

# PHYS 1441 – Section 001

## Lecture #5

*Tuesday, June 10, 2014*

*Dr. Jaehoon Yu*

- Trigonometry Refresher
- Properties and operations of vectors
- Components of the 2D Vector
- Understanding the 2 Dimensional Motion
- 2D Kinematic Equations of Motion
- Projectile Motion

Today's homework is homework #3, due 11pm, Friday, June 13!!

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# Announcements

- Reading Assignment
  - CH3.7
- Quiz #2
  - Beginning of the class this Thursday, June, 12
  - Covers CH3.1 to what we finish tomorrow, Wednesday, June 11
  - Bring your calculator but DO NOT input formula into it!
  - You can prepare a one 8.5x11.5 sheet (front and back) of handwritten formulae and values of constants for the exam → no solutions, derivations or definitions!
    - No additional formulae or values of constants will be provided!



# Special Project #2 for Extra Credit

- Show that the trajectory of a projectile motion is a parabola!!
  - 20 points
  - Due: Monday, June 16
  - You MUST show full details of your OWN computations to obtain any credit
    - Beyond what was covered in this lecture note and in the book!



# Trigonometry Refresher

- Definitions of  $\sin\theta$ ,  $\cos\theta$  and  $\tan\theta$

$$\sin \theta = \frac{\text{Length of the opposite side to } \theta}{\text{Length of the hypotenuse of the right triangle}} = \frac{h_o}{h}$$

$$\cos \theta = \frac{\text{Length of the adjacent side to } \theta}{\text{Length of the hypotenuse of the right triangle}} = \frac{h_a}{h}$$

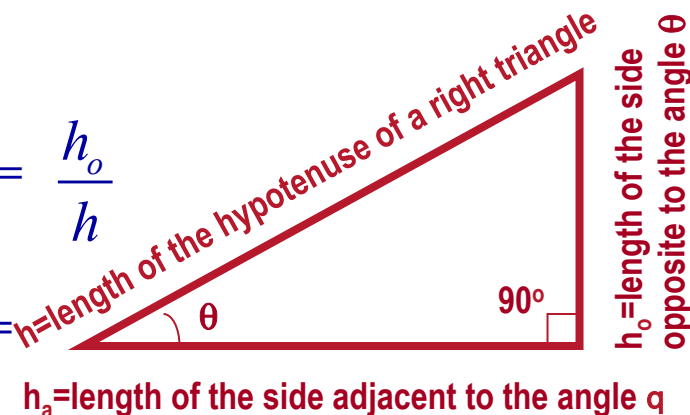
$$= \frac{h_a}{h} \quad \text{Solve for } \theta \quad \theta = \cos^{-1} \left( \frac{h_a}{h} \right)$$

$$\tan \theta = \frac{\text{Length of the opposite side to } \theta}{\text{Length of the adjacent side to } \theta} = \frac{h_o}{h_a} \quad \text{Solve for } \theta \quad \theta = \tan^{-1} \left( \frac{h_o}{h_a} \right)$$

$$\tan \theta = \frac{\sin \theta}{\cos \theta} = \frac{\frac{h_o}{h}}{\frac{h_a}{h}} = \frac{h_o}{h_a}$$

Pythagorean theorem: For right angle triangles

$$h^2 = h_o^2 + h_a^2 \quad \Rightarrow \quad h = \sqrt{h_o^2 + h_a^2}$$



# Vector and Scalar

Vector quantities have both magnitudes (sizes) and directions

*Velocity, acceleration, force, momentum, etc*

Normally denoted in **BOLD** letters,  $\mathbf{F}$ , or a letter with arrow on top  $\vec{F}$

Their sizes or magnitudes are denoted with normal letters,  $F$ , or absolute values:  $|\vec{F}|$  or  $|\mathbf{F}|$

Scalar quantities have magnitudes only

Can be completely specified with a value and its unit

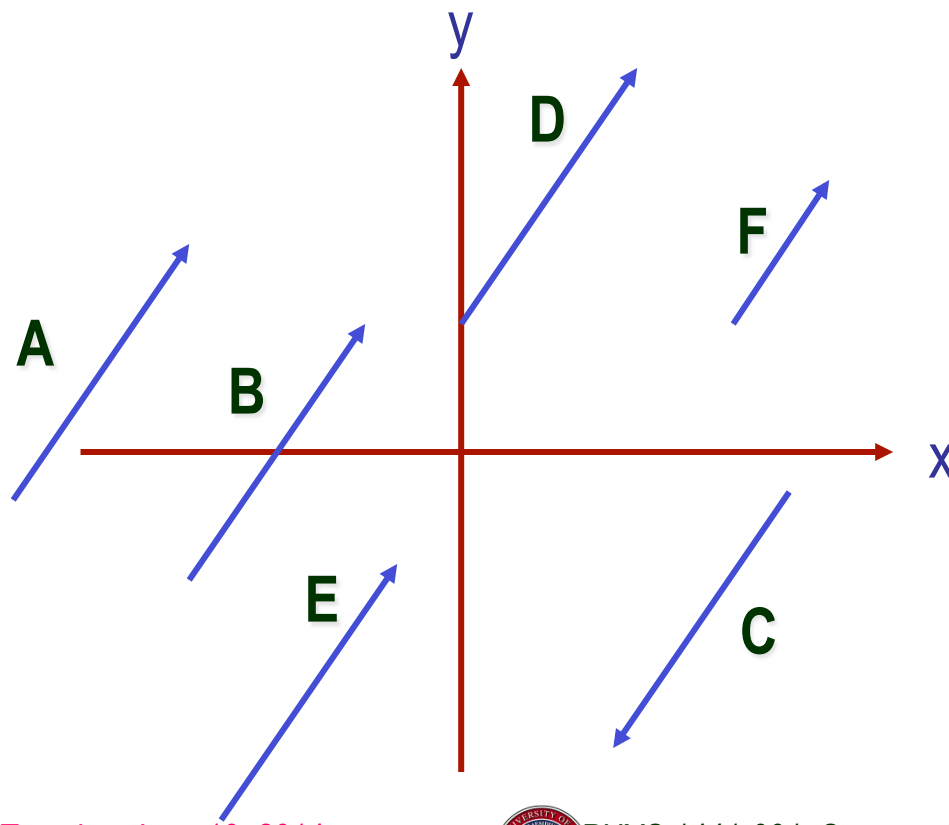
Normally denoted in normal letters,  $E$

*Speed, energy, heat, mass, time, etc*

Both have units!!!

# Properties of Vectors

- Two vectors are the same if their **sizes** and the **directions** are the same, no matter where they are on a coordinate system!! → You can move them around as you wish as long as their directions and sizes are kept the same.



Which ones are the same vectors?

**$A=B=E=D$**

Why aren't the others?

**C:** The same magnitude but opposite direction:  
 **$C=-A$ :** A negative vector

**F:** The same direction but different magnitude

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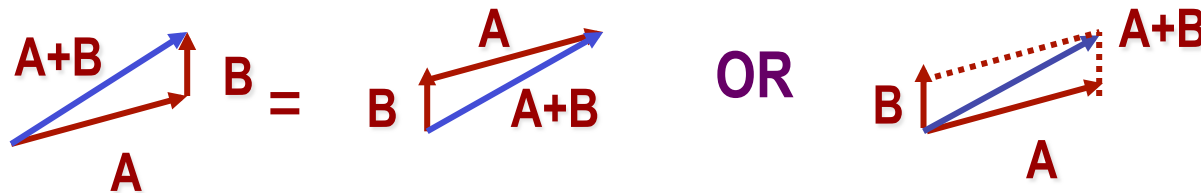


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# Vector Operations

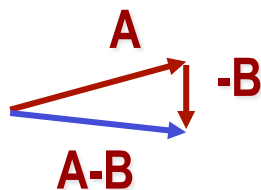
- Addition:

- Triangular Method: One can add vectors by connecting the head of one vector to the tail of the other (head-to-tail)
- Parallelogram method: Connect the tails of the two vectors and extend
- Addition is commutative: Changing order of operation does not affect the results  $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$ ,  $\mathbf{A} + \mathbf{B} + \mathbf{C} + \mathbf{D} + \mathbf{E} = \mathbf{E} + \mathbf{C} + \mathbf{A} + \mathbf{B} + \mathbf{D}$



- Subtraction:

- The same as adding a negative vector:  $\mathbf{A} - \mathbf{B} = \mathbf{A} + (-\mathbf{B})$



Since subtraction is the equivalent to adding a negative vector, subtraction is also commutative!!!

- Multiplication by a scalar is increasing the magnitude  $\mathbf{A}$ ,  $\mathbf{B} = 2\mathbf{A}$

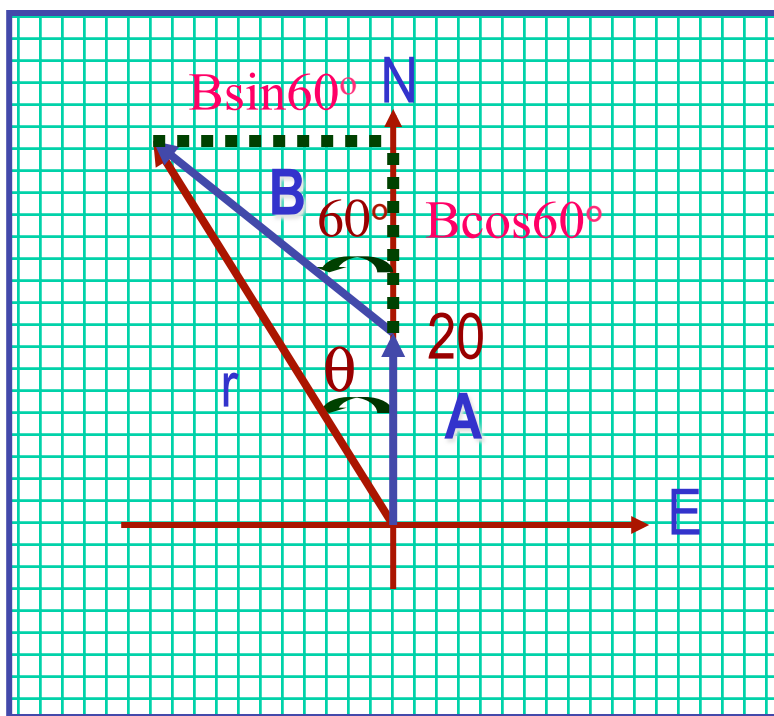


Tues  $|\mathcal{B}| = 2|\mathcal{A}|$



# Example for Vector Addition

A car travels 20.0km due north followed by 35.0km in a direction 60.0° West of North. Find the magnitude and direction of resultant displacement.



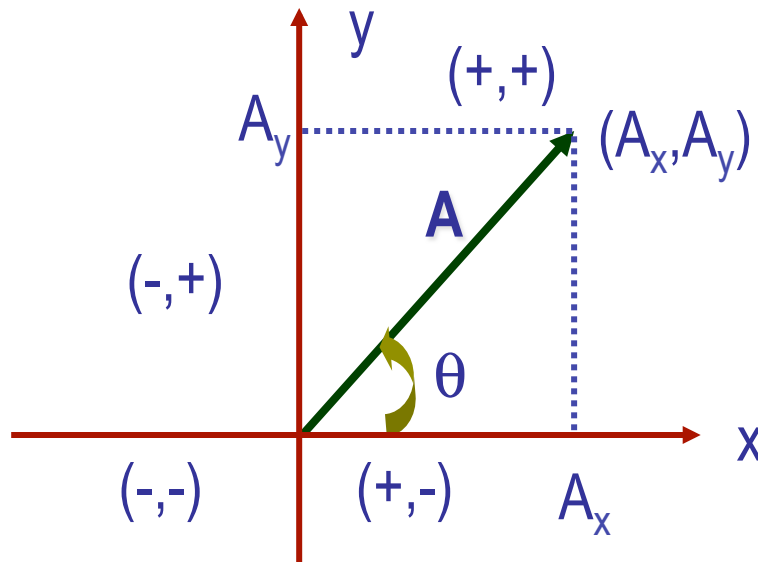
$$\begin{aligned}
 r &= \sqrt{(A + B \cos \theta)^2 + (B \sin \theta)^2} \\
 &= \sqrt{A^2 + B^2 (\cos^2 \theta + \sin^2 \theta) + 2AB \cos \theta} \\
 &= \sqrt{A^2 + B^2 + 2AB \cos \theta} \\
 &= \sqrt{(20.0)^2 + (35.0)^2 + 2 \times 20.0 \times 35.0 \cos 60} \\
 &= \sqrt{2325} = 48.2(\text{km})
 \end{aligned}$$

$$\begin{aligned}
 \theta &= \tan^{-1} \frac{|\vec{B}| \sin 60}{|\vec{A}| + |\vec{B}| \cos 60} \\
 &= \tan^{-1} \frac{35.0 \sin 60}{20.0 + 35.0 \cos 60} \\
 &= \tan^{-1} \frac{30.3}{37.5} = 38.9^\circ \text{ to W wrt N}
 \end{aligned}$$

Do this using components!!

# Components and Unit Vectors

Coordinate systems are useful in expressing vectors in their components



$$A_x = |\vec{A}| \cos \theta$$

$$A_y = |\vec{A}| \sin \theta$$

} Components

$$|\vec{A}| = \sqrt{A_x^2 + A_y^2}$$

} Magnitude

$$\begin{aligned} |\vec{A}| &= \sqrt{\left(|\vec{A}| \cos \theta\right)^2 + \left(|\vec{A}| \sin \theta\right)^2} \\ &= \sqrt{|\vec{A}|^2 (\cos^2 \theta + \sin^2 \theta)} = |\vec{A}| \end{aligned}$$

# Unit Vectors

- Unit vectors are the ones that tells us the directions of the components
  - Very powerful and makes vector notation and operations much easier!
- Dimensionless
- Magnitudes these vectors are exactly 1
- Unit vectors are usually expressed in  $\vec{i}$ ,  $\vec{j}$ ,  $\vec{k}$  or  $i, j, k$

So a vector **A** can be expressed as

$$\vec{A} = A_x \vec{i} + A_y \vec{j} = |\vec{A}| \cos \theta \vec{i} + |\vec{A}| \sin \theta \vec{j}$$

# Examples of Vector Operations

Find the resultant vector which is the sum of  $\mathbf{A}=(2.0\mathbf{i}+2.0\mathbf{j})$  and  $\mathbf{B}=(2.0\mathbf{i}-4.0\mathbf{j})$

$$\begin{aligned}\vec{C} &= \vec{A} + \vec{B} = (2.0\vec{i} + 2.0\vec{j}) + (2.0\vec{i} - 4.0\vec{j}) \\ &= (2.0 + 2.0)\vec{i} + (2.0 - 4.0)\vec{j} = 4.0\vec{i} - 2.0\vec{j} (m)\end{aligned}$$

$$\begin{aligned}|\vec{C}| &= \sqrt{(4.0)^2 + (-2.0)^2} \\ &= \sqrt{16 + 4.0} = \sqrt{20} = 4.5(m)\end{aligned}\quad \theta = \tan^{-1} \frac{C_y}{C_x} = \tan^{-1} \frac{-2.0}{4.0} = -27^\circ$$

Find the resultant displacement of three consecutive displacements:

$\mathbf{d}_1=(15\mathbf{i}+30\mathbf{j}+12\mathbf{k})\text{cm}$ ,  $\mathbf{d}_2=(23\mathbf{i}+14\mathbf{j}-5.0\mathbf{k})\text{cm}$ , and  $\mathbf{d}_3=(-13\mathbf{i}+15\mathbf{j})\text{cm}$

$$\begin{aligned}\vec{D} &= \vec{d}_1 + \vec{d}_2 + \vec{d}_3 = (15\vec{i} + 30\vec{j} + 12\vec{k}) + (23\vec{i} + 14\vec{j} - 5.0\vec{k}) + (-13\vec{i} + 15\vec{j}) \\ &= (15 + 23 - 13)\vec{i} + (30 + 14 + 15)\vec{j} + (12 - 5.0)\vec{k} = 25\vec{i} + 59\vec{j} + 7.0\vec{k} (cm)\end{aligned}$$

Magnitude

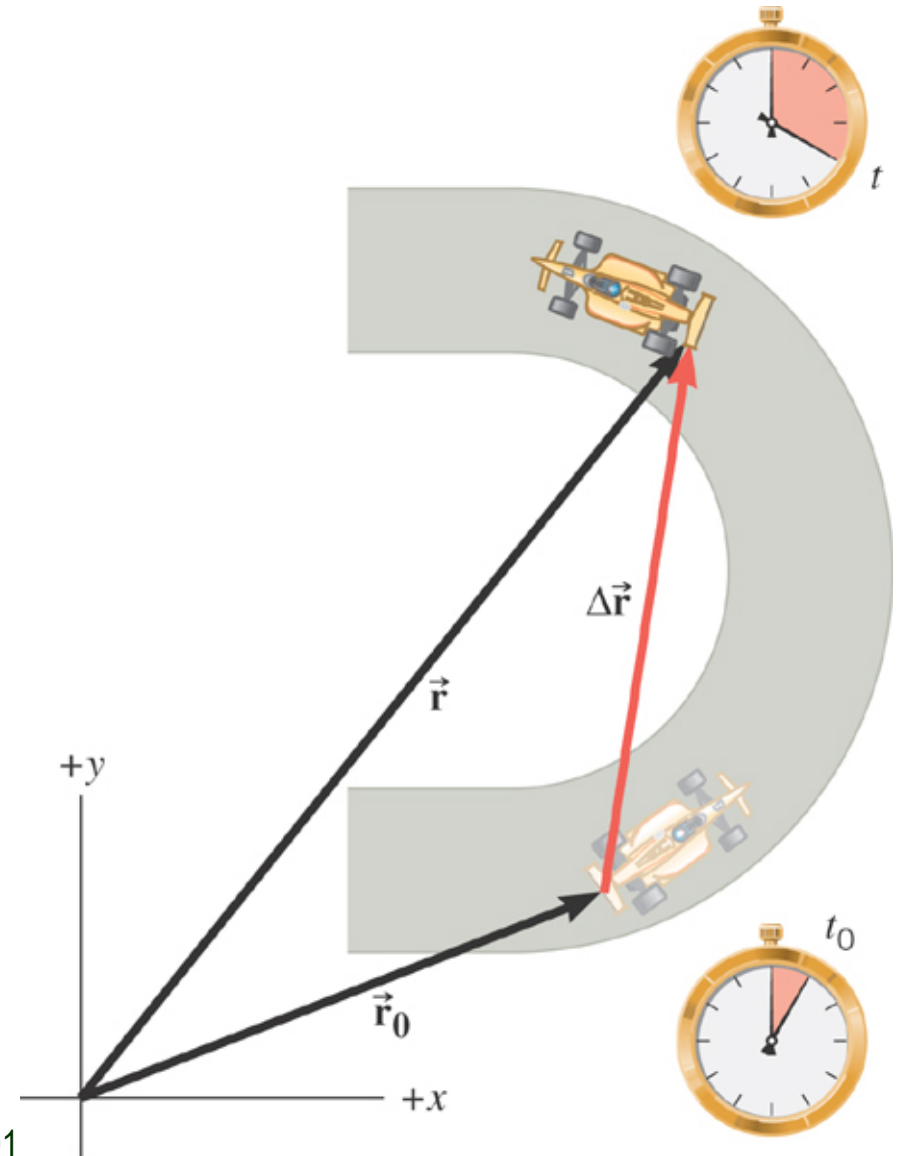
$$|\vec{D}| = \sqrt{(25)^2 + (59)^2 + (7.0)^2} = 65(cm)$$

# 2D Displacement

$\vec{r}_o$  = initial position

$\vec{r}$  = final position

Displacement:  $\Delta\vec{r} = \vec{r} - \vec{r}_o$



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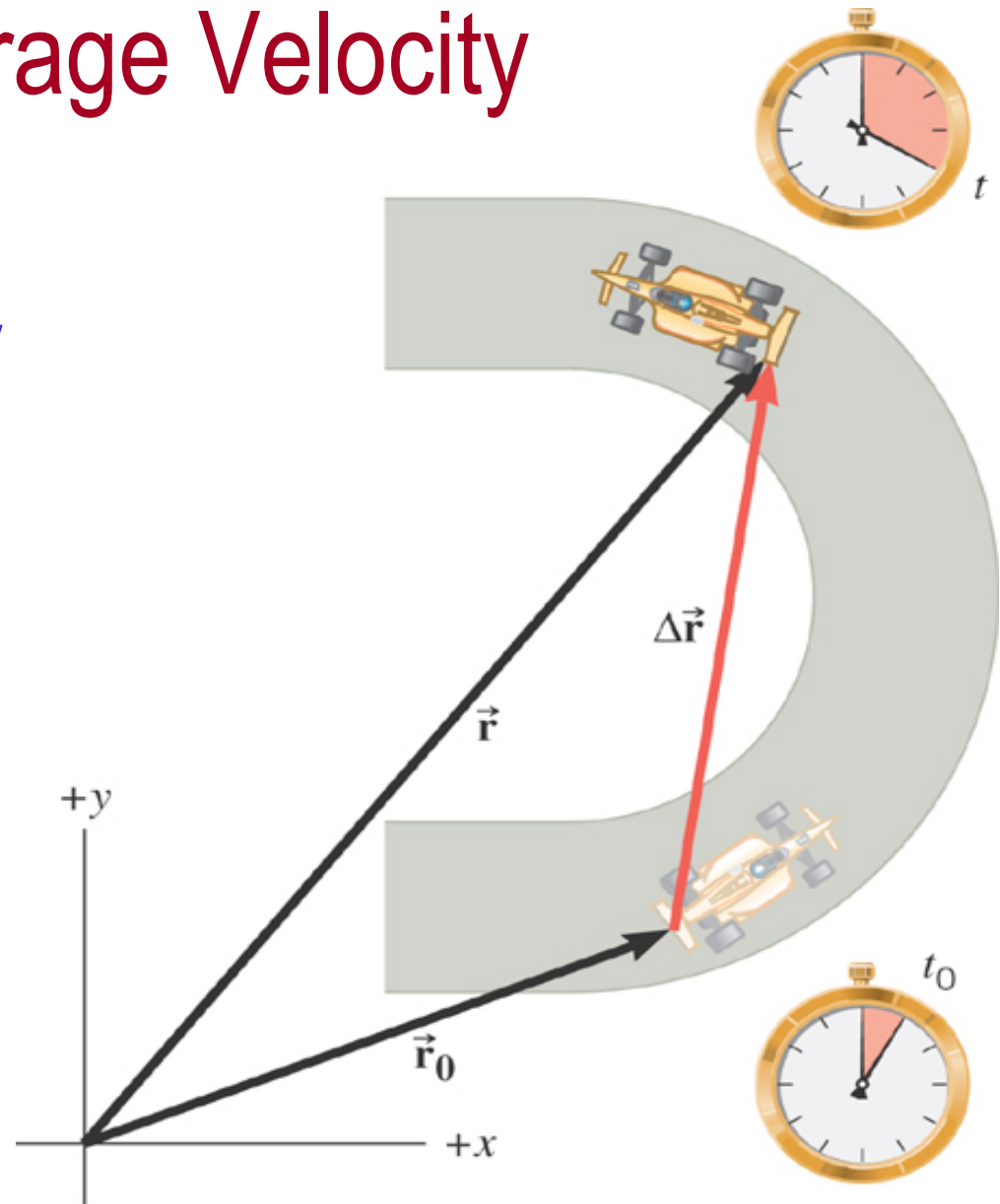


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# 2D Average Velocity

**Average velocity** is the displacement divided by the elapsed time.

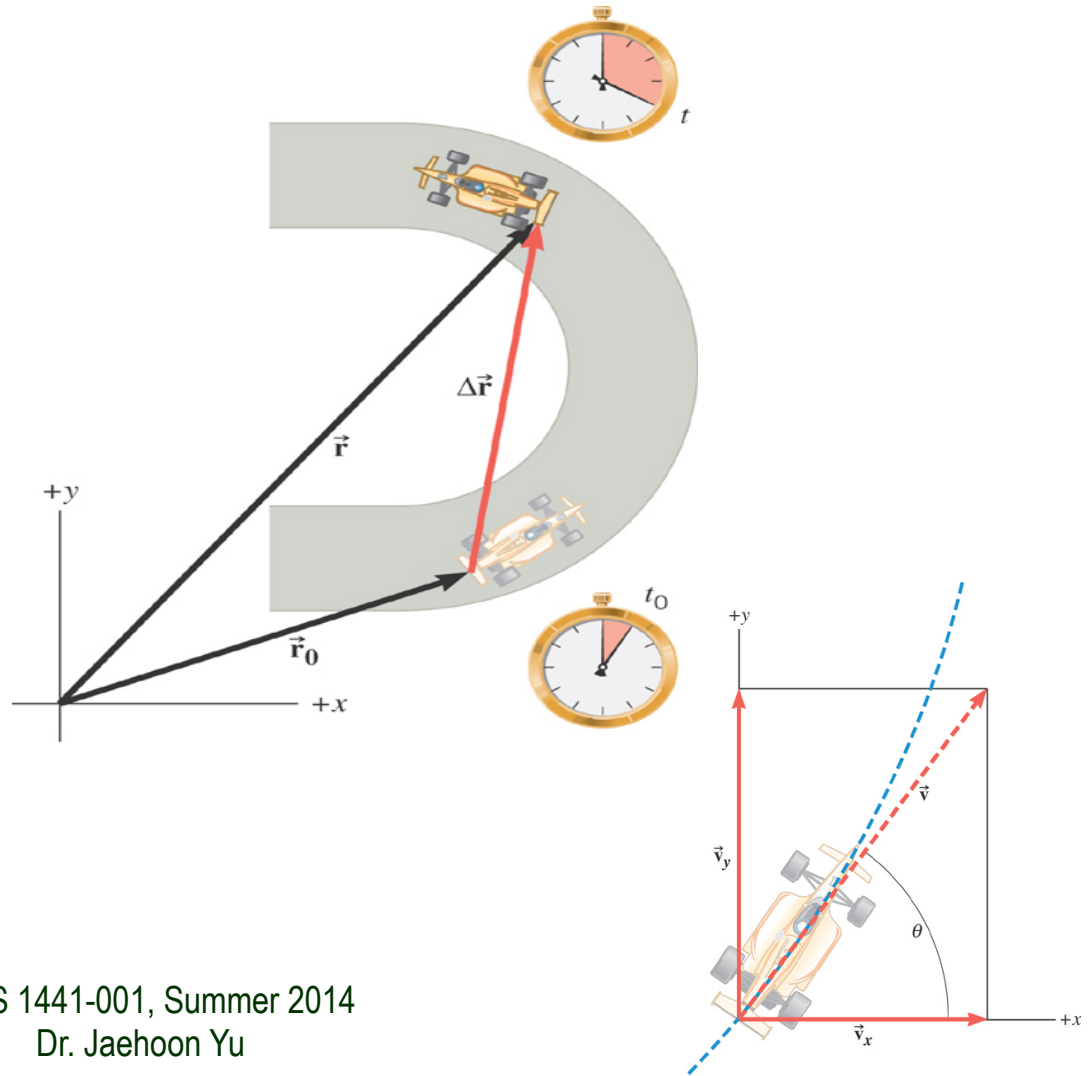
$$\vec{v} = \frac{\vec{r} - \vec{r}_o}{t - t_o} = \frac{\Delta \vec{r}}{\Delta t}$$



# 2D Instantaneous Velocity

The *instantaneous velocity* indicates how fast the car moves and the direction of motion at each instant of time.

$$\vec{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t}$$

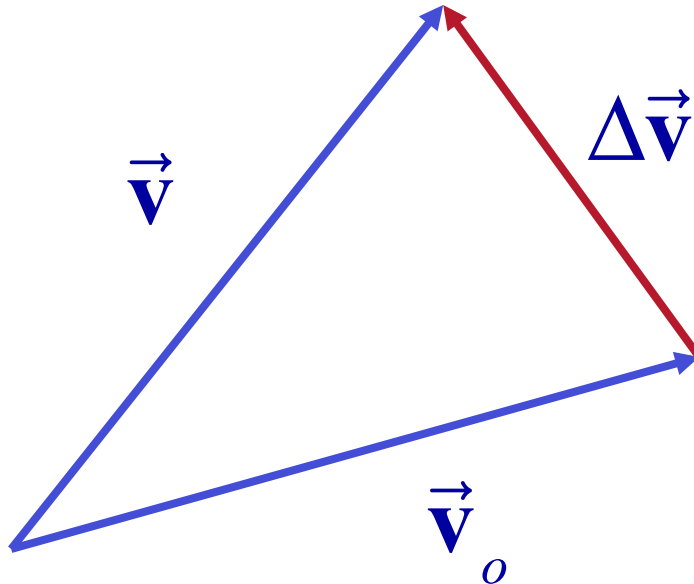


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# 2D Average Acceleration



$$\vec{a} = \frac{\vec{v} - \vec{v}_o}{t - t_o} = \frac{\Delta\vec{v}}{\Delta t}$$

# Displacement, Velocity, and Acceleration in 2-dim

- Displacement:

$$\vec{\Delta r} = \vec{r}_f - \vec{r}_i$$

- Average Velocity:

$$\vec{v} \equiv \frac{\vec{\Delta r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}$$

- Instantaneous Velocity:

$$\vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\vec{\Delta r}}{\Delta t}$$

- Average Acceleration

$$\vec{a} \equiv \frac{\vec{\Delta v}}{\Delta t} = \frac{\vec{v}_f - \vec{v}_i}{t_f - t_i}$$

- Instantaneous Acceleration:

$$\vec{a} \equiv \lim_{\Delta t \rightarrow 0} \frac{\vec{\Delta v}}{\Delta t}$$

How is each of these quantities defined in 1-D?

# Kinematic Quantities in 1D and 2D

| Quantities       | 1 Dimension                                                                  | 2 Dimension                                                                                |
|------------------|------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------|
| Displacement     | $\Delta x = x_f - x_i$                                                       | $\Delta \vec{r} = \vec{r}_f - \vec{r}_i$                                                   |
| Average Velocity | $v_x = \frac{\Delta x}{\Delta t} = \frac{x_f - x_i}{t_f - t_i}$              | $\vec{v} \equiv \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}$ |
| Inst. Velocity   | $v_x \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$         | $\vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t}$             |
| Average Acc.     | $a_x \equiv \frac{\Delta v_x}{\Delta t} = \frac{v_{xf} - v_{xi}}{t_f - t_i}$ | $\vec{a} \equiv \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_f - \vec{v}_i}{t_f - t_i}$ |
| Inst. Acc.       | $a_x \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta v_x}{\Delta t}$       | $\vec{a} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t}$             |