

# PHYS 1443 – Section 001

## Lecture #6

*Wednesday, June 6, 2007*

*Dr. Jaehoon Yu*

- Reference Frame and Relative Velocity
- Newton's Laws of Motion
  - Force
  - Newton's Law of Inertia & Mass
  - Newton's second law of motion
  - Gravitational Force and Weight
  - Newton's third law of motion
- Application of Newton's Laws
  - Motion without friction
- Forces of Friction



# Announcements

- Quiz tomorrow, Thursday, June 7
  - In the beginning of the class
  - CH 1 – what we cover today (CH 5?)
- Reading assignments:
  - CH 4 – 7, 5 – 4, 5 – 5
- Mid-term exam
  - 8:00 – 10am, Thursday, June 14, in class
  - CH 1 through what we cover Wednesday, June 13
- Tomorrow's lecture will be given by a mystery substitute instructor

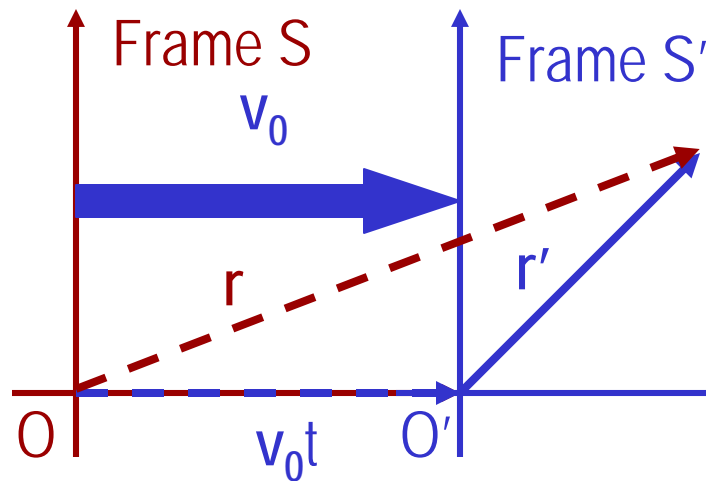


# Observations in Different Reference Frames

Results of physical measurements in different reference frames could be different

*Observations of the same motion in a stationary frame would be different than the ones made in the frame moving together with the moving object.*

*Consider that you are driving a car. To you, the objects in the car do not move while to the person outside the car they are moving in the same speed and direction as your car is.*



*The position vector  $\vec{r}'$  is still  $\vec{r}'$  in the moving frame  $S'$  no matter how much time has passed!!*

*The position vector  $\vec{r}$  is no longer  $\vec{r}$  in the stationary frame  $S$  when time  $t$  has passed.*

*How are these position vectors related to each other?*

$$\vec{r}(t) = \vec{r}_0 + \vec{v}_0 t$$

# Relative Velocity and Acceleration

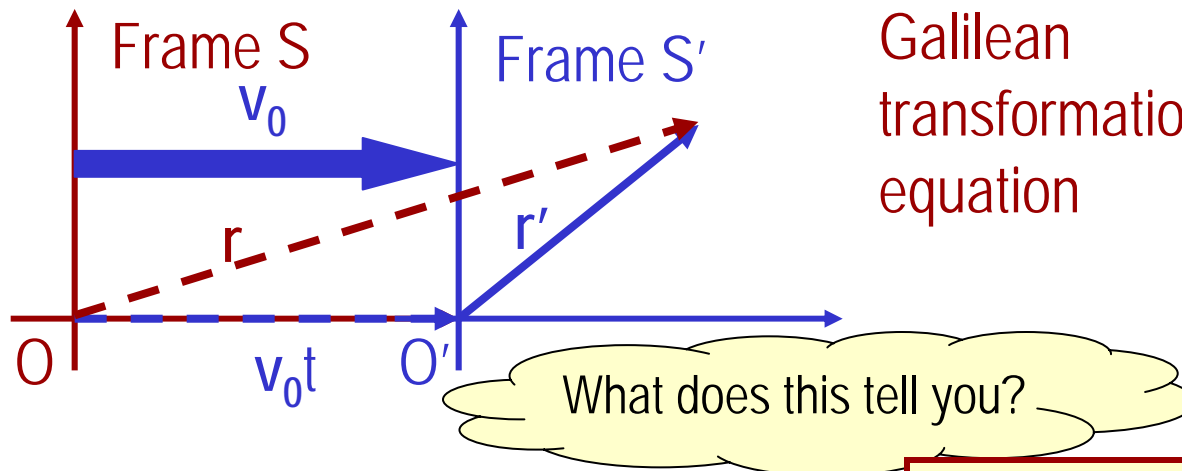
The velocity and acceleration in two different frames of references can be denoted, using the formula in the previous slide:

$$\vec{r}' = \vec{r} - \vec{v}_0 t$$

$$\frac{d\vec{r}'}{dt} = \frac{d\vec{r}}{dt} - \vec{v}_0$$

$$\vec{v}' = \vec{v} - \vec{v}_0$$

Galilean  
transformation  
equation



$$\frac{d\vec{v}'}{dt} = \frac{d\vec{v}}{dt} - \frac{d\vec{v}_0}{dt}$$

$\vec{a}' = \vec{a}$ , when  $\vec{v}_0$  is constant

The accelerations measured in two frames are the same when the frames move at a constant velocity with respect to each other!!!

*The earth's gravitational acceleration is the same in a frame moving at a constant velocity wrt the earth.*

# Force

We've been learning kinematics; describing motion without understanding what the cause of the motion is. Now we are going to learn dynamics!!

*Can someone tell me what FORCE is?*

~~FORCE~~ *is what causes an object to move.*

*The above statement is not entirely correct. Why?*

*Because when an object is moving with a constant velocity no force is exerted on the object!!!*

*FORCES are what cause any change in the velocity of an object!!*

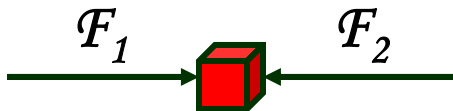
*What does this statement mean?*

*When there is force, there is change of velocity!!*

*What does force cause? It causes an acceleration.!!*

*What happens if there are several forces being exerted on an object?*

*Forces are vector quantities, so vector sum of all forces, the NET FORCE, determines the direction of the acceleration of the object.*



*NET FORCE,  
 $F = F_1 + F_2$*

*When the net force on an object is 0, it has constant velocity and is at its equilibrium!!*

# More Force

There are various classes of forces

*Contact Forces: Forces exerted by physical contact of objects*

*Examples of Contact Forces: Baseball hit by a bat, Car collisions*

*Field Forces: Forces exerted without physical contact of objects*

*Examples of Field Forces: Gravitational Force, Electro-magnetic force*

*What are possible ways to measure strength of Force?*

*A calibrated spring whose length changes linearly with the force exerted.*

*Forces are vector quantities, so addition of multiple forces must be done following the rules of vector additions.*



# Newton's First Law and Inertial Frames

Aristotle (384-322BC): *A natural state of a body is rest. Thus force is required to move an object. To move faster, one needs larger forces.*

Galileo's statement on natural states of matter: *Any velocity once imparted to a moving body will be rigidly maintained as long as the external causes of retardation are removed!!*

Galileo's statement is formulated by Newton into the **1<sup>st</sup> law of motion (Law of Inertia)**: *In the absence of external forces, an object at rest remains at rest and an object in motion continues in motion with a constant velocity.*

What does this statement tell us?

- When no force is exerted on an object, the acceleration of the object is 0.
- Any isolated object, the object that does not interact with its surrounding, is either at rest or moving at a constant velocity.
- Objects would like to keep its current state of motion, as long as there are no forces that interfere with the motion. This tendency is called the Inertia.

A frame of reference that is moving at a constant velocity is called an *Inertial Frame*

Is a frame of reference with an acceleration an *Inertial Frame*?

**NO!**



# Mass

Mass: *A measure of the inertia of a body Or quantity of matter*

- Independent of the object's surroundings: The same no matter where you go.
- Independent of method of measurement: The same no matter how you measure it.

*The heavier the object gets the bigger the inertia !!*

*It is harder to make changes of motion of a heavier object than the lighter ones.*

*The same forces applied to two different masses result in different acceleration depending on the mass.*

$$\frac{m_1}{m_2} \equiv \frac{a_2}{a_1}$$

*Note that the mass and the weight of an object are two different quantities!!*

*Weight of an object is the magnitude of the gravitational force exerted on the object.*

*Not an inherent property of an object!!!*

*Weight will change if you measure on the Earth or on the moon but the mass won't!!*





# Newton's Second Law of Motion

*The acceleration of an object is directly proportional to the net force exerted on it and is inversely proportional to the object's mass.*

*How do we write the above statement in a mathematical expression?*

$$\sum_i \vec{F}_i = m\vec{a}$$

Newton's 2<sup>nd</sup>  
Law of Motion

*Since it's a vector expression, each component should also satisfy:*

$$\sum_i F_{ix} = ma_x$$

$$\sum_i F_{iy} = ma_y$$

$$\sum_i F_{iz} = ma_z$$

*From the above vector expression, what do you conclude the dimension and unit of force are?*

*The dimension of force is*

$$[m][a] = [M][LT^{-2}]$$

*The unit of force in SI is*

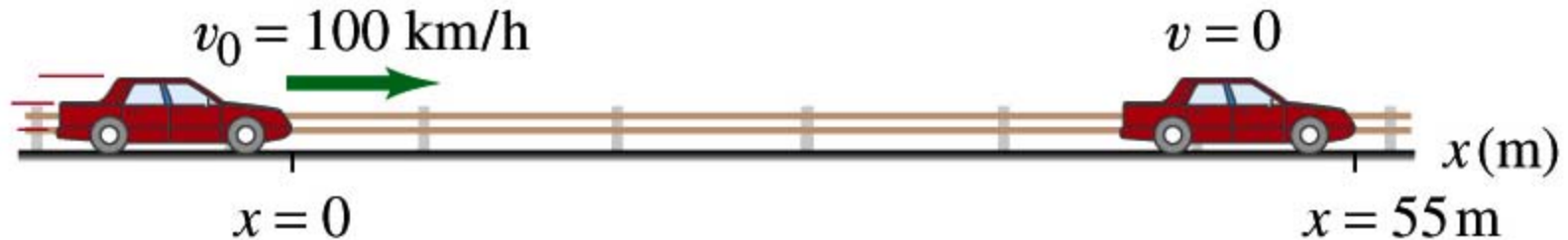
$$[Force] = [m][a] = [M][LT^{-2}] = \text{kg} \cdot \text{m} / \text{s}^2$$

*For ease of use, we define a new derived unit called, Newton (N)*

$$1 \text{ N} \equiv 1 \text{ kg} \cdot \text{m} / \text{s}^2 \approx \frac{1}{4} \text{ lb s}$$

# Example

What constant net force is required to bring a 1500kg car to rest from a speed of 100km/h within a distance of 55m?



What do we need to know to figure out the force?

**Acceleration!!**

What are given? Initial speed:  $v_{xi} = 100 \text{ km/h} = 28 \text{ m/s}$  Final speed:  $v_{xf} = 0 \text{ m/s}$

Displacement:  $\Delta x = x_f - x_i = 55 \text{ m}$

This is a one dimensional motion. Which kinetic formula do we use to find acceleration?

$$v_{xf}^2 = v_{xi}^2 + 2a_x(x_f - x_i) \quad \xrightarrow{\text{Acceleration}} \quad a_x = \frac{v_{xf}^2 - v_{xi}^2}{2(x_f - x_i)} = \frac{-(28 \text{ m/s})^2}{2(55 \text{ m})} = -7.1 \text{ m/s}^2$$

Thus, the force needed to stop the car is

$$F_x = ma_x = 1500 \text{ kg} \times (-7.1 \text{ m/s}^2) = -1.1 \times 10^4 \text{ N}$$

Given the force how far does the car move till it stops?

$$\Delta x = x_f - x_i = \frac{v_{xf}^2 - v_{xi}^2}{2a_x} = \frac{m(v_{xf}^2 - v_{xi}^2)}{2ma_x} = \frac{m(v_{xf}^2 - v_{xi}^2)}{2F_x}$$

- Linearly proportional to the mass of the car
- Squared proportional to the speed of the car
- Inversely proportional to the force by the brake

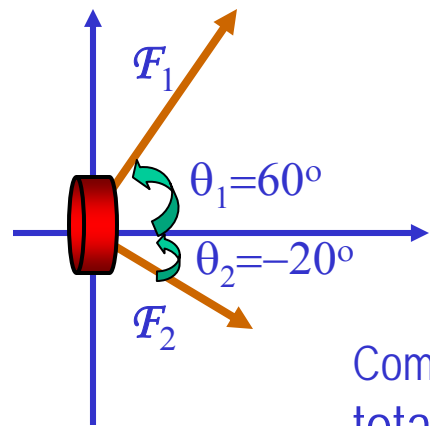
Wednesday, June 6, 2007



PHYS 1443-001, Summer 2007  
Dr. Jaehoon Yu

# Example for Newton's 2<sup>nd</sup> Law of Motion

Determine the magnitude and direction of acceleration of the puck whose mass is 0.30kg and is being pulled by two forces,  $F_1$  and  $F_2$ , as shown in the picture, whose magnitudes of the forces are 8.0 N and 5.0 N, respectively.



Components  
of  $F_1$

$$F_{1x} = |\vec{F}_1| \cos \theta_1 = 8.0 \times \cos(60^\circ) = 4.0 \text{ N}$$

$$F_{1y} = |\vec{F}_1| \sin \theta_1 = 8.0 \times \sin(60^\circ) = 6.9 \text{ N}$$

Components  
of  $F_2$

$$F_{2x} = |\vec{F}_2| \cos \theta_2 = 5.0 \times \cos(-20^\circ) = 4.7 \text{ N}$$

$$F_{2y} = |\vec{F}_2| \sin \theta_2 = 5.0 \times \sin(-20^\circ) = -1.7 \text{ N}$$

Components of  
total force  $F$

$$F_x = F_{1x} + F_{2x} = 4.0 + 4.7 = 8.7 \text{ N} = ma_x$$

$$F_y = F_{1y} + F_{2y} = 6.9 - 1.7 = 5.2 \text{ N} = ma_y$$

Magnitude and  
direction of  
acceleration  $a$

$$a_x = \frac{F_x}{m} = \frac{8.7}{0.3} = 29 \text{ m/s}^2 \quad a_y = \frac{F_y}{m} = \frac{5.2}{0.3} = 17 \text{ m/s}^2 \quad |\vec{a}| = \sqrt{(a_x)^2 + (a_y)^2} = \sqrt{(29)^2 + (17)^2} = 34 \text{ m/s}^2$$

$$\theta = \tan^{-1}\left(\frac{a_y}{a_x}\right) = \tan^{-1}\left(\frac{17}{29}\right) = 30^\circ$$

Acceleration  
Vector  $a$

$$\vec{a} = a_x \hat{i} + a_y \hat{j} = (29\hat{i} + 17\hat{j}) \text{ m/s}^2$$

# Gravitational Force and Weight

Gravitational Force,  $\mathcal{F}_g$

*The attractive force exerted  
on an object by the Earth*

$$\vec{F}_G = m\vec{a} = m\vec{g}$$

Weight of an object with mass M is

$$W = |\vec{F}_G| = M|\vec{g}| = Mg$$

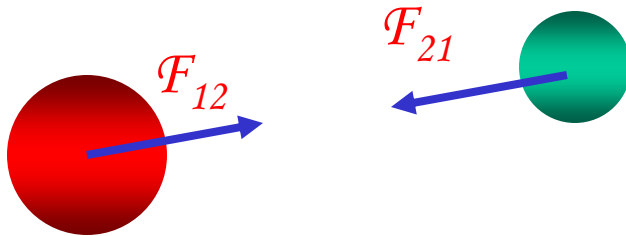
*Since weight depends on the magnitude of gravitational acceleration,  $g$ , it varies depending on geographical location.*

*By measuring the forces one can determine masses. This is why you can measure mass using the spring scale.*



# Newton's Third Law (Law of Action and Reaction)

*If two objects interact, the force  $F_{21}$  exerted on object 1 by object 2 is equal in magnitude and opposite in direction to the force  $F_{12}$  exerted on object 2 by object 1.*



$$\vec{F}_{12} = -\vec{F}_{21}$$

*The action force is equal in magnitude to the reaction force but in opposite direction. These two forces always act on different objects.*

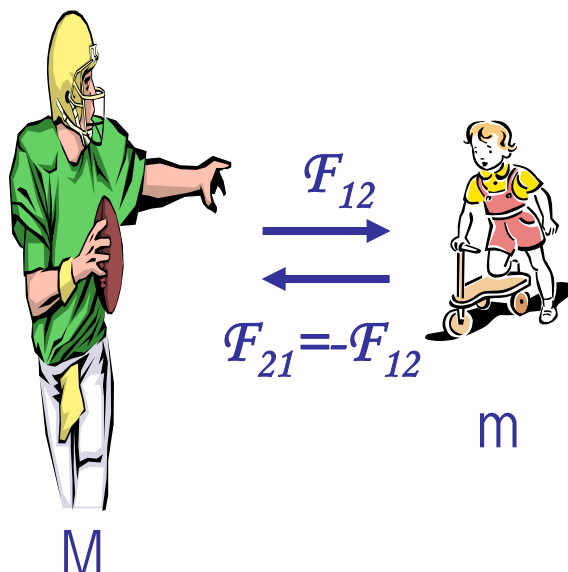
*What is the reaction force to the force of a free fall object?*

*The gravitational force exerted by the object to the Earth!*

*Stationary objects on top of a table has a reaction force (normal force) from table to balance the action force, the gravitational force.*

# Example of Newton's 3<sup>rd</sup> Law

A large man and a small boy stand facing each other on **frictionless ice**. They put their hands together and push against each other so that they move apart. a) Who moves away with the higher speed and by how much?



$$\vec{F}_{12} = -\vec{F}_{21}$$

$$|\vec{F}_{12}| = |\vec{F}_{21}| = F$$

$$\vec{F}_{12} = m \vec{a}_b$$

$$F_{12x} = m a_{bx}$$

$$F_{12y} = m a_{by} = 0$$

$$\vec{F}_{21} = M \vec{a}_M$$

$$F_{21x} = M a_{Mx}$$

$$F_{21y} = M a_{My} = 0$$

Since  $\vec{F}_{12} = -\vec{F}_{21}$  and  $|\vec{F}_{12}| = |-\vec{F}_{21}| = F$

Establish the equation

$$m a_{bx} = F = M a_{Mx}$$

Divide by m

$$a_{bx} = \frac{F}{m} = \frac{M}{m} a_{Mx}$$

# Example of Newton's 3<sup>rd</sup> Law

Man's velocity

$$v_{Mxf} = v_{Mxi} + a_{Mx}t = a_{Mx}t$$

Boy's velocity

$$v_{bxf} = v_{bxi} + a_{bx}t = a_{bx}t = \frac{M}{m}a_{Mx}t = \frac{M}{m}v_{Mxf}$$

So boy's velocity is higher than man's, if  $M > m$ , by the ratio of the masses.

b) Who moves farther while their hands are in contact?

Boy's displacement

$$x_b = v_{bxi}t + \frac{1}{2}a_{bx}t^2 = \frac{M}{2m}a_{Mx}t^2$$

$$x_b = \frac{M}{m} \left( \frac{1}{2}a_{Mx}t^2 \right) = \frac{M}{m}x_M$$

Man's displacement

Given in the same time interval, since the boy has higher acceleration and thereby higher speed, he moves farther than the man.