

# PHYS 1441 – Section 001

## Lecture #2

*Wednesday, May 28, 2008*

*Dr. Jaehoon Yu*

- Dimensional Analysis
- Trigonometry reminder
- Coordinate system, vector and scalars
- One Dimensional Motion: Average Velocity;  
Acceleration; Motion under constant acceleration;  
Free Fall



# Announcements

- E-mail Distribution list
  - 22 out of 55 registered as of this morning!!
  - 5 points extra credit if done by Friday, May 30
  - 3 points extra credit if done by next Monday, June 2
- There will be a quiz on Monday, June 2
  - Appendices
  - CH1 – CH3
- First term exam
  - 8 – 10am, Next Wednesday, June 4
  - SH103
  - Covers CH1 – what we finish next Tuesday + appendices



# Dimension and Dimensional Analysis

- An extremely useful tool in solving physical problems
- Good to write physical laws in mathematical expressions
- No matter what units are used, the base quantities are still the same
  - *Length* (distance) is length whether meter or inch is used to express the size: Denoted as  $[L]$
  - The same is true for *Mass* ( $[M]$ ) and *Time* ( $[T]$ )
  - One can say “Dimension of Length, Mass or Time”
  - Dimensions are used as algebraic quantities: Can perform two algebraic operations; multiplication or division
  - Can't add two quantities of different dimension



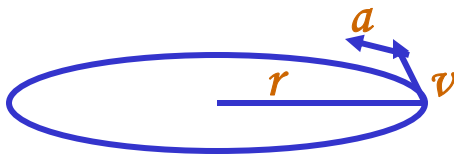
# Dimension and Dimensional Analysis

- One can use dimensions to check the validity of one's expression: Dimensional analysis
  - Eg: Speed  $[v] = [\mathcal{L}]/[T] = [\mathcal{L}][T^{-1}]$ 
    - *Distance ( $\mathcal{L}$ ) traveled by a car running at the speed  $\mathcal{V}$  in time  $T$*
    - $\mathcal{L} = \mathcal{V}^*T = [\mathcal{L}/T]^*[T] = [\mathcal{L}]$
- More general expression of dimensional analysis is using exponents: eg.  $[v] = [\mathcal{L}^n T^m] = [\mathcal{L}][T^{-1}]$   
*where  $n = 1$  and  $m = -1$*



# Examples

- Show that the expression  $[v] = [at]$  is dimensionally correct
  - Speed:  $[v] = L/T$
  - Acceleration:  $[a] = L/T^2$
  - Thus,  $[at] = (L/T^2) \times T = LT^{(-2+1)} = LT^{-1} = L/T = [v]$
- Suppose the acceleration  $a$  of a circularly moving particle with speed  $v$  and radius  $r$  is proportional to  $r^n$  and  $v^m$ . What are  $n$  and  $m$ ?



$$a = kr^n v^m$$

Dimensionless  
constant

Length

Speed

$$L^1 T^{-2} = (L)^n \left( \frac{L}{T} \right)^m = L^{n+m} T^{-m}$$

$$-m = -2 \Rightarrow m = 2$$

$$n + m = n + 2 \equiv 1 \Rightarrow n = -1$$

$$a = kr^{-1} v^2 = \frac{v^2}{r}$$

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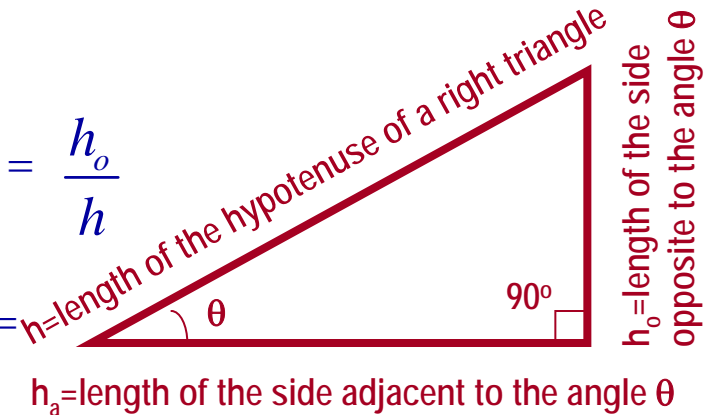
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# Trigonometry Reminders

- Definitions of  $\sin\theta$ ,  $\cos\theta$  and  $\tan\theta$

$$\sin \theta = \frac{\text{Length of the opposite side to } \theta}{\text{Length of the hypotenuse of the right triangle}} = \frac{h_o}{h}$$

$$\cos \theta = \frac{\text{Length of the adjacent side to } \theta}{\text{Length of the hypotenuse of the right triangle}} = \frac{h_a}{h}$$



$$\tan \theta = \frac{\text{Length of the opposite side to } \theta}{\text{Length of the adjacent side to } \theta} = \frac{h_o}{h_a}$$

$$\tan \theta = \frac{\sin \theta}{\cos \theta} = \frac{\frac{h_o}{h}}{\frac{h_a}{h}} = \frac{h_o}{h_a}$$

Pythagorean theorem: For right triangles

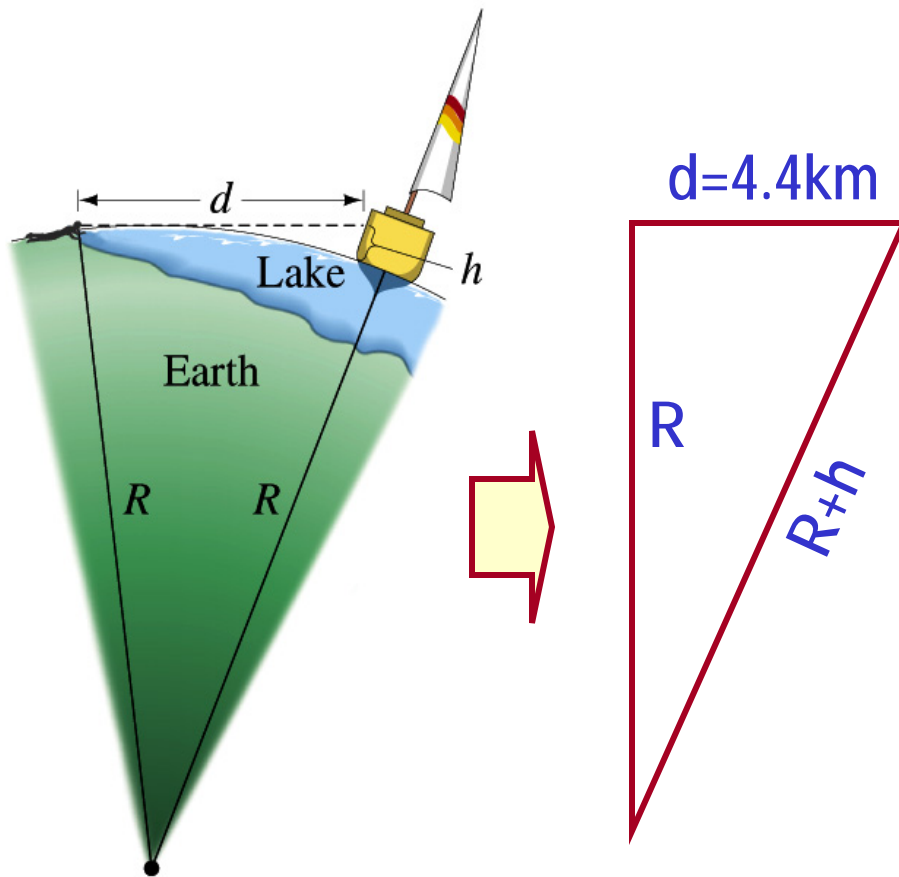
$$h^2 = h_o^2 + h_a^2 \Rightarrow h = \sqrt{h_o^2 + h_a^2}$$

Do Ex. 3 and 4 yourselves...



# Example for estimates using trig..

Estimate the radius of the Earth using triangulation as shown in the picture when  $d=4.4\text{km}$  and  $h=1.5\text{m}$ .



Pythagorean theorem

$$(R + h)^2 \approx d^2 + R^2$$

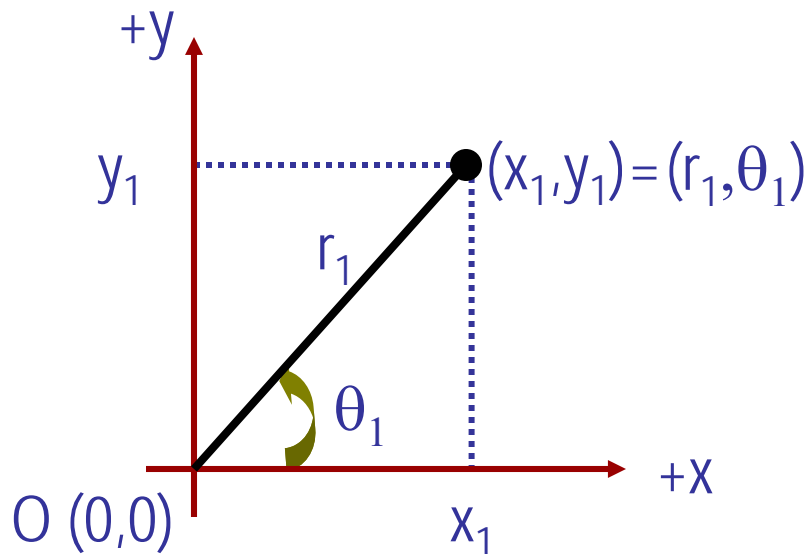
$$R^2 + 2hR + h^2 \approx d^2 + R^2$$

Solving for R

$$\begin{aligned} R &\approx \frac{d^2 - h^2}{2h} \\ &= \frac{(4400\text{m})^2 - (1.5\text{m})^2}{2 \times 1.5\text{m}} \\ &= 6500\text{km} \end{aligned}$$

# Coordinate Systems

- They make it easy and consistent to express locations or positions
- Two commonly used systems, depending on convenience, are
  - Cartesian (Rectangular) Coordinate System
    - Coordinates are expressed in  $(x,y)$
  - Polar Coordinate System
    - Coordinates are expressed in distance from the origin  $^{\circ}$  and the angle measured from the x-axis,  $\theta$  ( $r,\theta$ )
- Vectors become a lot easier to express and compute



How are Cartesian and Polar coordinates related?

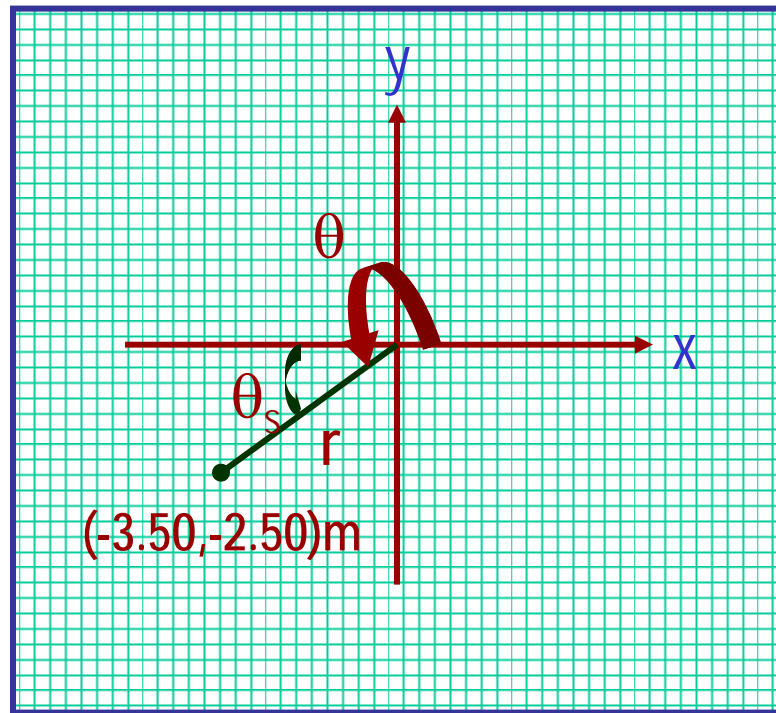
$$x_1 = r_1 \cos \theta_1 \quad r_1 = \sqrt{(x_1^2 + y_1^2)}$$

$$y_1 = r_1 \sin \theta_1 \quad \tan \theta_1 = \frac{y_1}{x_1}$$
$$\theta_1 = \tan^{-1} \left( \frac{y_1}{x_1} \right)$$



# Example

Cartesian Coordinate of a point in the xy plane are  $(x,y) = (-3.50, -2.50)\text{m}$ . Find the equivalent polar coordinates of this point.



$$\begin{aligned} r &= \sqrt{(x^2 + y^2)} \\ &= \sqrt{((-3.50)^2 + (-2.50)^2)} \\ &= \sqrt{18.5} = 4.30(m) \end{aligned}$$

$$\theta = 180 + \theta_s$$

$$\tan \theta_s = \frac{-2.50}{-3.50} = \frac{5}{7}$$

$$\theta_s = \tan^{-1}\left(\frac{5}{7}\right) = 35.5^\circ$$

$$\therefore \theta = 180 + \theta_s = 180^\circ + 35.5^\circ = 216^\circ$$

# Vector and Scalar

Vector quantities have both magnitudes (sizes) and directions

*Force, gravitational acceleration, momentum*

Normally denoted in **BOLD** letters,  $\mathbf{F}$ , or a letter with arrow on top  $\vec{F}$

Their sizes or magnitudes are denoted with normal letters,  $F$ , or absolute values:  $|\vec{F}|$  or  $|\mathbf{F}|$

Scalar quantities have magnitudes only

Can be completely specified with a value and its unit

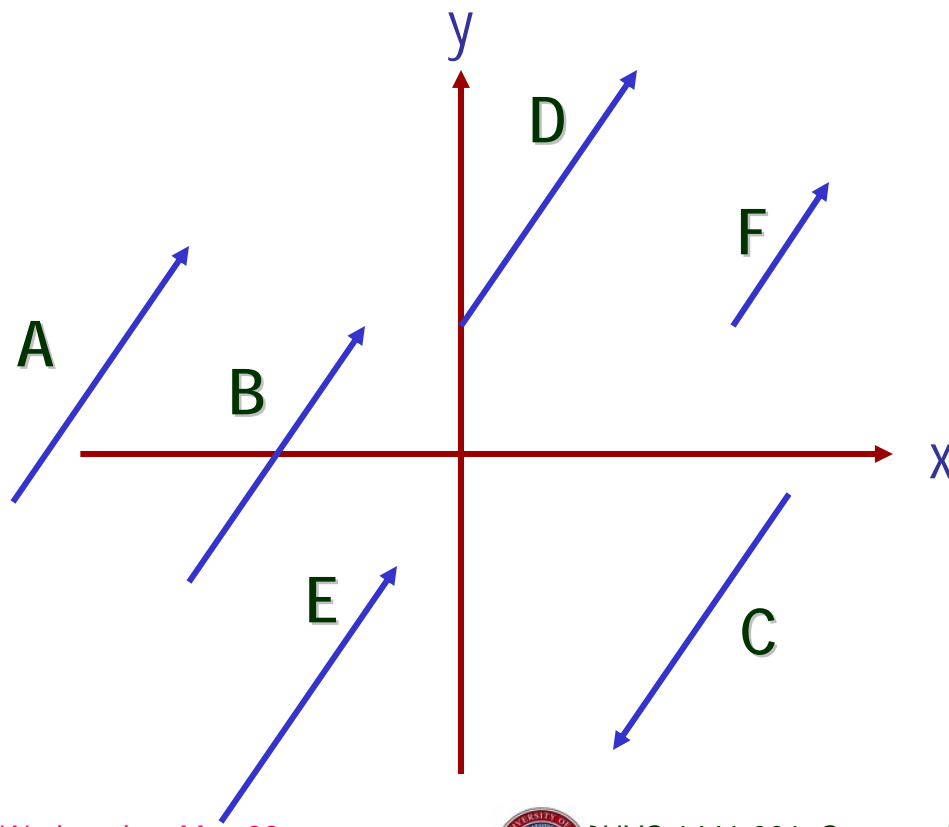
Normally denoted in normal letters,  $E$

*Energy, heat, mass, time*

Both have units!!!

# Properties of Vectors

- Two vectors are the same if their sizes and the directions are the same, no matter where they are on a coordinate system!!



Which ones are the same vectors?

**$A=B=E=D$**

Why aren't the others?

**C:** The same magnitude but opposite direction:  
 **$C=-A$ :** A negative vector

**F:** The same direction but different magnitude

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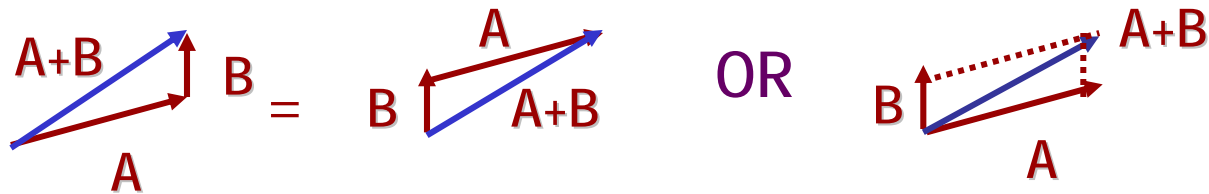


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# Vector Operations

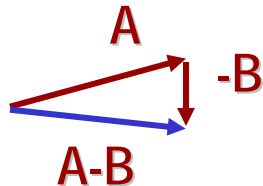
- Addition:

- Triangular Method: One can add vectors by connecting the head of one vector to the tail of the other (head-to-tail)
- Parallelogram method: Connect the tails of the two vectors and extend
- Addition is commutative: Changing order of operation does not affect the results  
 $A+B=B+A$ ,  $A+B+C+D+E=E+C+A+B+D$



- Subtraction:

- The same as adding a negative vector:  $A - B = A + (-B)$



Since subtraction is the equivalent to adding a negative vector, subtraction is also commutative!!!

- Multiplication by a scalar is increasing the magnitude  $A$ ,  $B=2A$



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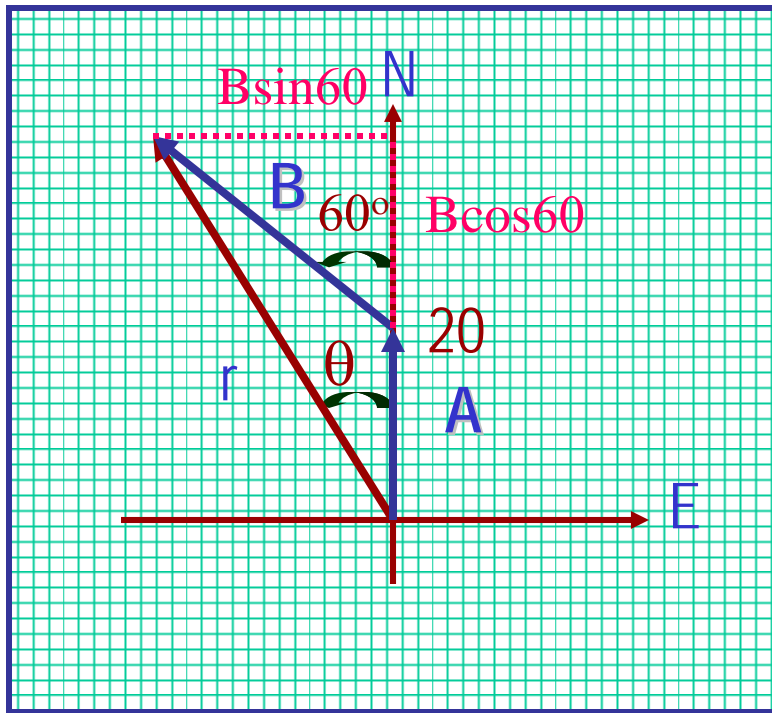
$$|B| = 2|A|$$



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# Example for Vector Addition

A car travels 20.0km due north followed by 35.0km in a direction 60.0° west of north. Find the magnitude and direction of resultant displacement.



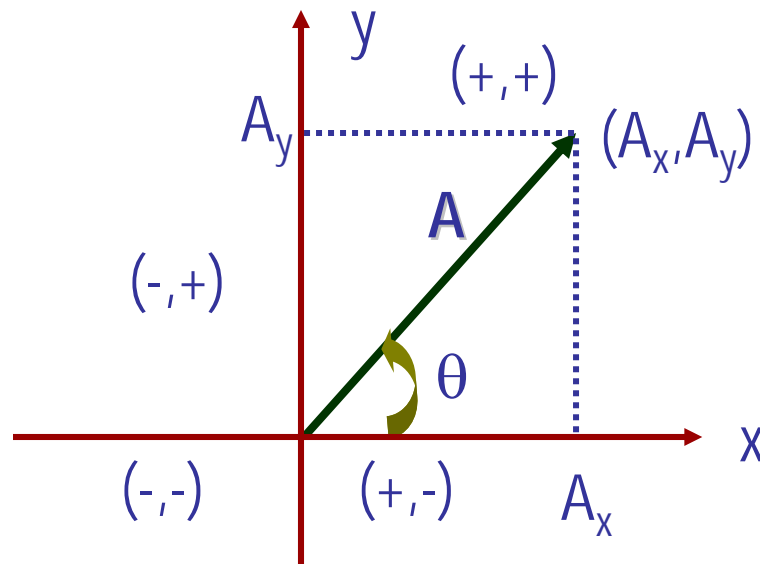
$$\begin{aligned}
 r &= \sqrt{(A + B \cos 60)^2 + (B \sin 60)^2} \\
 &= \sqrt{A^2 + B^2 (\cos^2 60 + \sin^2 60) + 2AB \cos 60} \\
 &= \sqrt{A^2 + B^2 + 2AB \cos 60} \\
 &= \sqrt{(20.0)^2 + (35.0)^2 + 2 \times 20.0 \times 35.0 \cos 60} \\
 &= \sqrt{2325} = 48.2(\text{km})
 \end{aligned}$$

$$\begin{aligned}
 \theta &= \tan^{-1} \frac{|\vec{B}| \sin 60}{|\vec{A}| + |\vec{B}| \cos 60} \\
 &= \tan^{-1} \frac{35.0 \sin 60}{20.0 + 35.0 \cos 60} \\
 &= \tan^{-1} \frac{30.3}{37.5} = 38.9^\circ \text{ to W wrt N}
 \end{aligned}$$

Find other ways to solve this problem...

# Components and Unit Vectors

Coordinate systems are useful in expressing vectors in their components



$$A_x = |\vec{A}| \cos \theta$$

$$A_y = |\vec{A}| \sin \theta$$

} Components

$$|\vec{A}| = \sqrt{A_x^2 + A_y^2}$$

} Magnitude

$$\begin{aligned} |\vec{A}| &= \sqrt{\left(|\vec{A}| \cos \theta\right)^2 + \left(|\vec{A}| \sin \theta\right)^2} \\ &= \sqrt{|\vec{A}|^2 \left(\cos^2 \theta + \sin^2 \theta\right)} = |\vec{A}| \end{aligned}$$

# Unit Vectors

- Unit vectors are the ones that tells us the directions of the components
- Dimensionless
- Magnitudes are exactly 1
- Unit vectors are usually expressed in  $\hat{i}$ ,  $\hat{j}$ ,  $\hat{k}$  or  $\vec{i}$ ,  $\vec{j}$ ,  $\vec{k}$

So the vector **A** can be re-written as

$$\vec{A} = A_x \vec{i} + A_y \vec{j} = |\vec{A}| \cos \theta \vec{i} + |\vec{A}| \sin \theta \vec{j}$$



# Examples of Vector Operations

Find the resultant vector which is the sum of  $\mathbf{A}=(2.0\mathbf{i}+2.0\mathbf{j})$  and  $\mathbf{B}=(2.0\mathbf{i}-4.0\mathbf{j})$

$$\begin{aligned}\vec{C} &= \vec{A} + \vec{B} = (2.0\vec{i} + 2.0\vec{j}) + (2.0\vec{i} - 4.0\vec{j}) \\ &= (2.0 + 2.0)\vec{i} + (2.0 - 4.0)\vec{j} = 4.0\vec{i} - 2.0\vec{j} (m)\end{aligned}$$

$$\begin{aligned}|\vec{C}| &= \sqrt{(4.0)^2 + (-2.0)^2} \\ &= \sqrt{16 + 4.0} = \sqrt{20} = 4.5(m)\end{aligned}\quad \theta = \tan^{-1} \frac{C_y}{C_x} = \tan^{-1} \frac{-2.0}{4.0} = -27^\circ$$

Find the resultant displacement of three consecutive displacements:  
 $\mathbf{d}_1=(15\mathbf{i}+30\mathbf{j}+12\mathbf{k})\text{cm}$ ,  $\mathbf{d}_2=(23\mathbf{i}+14\mathbf{j}-5.0\mathbf{k})\text{cm}$ , and  $\mathbf{d}_3=(-13\mathbf{i}+15\mathbf{j})\text{cm}$

$$\begin{aligned}\vec{D} &= \vec{d}_1 + \vec{d}_2 + \vec{d}_3 = (15\vec{i} + 30\vec{j} + 12\vec{k}) + (23\vec{i} + 14\vec{j} - 5.0\vec{k}) + (-13\vec{i} + 15\vec{j}) \\ &= (15 + 23 - 13)\vec{i} + (30 + 14 + 15)\vec{j} + (12 - 5.0)\vec{k} = 25\vec{i} + 59\vec{j} + 7.0\vec{k} (cm)\end{aligned}$$

Magnitude

$$|\vec{D}| = \sqrt{(25)^2 + (59)^2 + (7.0)^2} = 65(cm)$$



# Some Fundamentals

- Kinematics: Description of Motion without understanding the cause of the motion
- Dynamics: Description of motion accompanied with understanding the cause of the motion
- Vector and Scalar quantities:
  - Scalar: Physical quantities that require magnitude but no direction
    - Speed, length, mass, height, volume, area, magnitude of a vector quantity, etc
  - Vector: Physical quantities that require both magnitude and direction
    - Velocity, Acceleration, Force, Momentum
    - It does not make sense to say “I ran with velocity of 10miles/hour.”
- Objects can be treated point-like if their sizes are smaller than the scale in the problem
  - Earth can be treated as a point like object (or a particle) in celestial problems
    - Simplification of the problem (The first step in setting up to solve a problem...)



# Some More Fundamentals

- **Motions**: Can be described as long as the position is known at any given time (or position is expressed as a function of time)
  - Translation: Linear motion along a line
  - Rotation: Circular or elliptical motion
  - Oscillation or Vibration: Repeated, periodic motion
- **Dimensions**
  - 0 dimension: A point
  - 1 dimension: Linear drag of a point, resulting in a line →  
Motion in one-dimension is a motion on a straight line
  - 2 dimension: Linear drag of a line resulting in a surface
  - 3 dimension: Perpendicular Linear drag of a surface, resulting in a stereo object



# Displacement, Velocity and Speed

One dimensional displacement is defined as:

$$\Delta x \equiv x_f - x_i$$

A vector quantity

*Displacement is the difference between initial and final positions of the motion and is a vector quantity. How is this different than distance?*

Unit?

m

The average velocity is defined as:  $v_x \equiv \frac{x_f - x_i}{t_f - t_i} = \frac{\Delta x}{\Delta t} \equiv \frac{\text{Displacement}}{\text{Elapsed Time}}$

Unit?

m/s

A vector quantity

*Displacement per unit time in the period throughout the motion*

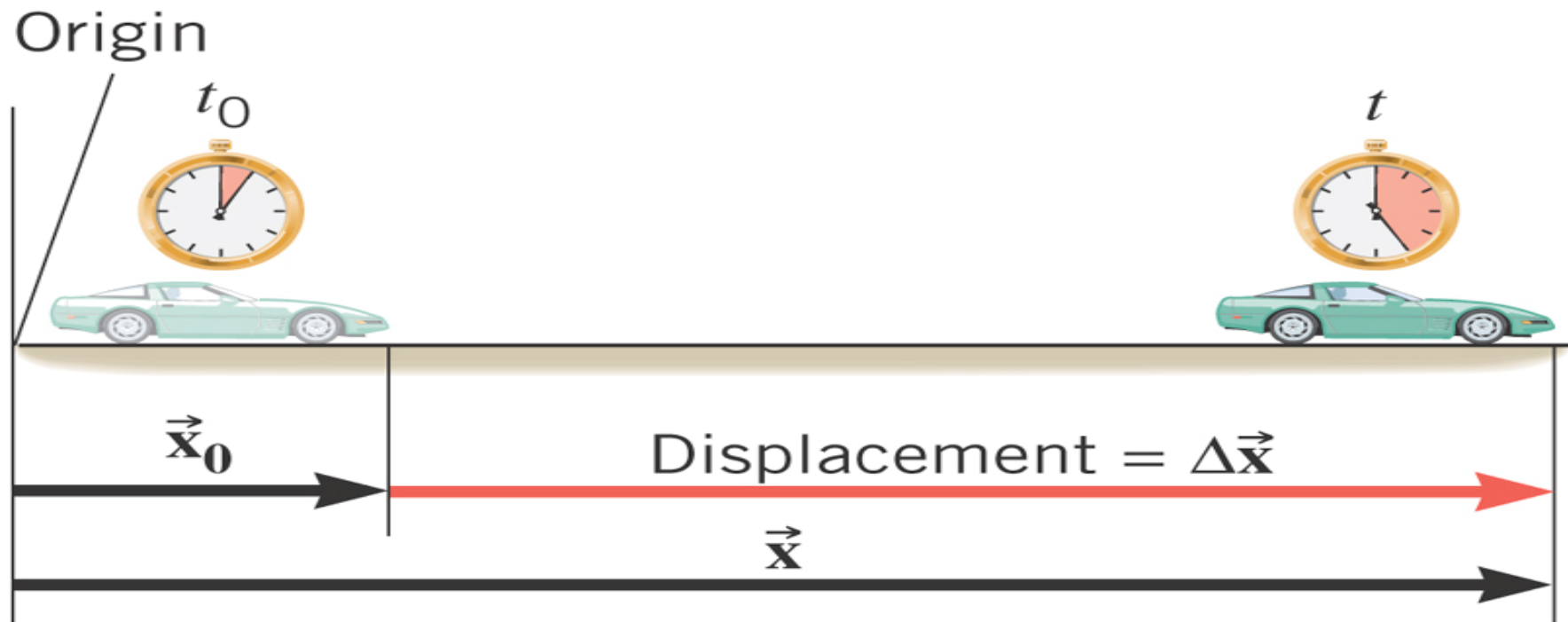
The average speed is defined as:

Unit?

m/s

A scalar quantity

$$v \equiv \frac{\text{Total Distance Traveled}}{\text{Total Elapsed Time}}$$



What is the displacement?  $\Delta x = \vec{x} - \vec{x}_0$

How much is the elapsed time?  $\Delta t = t - t_0$

# Difference between Speed and Velocity

- Let's take a simple one dimensional translation that has many steps:

Let's call this line X-axis

Let's have a couple of motions in a total time interval of 20 sec.



Total Displacement:  $\Delta x \equiv x_f - x_i = x_i - x_i = 0(m)$

Average Velocity:  $v_x \equiv \frac{x_f - x_i}{t_f - t_i} = \frac{\Delta x}{\Delta t} = \frac{0}{20} = 0(m/s)$

---

Total Distance Traveled:  $D = 10 + 15 + 5 + 15 + 10 + 5 = 60(m)$

Average Speed:  $v \equiv \frac{\text{Total Distance Traveled}}{\text{Total Elapsed Time}} = \frac{60}{20} = 3(m/s)$

