PHYS 5326 – Lecture #14

Monday, Mar. 10, 2003 Dr. Jae Yu

Completion of U(1) Gauge Invariance SU(2) Gauge invariance and Yang-Mills Lagrangian

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Announcement

- Remember the mid-term exam Friday, Mar. 14, between 10am-noon in room 200
 - Written exam
 - Mostly on concepts to gauge the level of your understanding on the subjects
 - Some simple computations might be necessary
 - Covers up to SU(2) gauge invariance
 - Bring your own pads for the exam
- Review Wednesday, Mar. 12.

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U(1) Local Gauge Invariance

The requirement of local gauge invariance forces the introduction of <u>a massless vector field</u> into the free Dirac Lagrangian.



U(1) Local Gauge Invariance

The last two terms in Dirac Lagrangian form the Maxwell Lagrangian

$$L_{Maxwell} = \left[\frac{-1}{16p}F^{m}F_{m}\right] - \frac{1}{c}J^{m}A_{m}$$
$$= \left[\frac{-1}{16p}F^{m}F_{m}\right] - \left(q\overline{y}g^{m}y\right)A_{m}$$

with the current density $J = cq \left(\overline{y} g^{m} y \right)$

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U(1) Local Gauge Invariance

Local gauge invariance is preserved if all the derivatives in the lagrangian are replaced by the covariant derivative

$$D_{m} \equiv \partial_{m} + i \frac{q}{\hbar c} A_{m} \qquad \frac{\text{Minimal}}{\text{Coupling}}$$
Rule

The gauge transformation preserves local invariance

$$D_{\mathbf{m}} \mathbf{y} \rightarrow \left(\partial_{\mathbf{m}} + \frac{iq}{\hbar c} A_{\mathbf{m}}\right) e^{-iq\mathbf{l}/\hbar c} \mathbf{y}$$
$$= e^{-iq\mathbf{l}/\hbar c} \left[\partial_{\mathbf{m}} + \frac{iq}{\hbar c} (A_{\mathbf{m}} + \partial_{\mathbf{m}} \mathbf{l})\right] \mathbf{y} = e^{-iq\mathbf{l}/\hbar c} D_{\mathbf{m}} \mathbf{y}$$

Since the gauge transformation, transforms the covariant derivative $D_m \rightarrow \partial_m + i \frac{q}{\hbar c} (A_m + \partial_m I)$

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U(1) Gauge Invariance

The global gauge transformation $\mathbf{y} \rightarrow e^{i\mathbf{q}}\mathbf{y}$ is the same as multiplication of ψ by a unitary 1x1 matrix

$$\mathbf{y} \rightarrow U\mathbf{y}$$
 where $U^+U = 1 \quad \left(U = e^{iq}\right)$

The group of all such matrices as U is U(1).

The symmetry involved in gauge transformation is called "U(1) gauge invariance".

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Lagrangian for Two Spin ½ fields

Free Lagrangian for two Dirac fields ψ_1 and ψ_2 with masses m_1 and m_2 is

$$L = \left[i(\hbar c) \overline{\mathbf{y}}_{1} \mathbf{g}^{\mathbf{m}} \partial_{\mathbf{m}} \mathbf{y}_{1} - (m_{1}c^{2}) \overline{\mathbf{y}}_{1} \mathbf{y}_{1} \right] + \left[i(\hbar c) \overline{\mathbf{y}}_{2} \mathbf{g}^{\mathbf{m}} \partial_{\mathbf{m}} \mathbf{y}_{2} - (m_{2}c^{2}) \overline{\mathbf{y}}_{2} \mathbf{y}_{2} \right]$$

Applying Euler-Lagrange equation to *L* we obtain Dirac equations for two fields

$$i\mathbf{g}^{\mathbf{m}}\partial_{\mathbf{m}}\mathbf{y}_{1} - \left(\frac{m_{1}c}{\hbar}\right)\mathbf{y}_{1} = 0 \quad i\mathbf{g}^{\mathbf{m}}\partial_{\mathbf{m}}\mathbf{y}_{2} - \left(\frac{m_{2}c}{\hbar}\right)\mathbf{y}_{2} = 0$$

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Lagrangian for Two Spin ½ fields

By defining a two-component column vector

$$\boldsymbol{y} = \begin{pmatrix} \boldsymbol{y}_1 \\ \boldsymbol{y}_2 \end{pmatrix}$$

Where y_1 and y_2 are four component Dirac spinors

The Lagrangian can be compactified as

$$L = i(\hbar c) \overline{\mathbf{y}} \mathbf{g}^{\mathbf{m}} \partial_{\mathbf{m}} \mathbf{y} - c^{2} \overline{\mathbf{y}} M \mathbf{y}$$

With the mass matrix $M = \begin{pmatrix} m_{1} & 0 \\ 0 & m_{2} \end{pmatrix}$

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Lagrangian for Two Spin ½ fields

If $m_1 = m_2$, the Lagrangian looks the same as one particle free Dirac Lagrangian

$$L = i(\hbar c) \overline{\mathbf{y}} g^{\mathbf{m}} \partial_{\mathbf{m}} \mathbf{y} - mc^{2} \overline{\mathbf{y}} \mathbf{y}$$

However, ψ now is a two component column vector. Global gauge transformation of ψ is $y \rightarrow Uy$. Where U is any 2x2 unitary matrix $U^+U = 1$ Since $\overline{y} \rightarrow \overline{y}U^+$, $\overline{y}\overline{y}$ is invariant under the transformation.

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SU(2) Gauge Invariance

Any 2x2 unitary matrix can be written, $U = e^{iH}$, where H is a hermitian matrix (H⁺=H).

The matrix H can be generalized by expressing in terms of four real numbers, a_1 , a_2 , a_3 and q as;

 $H = q \mathbf{1} + \mathbf{a}$

Where **1** is the 2x2 unit matrix and **t** is the Pauli matrices Thus, any unitary 2x2 matrix can be expressed as



SU(2) Gauge Invariance

The global SU(2) gauge transformation takes the form

$$\mathbf{y} \rightarrow e^{\mathbf{\dot{e}} \cdot \mathbf{a}} \mathbf{y}$$

Since the determinant of the matrix $\vec{e}^{\mathbf{i} \cdot \mathbf{a}}$ is 1, the extended Dirac Lagrangian for two spin $\frac{1}{2}$ fields is invariant under SU(2) global transformations.

Yang and Mills took this global SU(2) invariance to local invariance.

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SU(2) Local Gauge Invariance

The local SU(2) gauge transformation by taking the parameter **a** dependent on the position x_{μ} and defining

$$\mathbf{I} \equiv -\frac{\hbar c}{q} \mathbf{a}(x)$$
Where q is a coupling
constant analogous
to electric charge

is
$$\mathbf{y} \to S\mathbf{y}$$
 where $S \equiv e^{-iq\mathbf{t} \cdot \mathbf{I}(x)/\hbar c}$

L is not invariant under this transformation, since the derivative becomes $\partial_m y \to S \partial_m y + (\partial_m S) y$

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SU(2) Local Gauge Invariance

Local gauge invariance can be preserved by replacing the derivatives with covariant derivative

$$D_{\mathbf{m}} \equiv \partial_{\mathbf{m}} + i \frac{q}{\hbar c} \cdot \mathbf{A}_{\mu}$$

where the vector gauge field follows the transformation rule $D_{\mathbf{m}}\mathbf{y} \rightarrow S(D_{\mathbf{m}}\mathbf{y})$ with a bit more involved manipulation, the resulting *L* that is local gauge invariant is

$$L = i(\hbar c)\overline{y}g^{m}D_{m}y - mc^{2}\overline{y}y$$

= $[i(\hbar c)\overline{y}g^{m}\partial_{m}y - mc^{2}\overline{y}\overline{y}] - (q\overline{y}g^{m}\overline{y}) A_{m}$

SU(2) Local Gauge Invariance

Since the intermediate *L* introduced three new vector fields $A^{\mu}=(A_1^{\mu}, A_2^{\mu}, A_3^{\mu})$, and the *L* requires free *L* for these vector fields

$$L_{A} = -\frac{1}{16p} F_{1}^{m} F_{m1} - \frac{1}{16p} F_{2}^{m} F_{m2} - \frac{1}{16p} F_{3}^{m} F_{m3} = -\frac{1}{16p} \mathbf{F}_{3}^{\mu?} \cdot \mathbf{F}_{\mu?3}$$

The Proca mass terms in L , $\frac{1}{8p} \left(\frac{mc}{\hbar}\right)^{2} \mathbf{A}^{?} \cdot \mathbf{A}_{?} = 0$ to preserve local gauge invariance, making the vector bosons massless.

This time $F^{mn} = (\partial^m A^n - \partial^n A^m)$ also does not make the *L* local gauge invariant due to cross terms.

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SU(2) Local Gauge Invariance By redefining $\mathbf{F}^{\mu ?} \equiv \partial^m \mathbf{A}^? - \partial^n \mathbf{A}^{\mu} - \frac{2q}{\hbar c} (\mathbf{A}^{\mu} \times \mathbf{A}^?)$

The complete Yang-Mills Lagrangian *L* becomes

$$L = \left[i(\hbar c)\overline{y}g^{m}\partial_{m}y - mc^{2}\overline{y}y\right] - \frac{1}{16p}\mathbf{F}^{\mu^{2}}\cdot\mathbf{F}_{\mu^{2}} - \left(q\overline{y}g^{m}\right)\cdot\mathbf{A}_{m}$$

This L

is invariant under SU(2) local gauge transformation.
describes two equal mass Dirac fields interacting with three massless vector gauge fields.

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Yang-Mills Lagrangian

The Dirac fields generates three currents

$$\mathbf{J} \equiv c \left(q \mathbf{y} \mathbf{g}^{\mathbf{m}} \mathbf{y} \right)$$

These act as sources for the gauge fields whose lagrangian is

$$L_{gauge} = -\frac{1}{16p} \mathbf{F}^{\mu?} \cdot \mathbf{F}_{\mu?} - \left(q \mathbf{y} \mathbf{g}^{\mathbf{m}} \mathbf{y}\right) \cdot \mathbf{A}_{\mathbf{m}}$$

The complication in SU(2) gauge symmetry stems from the fact that U(2) group is non-Abelian (non-commutative).

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Epilogue

Yang-Mills gauge symmetry did not work due to the fact that no-two Dirac particles are equal mass and the requirement of massless iso-triplet vector particle.

This was solved by the introduction of Higgs mechanism to give mass to the vector fields, thereby causing EW symmetry breaking.

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