PHYS 1443 Lecture #2

Wednesday, Aug. 25, 2004 Venkat

- 1. Dimensional Analysis
- 2. Fundamentals
- 3. One Dimensional Motion
 - Displacement
 - Velocity and Speed
 - Acceleration
 - Motion under constant acceleration



Announcements

- Homework #2 is due 1pm, Wednesday, September 1st 2004
- Reading assignment is
 - Appendix A
 - Appendix B
- Ouiz on September 1st will cover both appendices



Uncertainties

- Physical measurements have limited precision, however good it is, due to:
- Stat.{ Number of measurements
- Quality of instruments (meter stick vs micro-meter)
 Syst. Experience of the person doing measurements
 - In many cases, uncertainties are more important and difficult to estimate than the central (or mean) values



Significant Figures

- Significant figures denote the precision of the measured values
 - Significant figures: non-zero numbers or zeros that are not place-holders
 - 34 has two significant digits, 34.2 has 3, 0.001 has one because the 0's before 1 are place holders, 34.100 has 5, because the 0's after 1 indicates that the numbers in these digits are indeed 0's.
 - When there are many 0's, use scientific notation:
 - $31400000 = 3.14 \times 10^{7}$
 - $0.00012 = 1.2 \times 10^{-4}$



Significant Figures

- Operational rules:
 - Addition or subtraction: Keep the <u>smallest number of</u> <u>decimal place</u> in the result, independent of the number of significant digits: 12.001+ 3.1= ???
 - Multiplication or Division: Keep the <u>smallest</u> <u>significant figures</u> in the result: 12.001 x 3.1 = ???, because the smallest significant figures is ?.



Dimension and Dimensional Analysis

- An extremely useful concept in solving physical problems
- Good to write physical laws in mathematical expressions
- No matter what units are used the base quantities are the same
 - *Length* (distance) is length whether meter or inch is used to express the size: Usually denoted as [L]
 - The same is true for *Mass ([M])* and *Time ([T])*
 - One can say "Dimension of Length, Mass or Time"
 - Dimensions are used as algebraic quantities: Can perform algebraic operations, addition, subtraction, multiplication or division



Dimension and Dimensional Analysis

- One can use dimensions only to check the validity of one's expression: Dimensional analysis
 - Eg: Speed $[v] = [\mathcal{L}]/[\mathcal{T}] = [\mathcal{L}]/[\mathcal{T}^{-1}]$
 - Distance (L) traveled by a car running at the speed V in time T

 $\bullet \mathcal{L} = \mathcal{V}^{\star}\mathcal{T} = [\mathcal{L}/\mathcal{T}]^{\star}[\mathcal{T}] = [\mathcal{L}]$

• More general expression of dimensional analysis is using exponents: eg. $[v] = [\mathcal{L}^n \mathcal{T}^m] = [\mathcal{L}] \{\mathcal{T}^{-1}\}$ where n = 1 and m = -1



Examples

- Show that the expression [v] = [at] is dimensionally correct
 - Speed: [v] =L/T
 - Acceleration: [a] =L/T²
 - Thus, $[at] = (L/T^2)xT = LT^{(-2+1)} = LT^{-1} = L/T = [v]$

•Suppose the acceleration *a* of a circularly moving particle with speed v and radius *r* is proportional to r^n and v^m . What are *n* and *m*?



$$L^{1}T^{-2} = \left(L\right)^{n} \left(\frac{L}{T}\right)^{m} = L^{n+m}T^{-m}$$

$$-m = -2 \implies m = 2$$

$$n+m=n+2=1 \implies n=-1$$

$$a = kr^{-1}v^2 = \frac{v^2}{r}$$

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Some Fundamentals

- Kinematics: Description of Motion without understanding the cause of the motion
- Dynamics: Description of motion accompanied with understanding the cause of the motion
- Vector and Scalar quantities:
 - Scalar: Physical quantities that require magnitude but no direction
 - Speed, length, mass, height, volume, area, magnitude of a vector quantity, etc
 - Vector: Physical quantities that require both magnitude and direction
 - Velocity, Acceleration, Force, Momentum
 - It does not make sense to say "I ran with velocity of 10miles/hour."
- Objects can be treated as point-like if their sizes are smaller than the scale in the problem
 - Earth can be treated as a point like object (or a particle)in celestial problems
 - Simplification of the problem (<u>The first step in setting up to solve a problem...</u>)
 - Any other examples?



Some More Fundamentals

- Motions:Can be described as long as the position is known at any time (or position is expressed as a function of time)
 - Translation: Linear motion along a line
 - Rotation: Circular or elliptical motion
 - Vibration: Oscillation
- Dimensions
 - 0 dimension: A point
 - 1 dimension: Linear drag of a point, resulting in a line →
 Motion in one-dimension is a motion on a line
 - 2 dimension: Linear drag of a line resulting in a surface
 - 3 dimension: Perpendicular Linear drag of a surface, resulting in a stereo object



Displacement, Velocity and Speed

One dimensional displacement is defined as:

 $\Delta x \equiv x_f - x_i$

Displacement is the difference between initial and final potions of motion and is a vector quantity. How is this different than distance?

Average velocity is defined as:

$$v_x \equiv \frac{x_f - x_i}{t_f - t_i} = \frac{\Delta x}{\Delta t}$$

Displacement per unit time in the period throughout the motion Average speed is defined as:

$$v \equiv \frac{\text{Total Distance Traveled}}{\text{Total Time Spent}}$$

Can someone tell me what the difference between speed and velocity is?

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Coordinate Systems

- Makes it easy to express locations or positions
- Two commonly used systems, depending on convenience
 - Cartesian (Rectangular) Coordinate System
 - Coordinates are expressed in (x,y)
 - Polar Coordinate System
 - Coordinates are expressed in (r, θ)
- Vectors become a lot easier to express and compute



How are Cartesian and Polar coordinates related?

$$x_1 = r\cos\theta \qquad r = \sqrt{\left(x_1^2 + y_1^2\right)}$$

$$y_1 = r \sin \theta$$
 $\tan \theta = \frac{y_1}{x_1}$

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Difference between Speed and Velocity

• Let's take a simple one dimensional translation that has many steps:

Let's call this line as X-axis



Venkat