-2.50)^2)}$$

$$= \sqrt{18.5} = 4.30(m)$$

$$\theta = 180 + \theta_s$$
 $\tan \theta_s = \frac{-2.50}{-3.50} = \frac{5}{7}$

$$\theta_s = \tan^{-1}\left(\frac{5}{7}\right) = 35.5^\circ$$

$$\theta = 180 + \theta_s = 180^{\circ} + 35.5^{\circ} = 216^{\circ}$$

Vector and Scalar

Vector quantities have both magnitudes (sizes)

and directions

Force, gravitational acceleration, momentum

Normally denoted in **BOLD** letters, \mathcal{F} , or a letter with arrow on top \mathcal{F} Their sizes or magnitudes are denoted with normal letters, \mathcal{F}_{i} or absolute values: $|\vec{r}|$ or $|\mathcal{F}|$

Scalar quantities have magnitudes only Can be completely specified with a value and its unit

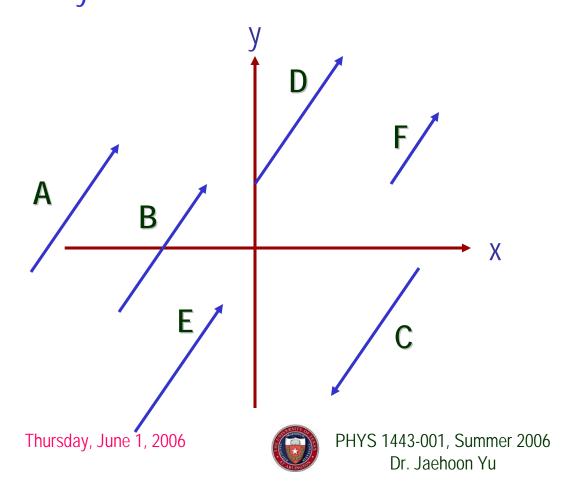
Normally denoted in normal letters, £

Both have units!!!



Properties of Vectors

 Two vectors are the same if their sizes and the directions are the same, no matter where they are on a coordinate system!!



Which ones are the same vectors?

A=B=E=D

Why aren't the others?

C: The same magnitude but opposite direction:

C=-A:A negative vector

F: The same direction but different magnitude

Vector Operations

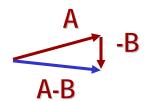
Addition:

- Triangular Method: One can add vectors by connecting the head of one vector to the tail of the other (head-to-tail)
- Parallelogram method: Connect the tails of the two vectors and extend
- Addition is commutative: Changing order of operation does not affect the results
 A+B=B+A, A+B+C+D+E=E+C+A+B+D



Subtraction:

- The same as adding a negative vector: $\mathbf{A} - \mathbf{B} = \mathbf{A} + (-\mathbf{B})$



Since subtraction is the equivalent to adding a negative vector, subtraction is also commutative!!!

 Multiplication by a scalar is increasing the magnitude A, B=2A





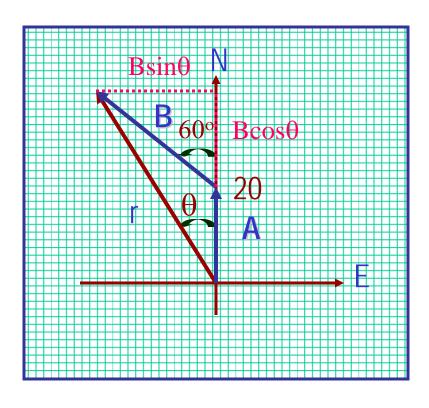
Thursd $|\mathcal{B}| = 2|\mathcal{A}|$



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Example for Vector Addition

A car travels 20.0km due north followed by 35.0km in a direction 60.0° west of north. Find the magnitude and direction of resultant displacement.



$$r = \sqrt{(A + B\cos\theta)^2 + (B\sin\theta)^2}$$

$$= \sqrt{A^2 + B^2(\cos^2\theta + \sin^2\theta) + 2AB\cos\theta}$$

$$= \sqrt{A^2 + B^2 + 2AB\cos\theta}$$

$$= \sqrt{(20.0)^2 + (35.0)^2 + 2 \times 20.0 \times 35.0\cos60}$$

$$= \sqrt{2325} = 48.2(km)$$

$$\theta = \tan^{-1} \frac{|\vec{B}| \sin 60}{|\vec{A}| + |\vec{B}| \cos 60}$$

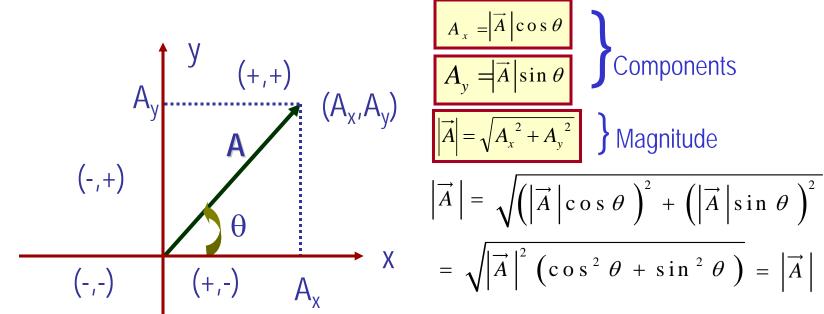
$$= \tan^{-1} \frac{35.0 \sin 60}{20.0 + 35.0 \cos 60}$$

$$= \tan^{-1} \frac{30.3}{37.5} = 38.9^{\circ} \text{ to W wrt N}$$

Find other ways to solve this problem...

Components and Unit Vectors

Coordinate systems are useful in expressing vectors in their components



- Unit vectors are dimensionless vectors whose magnitude are exactly 1
 - Unit vectors are usually expressed in i, j, k or \vec{i} , \vec{j} , \vec{k}
 - Vectors can be expressed using components and unit vectors

So the above vector A can be written as

$$\vec{A} = A_x \vec{i} + A_y \vec{j} = |\vec{A}| \cos \theta \vec{i} + |\vec{A}| \sin \theta \vec{j}$$



Examples of Vector Operations

Find the resultant vector which is the sum of $\mathbf{A}=(2.0\mathbf{i}+2.0\mathbf{j})$ and $\mathbf{B}=(2.0\mathbf{i}-4.0\mathbf{j})$

$$\vec{C} = \vec{A} + \vec{B} = (2.0\vec{i} + 2.0\vec{j}) + (2.0\vec{i} - 4.0\vec{j})$$

$$= (2.0 + 2.0)\vec{i} + (2.0 - 4.0)\vec{j} = 4.0\vec{i} - 2.0\vec{j}(m)$$

$$|\vec{C}| = \sqrt{(4.0)^2 + (-2.0)^2}$$

$$= \sqrt{16 + 4.0} = \sqrt{20} = 4.5(m)$$

$$\theta = \tan^{-1} \frac{C_y}{C_x} = \tan^{-1} \frac{-2.0}{4.0} = -27^\circ$$

Find the resultant displacement of three consecutive displacements: $d_1=(15i+30j+12k)cm$, $d_2=(23i+14j-5.0k)cm$, and $d_3=(-13i+15j)cm$

$$\vec{D} = \vec{d}_1 + \vec{d}_2 + \vec{d}_3 = (15\vec{i} + 30\vec{j} + 12\vec{k}) + (23\vec{i} + 14\vec{j} - 5.0\vec{k}) + (-13\vec{i} + 15\vec{j})$$

$$= (15 + 23 - 13)\vec{i} + (30 + 14 + 15)\vec{j} + (12 - 5.0)\vec{k} = 25\vec{i} + 59\vec{j} + 7.0\vec{k}(cm)$$

Magnitude
$$|\vec{D}| = \sqrt{(25)^2 + (59)^2 + (7.0)^2} = 65(cm)$$

Displacement, Velocity, and Acceleration in 2-dim

Displacement:

$$\Delta \vec{r} = \vec{r}_f - \vec{r}_i$$

Average Velocity:

$$\vec{v} \equiv \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}$$

Instantaneous Velocity:

$$\vec{v} \equiv \lim_{\Delta t \to 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d \vec{r}}{d t}$$

How is each of these quantities defined in 1-D?

- Average
 - **Acceleration**

Instantaneous **Acceleration:**

$$\vec{a} \equiv \lim_{\Delta t \to 0} \frac{\vec{\Delta v}}{\Delta t} = \frac{d\vec{v}}{dt} = \frac{d}{dt} \left(\frac{d\vec{r}}{dt} \right) = \frac{d^2\vec{r}}{dt^2}$$