

PHYS 1443 – Section 001

Lecture #4

Monday, June 4, 2007

Dr. Jaehoon Yu

- Coordinate System
- Vectors and Scalars
- Motion in Two Dimensions
 - Motion under constant acceleration
 - Projectile Motion
 - Maximum ranges and heights
- Reference Frames and relative motion



Announcements

- All of you but one have registered for the homework
 - Good job!!!
- Mail distribution list
 - As of this morning there were 15 of you on the list
 - 7 more to go!!
 - Extra credit
 - 5 points if done by Today, June 4
 - 3 points if done by Wednesday, June 6



Displacement, Velocity and Speed

Displacement

$$\Delta x \equiv x_f - x_i$$

Average velocity

$$v_x \equiv \frac{x_f - x_i}{t_f - t_i} = \frac{\Delta x}{\Delta t}$$

Average speed

$$v \equiv \frac{\text{Total Distance Traveled}}{\text{Total Time Spent}}$$

Instantaneous velocity

$$v_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

Instantaneous speed

$$|v_x| = \left| \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} \right| = \left| \frac{dx}{dt} \right|$$



1D Kinematic Equations of Motion on a Straight Line Under Constant Acceleration

$$v_{xf}(t) = v_{xi} + a_x t$$

Velocity as a function of time

$$x_f - x_i = \frac{1}{2} \bar{v}_x t = \frac{1}{2} (v_{xf} + v_{xi}) t$$

Displacement as a function of velocities and time

$$x_f = x_i + v_{xi} t + \frac{1}{2} a_x t^2$$

Displacement as a function of time, velocity, and acceleration

$$v_{xf}^2 = v_{xi}^2 + 2a_x(x_f - x_i)$$

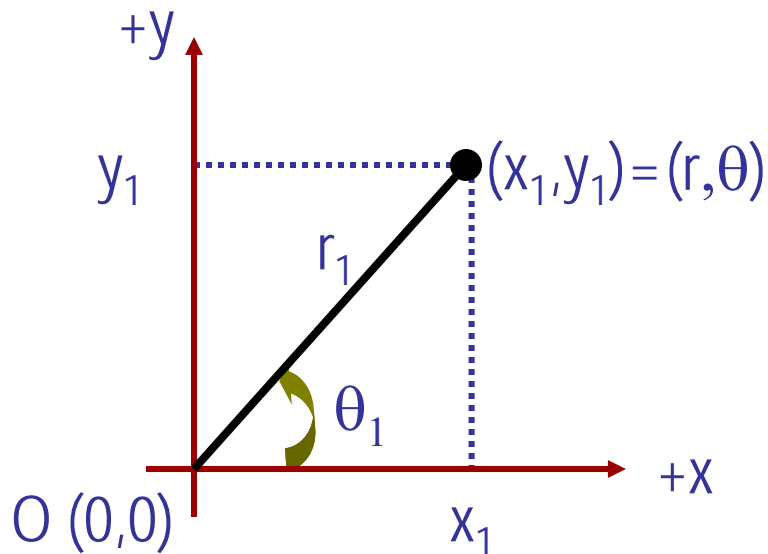
Velocity as a function of Displacement and acceleration

You may use different forms of Kinetic equations, depending on the information given to you for specific physical problems!!



Coordinate Systems

- They make it easy and consistent to express locations or positions
- Two commonly used systems, depending on convenience, are
 - Cartesian (Rectangular) Coordinate System
 - Coordinates are expressed in (x,y)
 - Polar Coordinate System
 - Coordinates are expressed in distance from the origin [®] and the angle measured from the x-axis, θ (r, θ)
- Vectors become a lot easier to express and compute



How are Cartesian and Polar coordinates related?

$$x_1 = r_1 \cos \theta_1 \quad r_1 = \sqrt{(x_1^2 + y_1^2)}$$

$$y_1 = r_1 \sin \theta_1 \quad \tan \theta_1 = \frac{y_1}{x_1}$$

$$\theta_1 = \tan^{-1} \left(\frac{y_1}{x_1} \right) \quad 5$$

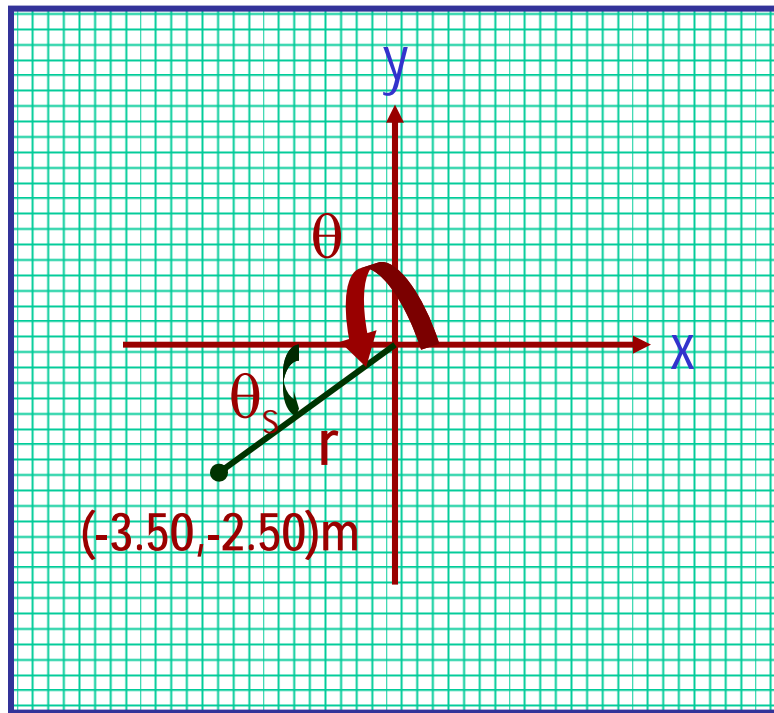
Monday, June 4, 2007



PHYS 1443-001, Summer 2007
Dr. Jaehoon Yu

Example

Cartesian Coordinate of a point in the xy plane are $(x,y) = (-3.50, -2.50)\text{m}$. Find the equivalent polar coordinates of this point.



$$\begin{aligned} r &= \sqrt{(x^2 + y^2)} \\ &= \sqrt{((-3.50)^2 + (-2.50)^2)} \\ &= \sqrt{18.5} = 4.30(m) \end{aligned}$$

$$\theta = 180 + \theta_s$$

$$\tan \theta_s = \frac{-2.50}{-3.50} = \frac{5}{7}$$

$$\theta_s = \tan^{-1}\left(\frac{5}{7}\right) = 35.5^\circ$$

$$\therefore \theta = 180 + \theta_s = 180^\circ + 35.5^\circ = 216^\circ$$

Vector and Scalar

Vector quantities have both magnitudes (sizes) and directions

Force, gravitational acceleration, momentum

Normally denoted in **BOLD** letters, \mathbf{F} , or a letter with arrow on top \vec{F}

Their sizes or magnitudes are denoted with normal letters, F , or absolute values: $|\vec{F}|$ or $|\mathbf{F}|$

Scalar quantities have magnitudes only

Can be completely specified with a value and its unit

Normally denoted in normal letters, E

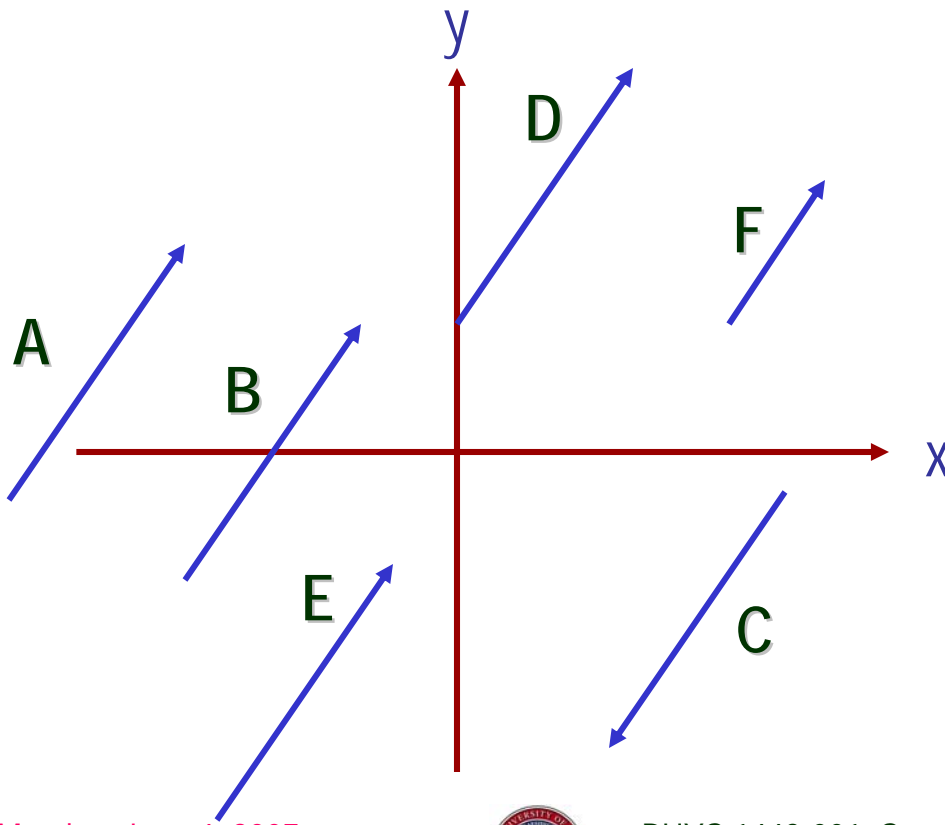
Energy, heat, mass, weight

Both have units!!!



Properties of Vectors

- Two vectors are the same if their sizes and the directions are the same, no matter where they are on a coordinate system!!



Which ones are the same vectors?

$A=B=E=D$

Why aren't the others?

C: The same magnitude but opposite direction:
 $C=-A$: A negative vector

F: The same direction but different magnitude

Monday, June 4, 2007

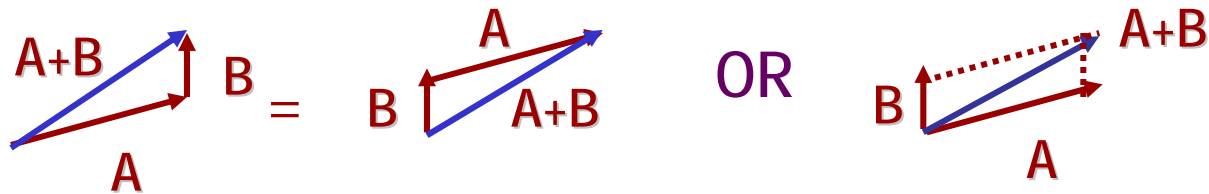


PHYS 1443-001, Summer 2007
Dr. Jaehoon Yu

Vector Operations

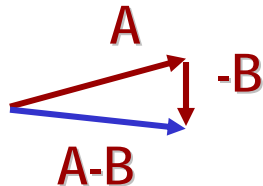
- Addition:

- Triangular Method: One can add vectors by connecting the head of one vector to the tail of the other (head-to-tail)
- Parallelogram method: Connect the tails of the two vectors and extend
- Addition is commutative: Changing order of operation does not affect the results
 $A+B=B+A$, $A+B+C+D+E=E+C+A+B+D$



- Subtraction:

- The same as adding a negative vector: $A - B = A + (-B)$



Since subtraction is the equivalent to adding a negative vector, subtraction is also commutative!!!

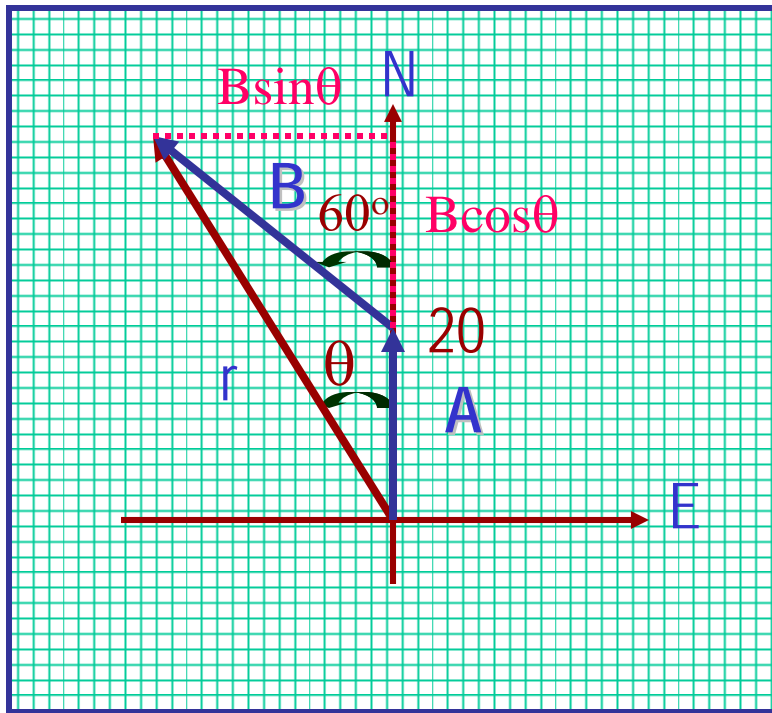
- Multiplication by a scalar is increasing the magnitude A , $B=2A$

Monda $|B| = 2|A|$



Example for Vector Addition

A car travels 20.0km due north followed by 35.0km in a direction 60.0° west of north. Find the magnitude and direction of resultant displacement.



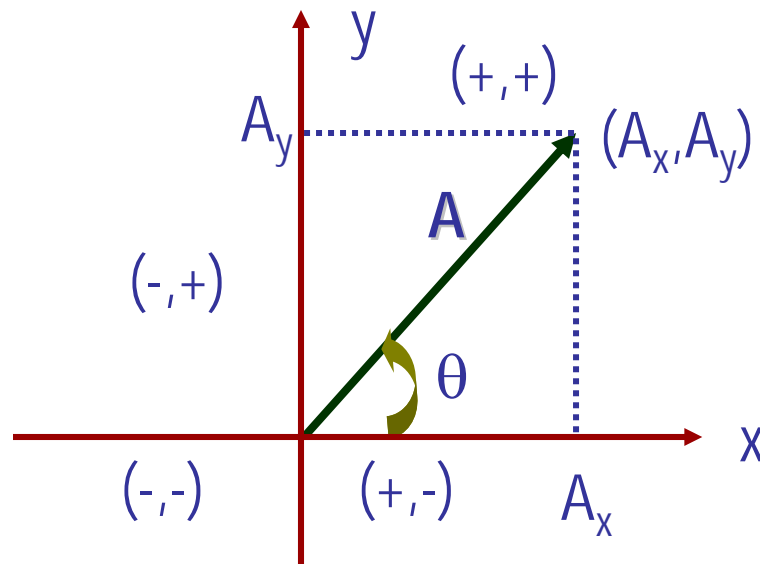
$$\begin{aligned}
 r &= \sqrt{(A + B \cos \theta)^2 + (B \sin \theta)^2} \\
 &= \sqrt{A^2 + B^2 (\cos^2 \theta + \sin^2 \theta) + 2AB \cos \theta} \\
 &= \sqrt{A^2 + B^2 + 2AB \cos \theta} \\
 &= \sqrt{(20.0)^2 + (35.0)^2 + 2 \times 20.0 \times 35.0 \cos 60} \\
 &= \sqrt{2325} = 48.2(\text{km})
 \end{aligned}$$

$$\begin{aligned}
 \theta &= \tan^{-1} \frac{|\vec{B}| \sin 60}{|\vec{A}| + |\vec{B}| \cos 60} \\
 &= \tan^{-1} \frac{35.0 \sin 60}{20.0 + 35.0 \cos 60} \\
 &= \tan^{-1} \frac{30.3}{37.5} = 38.9^\circ \text{ to W wrt N}
 \end{aligned}$$

Find other ways to solve this problem...

Components and Unit Vectors

Coordinate systems are useful in expressing vectors in their components



$$A_x = |\vec{A}| \cos \theta$$

$$A_y = |\vec{A}| \sin \theta$$

} Components

$$|\vec{A}| = \sqrt{A_x^2 + A_y^2}$$

} Magnitude

$$\begin{aligned} |\vec{A}| &= \sqrt{\left(|\vec{A}| \cos \theta\right)^2 + \left(|\vec{A}| \sin \theta\right)^2} \\ &= \sqrt{|\vec{A}|^2 \left(\cos^2 \theta + \sin^2 \theta\right)} = |\vec{A}| \end{aligned}$$

Unit Vectors

- Unit vectors are the ones that tells us the directions of the components
- Dimensionless
- Magnitudes are exactly 1
- Unit vectors are usually expressed in \hat{i} , \hat{j} , \hat{k} or \vec{i} , \vec{j} , \vec{k}

So the vector **A** can be re-written as

$$\vec{A} = A_x \vec{i} + A_y \vec{j} = |\vec{A}| \cos \theta \vec{i} + |\vec{A}| \sin \theta \vec{j}$$



Examples of Vector Operations

Find the resultant vector which is the sum of $\mathbf{A}=(2.0\mathbf{i}+2.0\mathbf{j})$ and $\mathbf{B}=(2.0\mathbf{i}-4.0\mathbf{j})$

$$\begin{aligned}\vec{C} &= \vec{A} + \vec{B} = (2.0\vec{i} + 2.0\vec{j}) + (2.0\vec{i} - 4.0\vec{j}) \\ &= (2.0 + 2.0)\vec{i} + (2.0 - 4.0)\vec{j} = 4.0\vec{i} - 2.0\vec{j} (m)\end{aligned}$$

$$\begin{aligned}|\vec{C}| &= \sqrt{(4.0)^2 + (-2.0)^2} \\ &= \sqrt{16 + 4.0} = \sqrt{20} = 4.5(m)\end{aligned}\quad \theta = \tan^{-1} \frac{C_y}{C_x} = \tan^{-1} \frac{-2.0}{4.0} = -27^\circ$$

Find the resultant displacement of three consecutive displacements:
 $\mathbf{d}_1=(15\mathbf{i}+30\mathbf{j}+12\mathbf{k})\text{cm}$, $\mathbf{d}_2=(23\mathbf{i}+14\mathbf{j}-5.0\mathbf{k})\text{cm}$, and $\mathbf{d}_3=(-13\mathbf{i}+15\mathbf{j})\text{cm}$

$$\begin{aligned}\vec{D} &= \vec{d}_1 + \vec{d}_2 + \vec{d}_3 = (15\vec{i} + 30\vec{j} + 12\vec{k}) + (23\vec{i} + 14\vec{j} - 5.0\vec{k}) + (-13\vec{i} + 15\vec{j}) \\ &= (15 + 23 - 13)\vec{i} + (30 + 14 + 15)\vec{j} + (12 - 5.0)\vec{k} = 25\vec{i} + 59\vec{j} + 7.0\vec{k} (cm)\end{aligned}$$

Magnitude

$$|\vec{D}| = \sqrt{(25)^2 + (59)^2 + (7.0)^2} = 65(cm)$$

Displacement, Velocity, and Acceleration in 2-dim

- Displacement:

$$\Delta \vec{r} = \vec{r}_f - \vec{r}_i$$

- Average Velocity:

$$\vec{v} \equiv \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}$$

- Instantaneous Velocity:

$$\vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt}$$

- Average Acceleration

$$\vec{a} \equiv \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_f - \vec{v}_i}{t_f - t_i}$$

- Instantaneous Acceleration:

$$\vec{a} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt} = \frac{d}{dt} \left(\frac{d\vec{r}}{dt} \right) = \frac{d^2 \vec{r}}{dt^2}$$

How is each of these quantities defined in 1-D?



Kinematic Quantities in 1D and 2D

Quantities	1 Dimension	2 Dimension
Displacement	$\Delta x = x_f - x_i$	$\Delta \vec{r} = \vec{r}_f - \vec{r}_i$
Average Velocity	$v_x = \frac{\Delta x}{\Delta t} = \frac{x_f - x_i}{t_f - t_i}$	$\vec{v} \equiv \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}$
Inst. Velocity	$v_x \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$	$\vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt}$
Average Acc.	$a_x \equiv \frac{\Delta v_x}{\Delta t} = \frac{v_{xf} - v_{xi}}{t_f - t_i}$	$\vec{a} \equiv \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_f - \vec{v}_i}{t_f - t_i}$
Inst. Acc.	$a_x \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta v_x}{\Delta t} = \frac{dv_x}{dt} = \frac{d^2 x}{dt^2}$	$\vec{a} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt} = \frac{d^2 \vec{r}}{dt^2}$