PHYS 1441 – Section 501
Lecture #13

Wednesday, July 14, 2004
Dr. Jaehoon Yu

- Rolling Motion
- Torque
- Moment of Inertia
- Rotational Kinetic Energy
- Angular Momentum and Its Conservation
- Conditions for Mechanical Equilibrium

Today's homework is #6 due 7pm, Friday, July 23!!

Remember the second term exam, Monday, July 19!!

Angular Displacement, Velocity, and Acceleration

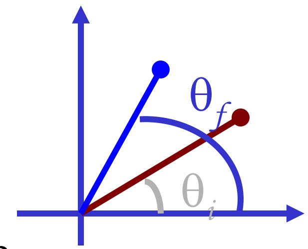
Using what we have learned in the previous slide, how would you define the angular displacement?

$$\Delta\theta = \theta_f - \theta_i$$

How about the average angular speed?

Unit? rad/s

$$\bar{\omega} \equiv \frac{\theta_f - \theta_i}{t_f - t_i} = \frac{\Delta\theta}{\Delta t}$$



And the instantaneous angular speed?

Unit? rad/s

$$\omega \equiv \lim_{\Delta t \to 0} \frac{\Delta\theta}{\Delta t} = \frac{d\theta}{dt}$$

By the same token, the average angular acceleration

Unit? rad/s^2

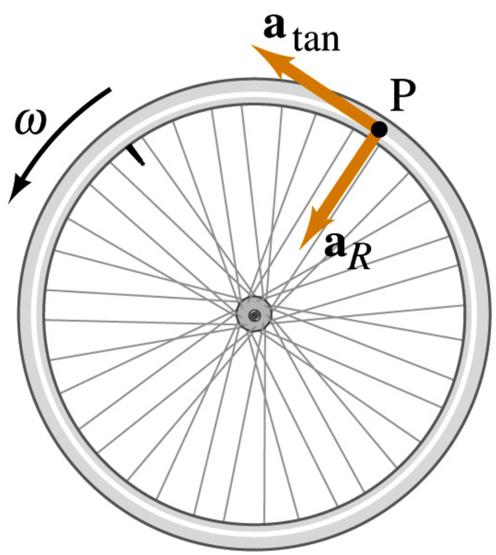
$$\bar{\alpha} \equiv \frac{\omega_f - \omega_i}{t_f - t_i} = \frac{\Delta\omega}{\Delta t}$$

And the instantaneous angular acceleration? Unit? rad/s^2

$$\alpha \equiv \lim_{\Delta t \to 0} \frac{\Delta\omega}{\Delta t} = \frac{d\omega}{dt}$$

When rotating about a fixed axis, every particle on a rigid object rotates through the same angle and has the same angular speed and angular acceleration.

How about the acceleration?



How many different linear accelerations do you see in a circular motion and what are they? Two

Tangential, a_t, and the radial acceleration, a_r.

Since the tangential speed v is $v = r\omega$

The magnitude of tangential acceleration a_t is $a_t = \frac{\Delta v}{\Delta t} = \frac{\Delta}{\Delta t}(r\omega) = r\frac{\Delta\omega}{\Delta t} = r\alpha$

What does this relationship tell you?

Although every particle in the object has the same angular acceleration, its tangential acceleration differs proportional to its distance from the axis of rotation.

The radial or centripetal acceleration a_r is $a_r = \frac{v^2}{r} = \frac{(r\omega)^2}{r} = r\omega^2$

What does this tell you?

The father away the particle is from the rotation axis, the more radial acceleration it receives. In other words, it receives more centripetal force.

Total linear acceleration is $a = \sqrt{a_t^2 + a_r^2} = \sqrt{(r\alpha)^2 + (r\omega^2)^2} = r\sqrt{\alpha^2 + \omega^4}$

Rolling Motion of a Rigid Body

What is a rolling motion?

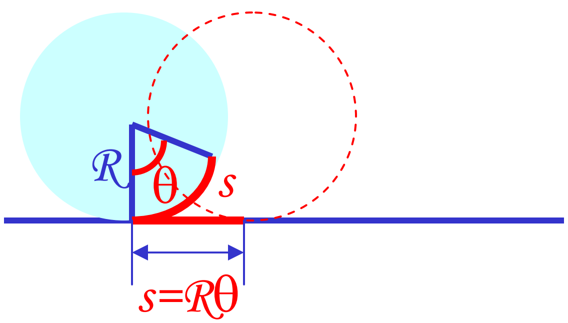
A more generalized case of a motion where the rotational axis moves together with the object

A rotational motion about the moving axis

To simplify the discussion, let's make a few assumptions

1. Limit our discussion on very symmetric objects, such as cylinders, spheres, etc
2. The object rolls on a flat surface

Let's consider a cylinder rolling without slipping on a flat surface



Under what condition does this "Pure Rolling" happen?

The total linear distance the CM of the cylinder moved is

$$s = R\theta$$

Thus the linear speed of the CM is

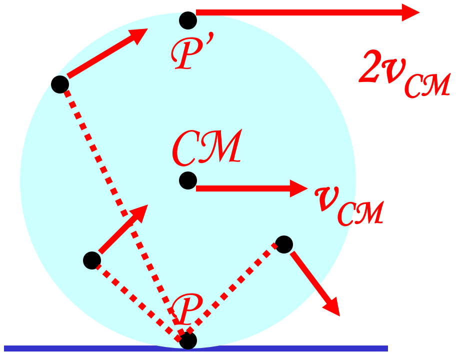
$$v_{CM} = \frac{ds}{dt} = R\frac{d\theta}{dt} = R\omega$$

Condition for "Pure Rolling"

More Rolling Motion of a Rigid Body

The magnitude of the linear acceleration of the CM is

$$a_{CM} = \frac{\Delta v_{CM}}{\Delta t} = R\frac{\Delta \omega}{\Delta t} = R\alpha$$



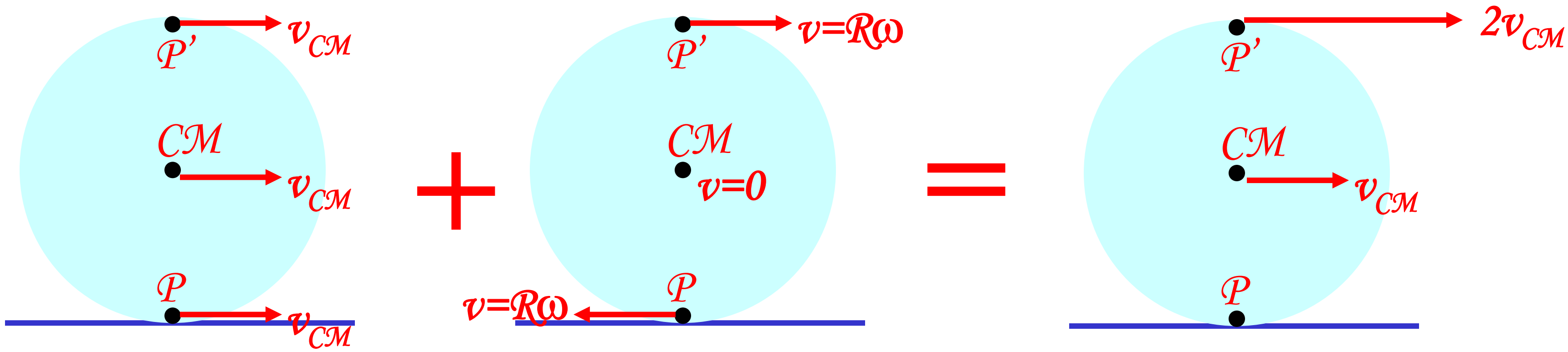
As we learned in the rotational motion, all points in a rigid body moves at the same angular speed but at a different linear speed.

At any given time the point that comes to P has 0 linear speed while the point at P' has twice the speed of CM

Why??

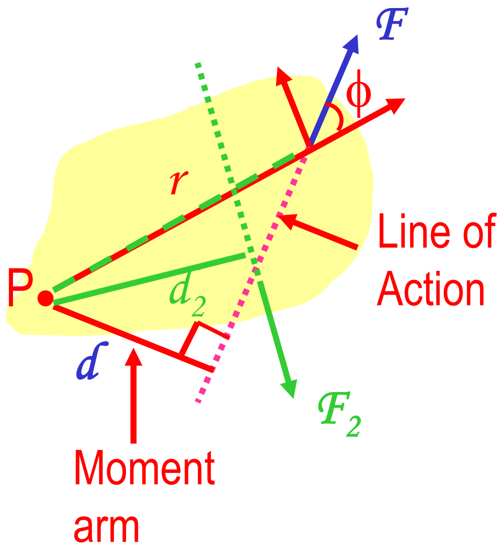
CM is moving at the same speed at all times.

A rolling motion can be interpreted as the sum of Translation and Rotation



Torque

Torque is the tendency of a force to rotate an object about an axis. Torque, τ, is a vector quantity.



Consider an object pivoting about the point P by the force F being exerted at a distance r.

The line that extends out of the tail of the force vector is called the line of action.

The perpendicular distance from the pivoting point P to the line of action is called Moment arm.

Magnitude of torque is defined as the product of the force exerted on the object to rotate it and the moment arm.

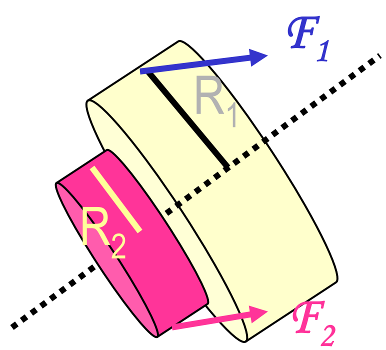
$$\tau \equiv rF\sin\phi = Fd$$

When there are more than one force being exerted on certain points of the object, one can sum up the torque generated by each force vectorially. The convention for sign of the torque is positive if rotation is in counter-clockwise and negative if clockwise.

$$\sum \tau = \tau_1 + \tau_2$$
$$= F_1 d_1 - F_2 d_2$$

Example for Torque

A one piece cylinder is shaped as in the figure with core section protruding from the larger drum. The cylinder is free to rotate around the central axis shown in the picture. A rope wrapped around the drum whose radius is R_1 exerts force F_1 to the right on the cylinder, and another force exerts F_2 on the core whose radius is R_2 downward on the cylinder. A) What is the net torque acting on the cylinder about the rotation axis?



The torque due to F_1 $\tau_1 = -R_1 F_1$ and due to F_2 $\tau_2 = R_2 F_2$

So the total torque acting on the system by the forces is

$$\sum \tau = \tau_1 + \tau_2 = -R_1 F_1 + R_2 F_2$$

Suppose F_1=5.0 N, R_1=1.0 m, F_2= 15.0 N, and R_2=0.50 m. What is the net torque about the rotation axis and which way does the cylinder rotate from the rest?

Using the above result

$$\sum \tau = -R_1 F_1 + R_2 F_2$$
$$= -5.0 \times 1.0 + 15.0 \times 0.50 = 2.5 N \bullet m$$

The cylinder rotates in counter-clockwise.

Moment of Inertia

Rotational Inertia: Measure of resistance of an object to changes in its rotational motion. Equivalent to mass in linear motion.

For a group of particles $$\boxed{I \equiv \sum_i m_i r_i^2}$$

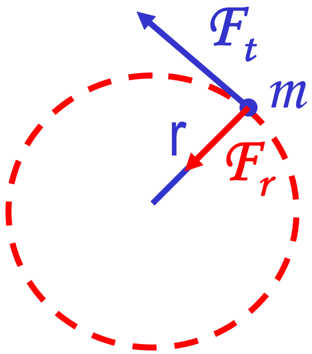
For a rigid body $$\boxed{I \equiv \int r^2 dm}$$

What are the dimension and unit of Moment of Inertia?

$$\left[ML^2\right] \qquad kg \cdot m^2$$

Determining Moment of Inertia is extremely important for computing equilibrium of a rigid body, such as a building.

Torque & Angular Acceleration



Let's consider a point object with mass m rotating on a circle.

What forces do you see in this motion?

The tangential force F_t and radial force F_r

The tangential force F_t is $F_t = ma_t = mr\alpha$

The torque due to tangential force F_t is $\tau = F_t r = ma_t r = mr^2\alpha = I\alpha$

What do you see from the above relationship? $\tau = I\alpha$

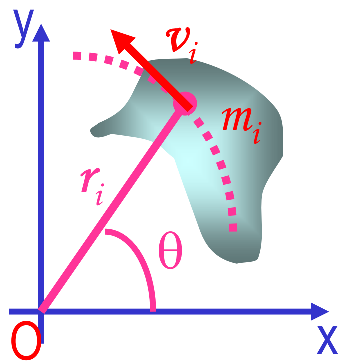
What does this mean?

Torque acting on a particle is proportional to the angular acceleration.

What law do you see from this relationship?

Analogs to Newton's 2nd law of motion in rotation.

Rotational Kinetic Energy



What do you think the kinetic energy of a rigid object that is undergoing a circular motion is?

Kinetic energy of a masslet, m_i, moving at a tangential speed, v_i, is

$$K_i = \frac{1}{2} m_i v_i^2 = \frac{1}{2} m_i r_i^2 \omega^2$$

Since a rigid body is a collection of masslets, the total kinetic energy of the rigid object is

$$K_R = \sum_i K_i = \frac{1}{2} \sum_i m_i r_i^2 \omega^2 = \frac{1}{2} \left(\sum_i m_i r_i^2 \right) \omega^2$$

Since moment of Inertia, I, is defined as

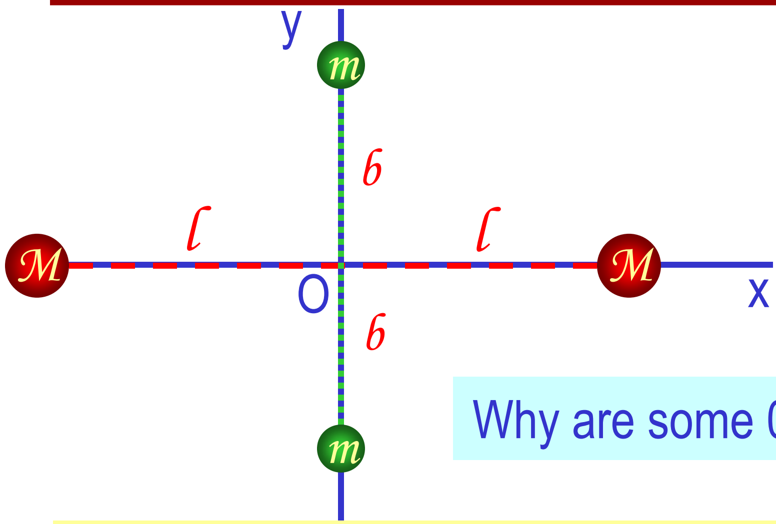
$$I = \sum_i m_i r_i^2$$

The above expression is simplified as

$$K_R = \frac{1}{2} I \omega^2$$

Example for Moment of Inertia

In a system consists of four small spheres as shown in the figure, assuming the radii are negligible and the rods connecting the particles are massless, compute the moment of inertia and the rotational kinetic energy when the system rotates about the y-axis at ω.



Since the rotation is about y axis, the moment of inertia about y axis, I_y, is

$$I = \sum_i m_i r_i^2 = Ml^2 + Ml^2 + m \cdot 0^2 + m \cdot 0^2 = 2Ml^2$$

Why are some 0s?

This is because the rotation is done about y axis, and the radii of the spheres are negligible.

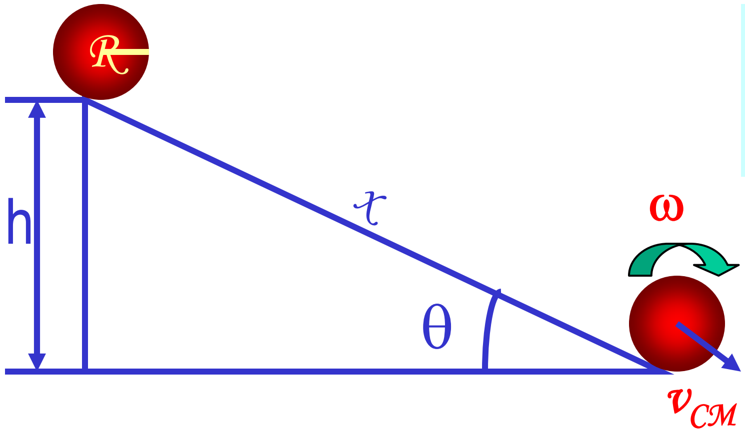
Thus, the rotational kinetic energy is

$$K_R = \frac{1}{2} I\omega^2 = \frac{1}{2}\left(2Ml^2\right)\omega^2 = Ml^2\omega^2$$

Find the moment of inertia and rotational kinetic energy when the system rotates on the x-y plane about the z-axis that goes through the origin O.

$$I = \sum_i m_i r_i^2 = Ml^2 + Ml^2 + mb^2 + mb^2 = 2\left(Ml^2 + mb^2\right) \qquad K_R = \frac{1}{2} I\omega^2 = \frac{1}{2}\left(2Ml^2 + 2mb^2\right)\omega^2 = \left(Ml^2 + mb^2\right)\omega^2$$

Kinetic Energy of a Rolling Sphere



Let's consider a sphere with radius R rolling down a hill without slipping.

Since $v_{CM}=R\omega$

$$K=\frac{1}{2}I_{CM}\omega^2+\frac{1}{2}MR^2\omega^2$$

$$=\frac{1}{2}I_{CM}\left(\frac{v_{CM}}{R}\right)^2+\frac{1}{2}Mv_{CM}^2$$

$$=\frac{1}{2}\left(\frac{I_{CM}}{R^2}+M\right)v_{CM}^2$$

What is the speed of the CM in terms of known quantities and how do you find this out?

Since the kinetic energy at the bottom of the hill must be equal to the potential energy at the top of the hill

$$K=\frac{1}{2}\left(\frac{I_{CM}}{R^2}+M\right)v_{CM}^2=Mgh$$

$$v_{CM}=\sqrt{\frac{2gh}{1+I_{CM}/MR^2}}$$

Angular Momentum and Its Conservation

Angular Momentum: Tendency to keep the rotational Motion $\vec{L} \equiv I\vec{\varpi}$

Remember under what condition the linear momentum is conserved?

Linear momentum is conserved when the net external force is 0.

$$\sum \vec{F} = 0 = \frac{d\vec{p}}{dt}$$

$$\vec{p} = const$$

By the same token, the angular momentum of a system is constant in both magnitude and direction, if the resultant external torque acting on the system is 0.

$$\sum \vec{\tau}_{ext} = \frac{d\vec{L}}{dt} = 0$$

$$\vec{L} = const$$

What does this mean?

Angular momentum of the system before and after a certain change is the same.

$$\vec{L}_i = \vec{L}_f = \text{constant}$$

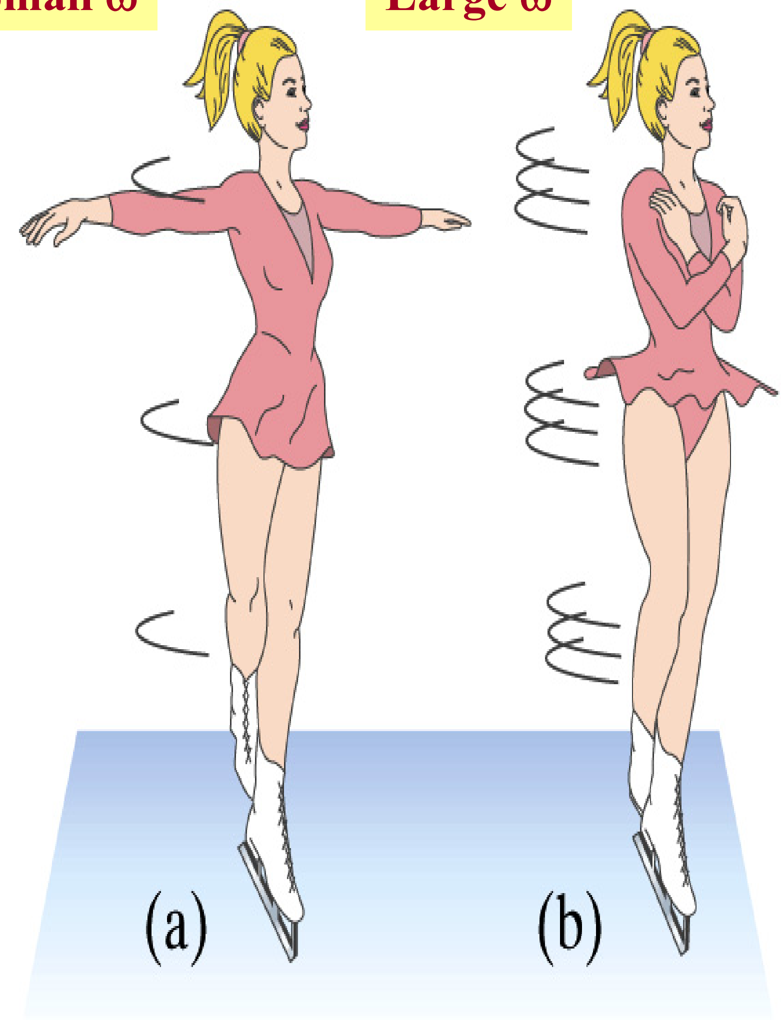
Three important conservation laws for isolated system that does not get affected by external forces

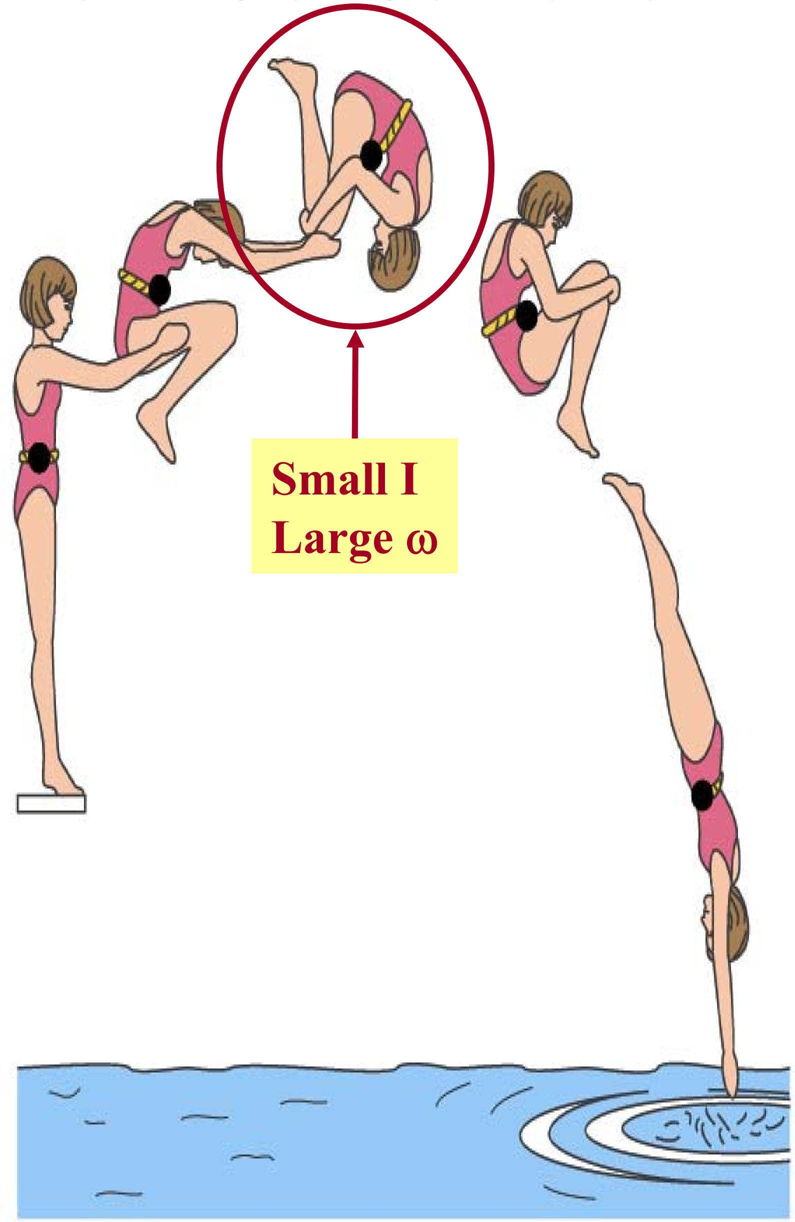
$$K_i + U_i = K_f + U_f$$ **Mechanical Energy**

$$\vec{p}_i = \vec{p}_f$$ **Linear Momentum**

$$\vec{L}_i = \vec{L}_f$$ **Angular Momentum**

Effect of Angular Momentum Conservation





Example for Angular Momentum Conservation

A star rotates with a period of 30days about an axis through its center. After the star undergoes a supernova explosion, the stellar core, which had a radius of $1.0\text{x}10^4$km, collapses into a neutron start of radius 3.0km. Determine the period of rotation of the neutron star.

What is your guess about the answer?

The period will be significantly shorter, because its radius got smaller.

Let's make some assumptions:

1. There is no torque acting on it
2. The shape remains spherical
3. Its mass remains constant

Using angular momentum conservation

$$L_i = L_f$$

$$I_i\omega_i = I_f\omega_f$$

The angular speed of the star with the period T is

$$\omega = \frac{2\pi}{T}$$

Thus

$$\omega_f = \frac{I_i\omega_i}{I_f} = \frac{mr_i^2}{mr_f^2}\frac{2\pi}{T_i}$$

$$T_f = \frac{2\pi}{\omega_f} = \left(\frac{r_f^2}{r_i^2}\right)T_i = \left(\frac{3.0}{1.0\times 10^4}\right)^2 \times 30\ days \quad = 2.7\times 10^{-6}\ days \quad = 0.23\ s$$

Similarity Between Linear and Rotational Motions

All physical quantities in linear and rotational motions show striking similarity.

Quantities	Linear	Rotational
Mass	Mass M	Moment of Inertia $I = mr^2$
Length of motion	Distance L	Angle θ (Radian)
Speed	$v = \frac{\Delta r}{\Delta t}$	$\omega = \frac{\Delta \theta}{\Delta t}$
Acceleration	$a = \frac{\Delta v}{\Delta t}$	$\alpha = \frac{\Delta \omega}{\Delta t}$
Force	Force $F = ma$	Torque $\tau = I\alpha$
Work	Work $W = Fd\cos\theta$	Work $W = \tau\theta$
Power	$P = \vec{F} \cdot \vec{v}$	$P = \tau\omega$
Momentum	$\vec{p} = m\vec{v}$	$\vec{L} = I\vec{\omega}$
Kinetic Energy	Kinetic $K = \frac{1}{2}mv^2$	Rotational $K_R = \frac{1}{2}I\omega^2$

Conditions for Equilibrium

What do you think does the term "An object is at its equilibrium" mean?

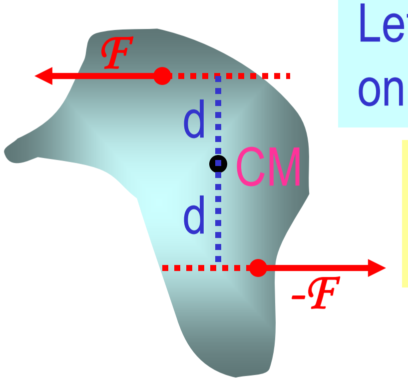
The object is either at rest (<u>Static Equilibrium</u>) or its center of mass is moving with a constant velocity (<u>Dynamic Equilibrium</u>).

When do you think an object is at its equilibrium?

Translational Equilibrium: Equilibrium in linear motion $\sum \vec{F} = 0$

Is this it?

The above condition is sufficient for a point-like particle to be at its static equilibrium. However for object with size this is not sufficient. One more condition is needed. What is it?



Let's consider two forces equal magnitude but opposite direction acting on a rigid object as shown in the figure. What do you think will happen?

The object will rotate about the CM. The net torque acting on the object about any axis must be 0.

$$\sum \vec{\tau} = 0$$

For an object to be at its *static equilibrium*, the object should not have linear or angular speed.

$$v_{CM} = 0 \quad \omega = 0$$

More on Conditions for Equilibrium

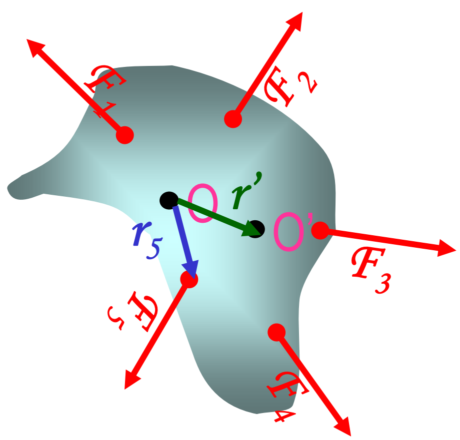
To simplify the problem, we will only deal with forces acting on x-y plane, giving torque only along z-axis. What do you think the conditions for equilibrium be in this case?

The six possible equations from the two vector equations turns to three equations.

$$\sum \vec{F} = 0 \quad \sum F_x = 0 \qquad\qquad \sum \vec{\tau} = 0 \quad \sum \tau_z = 0$$

$$\sum F_y = 0$$

What happens if there are many forces exerting on the object?



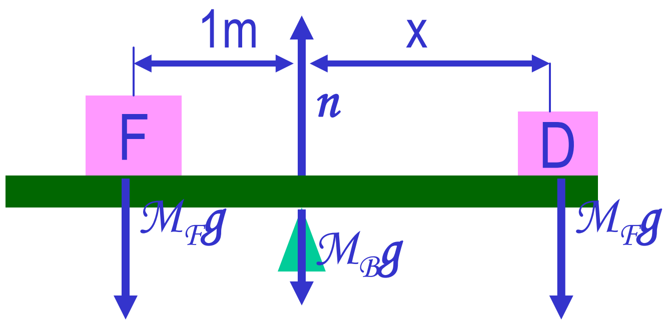
If an object is at its translational static equilibrium, and if the net torque acting on the object is 0 about one axis, the net torque must be 0 about any arbitrary axis.

Why is this true?

Because the object is ***not moving***, no matter what the rotational axis is, there should not be a motion. It is simply a matter of mathematical calculation.

Example for Mechanical Equilibrium

A uniform 40.0 N board supports a father and daughter weighing 800 N and 350 N, respectively. If the support (or fulcrum) is under the center of gravity of the board and the father is 1.00 m from CoG, what is the magnitude of normal force n exerted on the board by the support?



Since there is no linear motion, this system is in its translational equilibrium

$$\sum F_x = 0$$

$$\sum F_y = M_B g + M_F g + M_D g - n = 0$$

Therefore the magnitude of the normal force $n = 40.0 + 800 + 350 = 1190N$

Determine where the child should sit to balance the system.

The net torque about the fulcrum by the three forces are

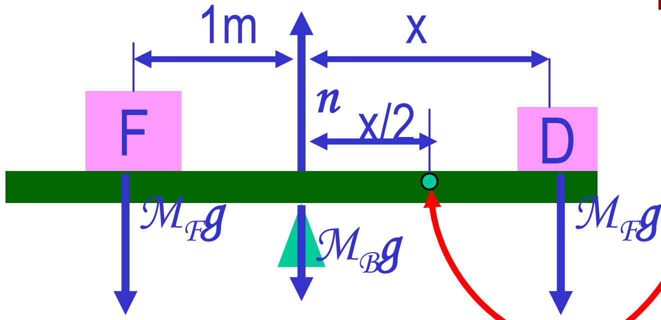
$$\tau = M_B g \cdot 0 + M_F g \cdot 1.00 - M_D g \cdot x = 0$$

Therefore to balance the system the daughter must sit

$$x = \frac{M_F g}{M_D g} \cdot 1.00m = \frac{800}{350} \cdot 1.00m = 2.29m$$

Example for Mech. Equilibrium Cont'd

Rotational axis



Determine the position of the child to balance the system for different position of axis of rotation.

The net torque about the axis of rotation by all the forces are

$$\tau = M_B g \cdot x/2 + M_F g \cdot (1.00 + x/2) - n \cdot x/2 - M_D g \cdot x/2 = 0$$

Since the normal force is $n = M_B g + M_F g + M_D g$

The net torque can be rewritten

$$\tau = M_B g \cdot x/2 + M_F g \cdot (1.00 + x/2) - (M_B g + M_F g + M_D g) \cdot x/2 - M_D g \cdot x/2$$
$$= M_F g \cdot 1.00 - M_D g \cdot x = 0$$

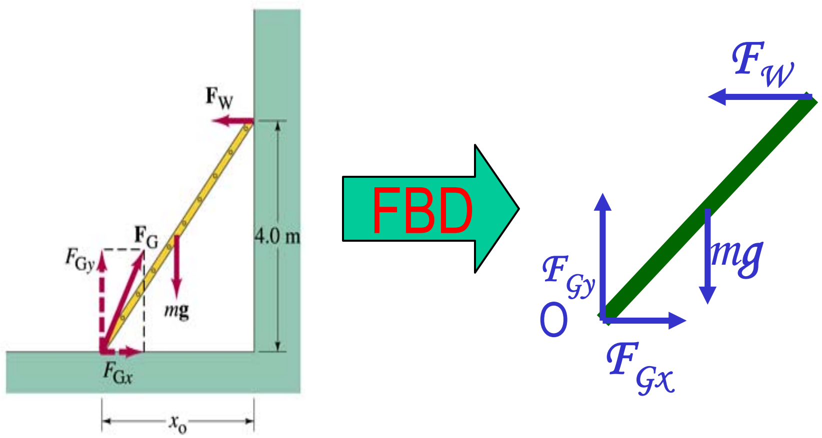
Therefore $$x = \frac{M_F g}{M_D g} \cdot 1.00m = \frac{800}{350} \cdot 1.00m = 2.29m$$

What do we learn?

No matter where the rotation axis is, net effect of the torque is identical.

Example 9 – 9

A 5.0 m long ladder leans against a wall at a point 4.0m above the ground. The ladder is uniform and has mass 12.0kg. Assuming the wall is frictionless (but ground is not), determine the forces exerted on the ladder by the ground and the wall.



First the translational equilibrium, using components

$$\sum F_x = F_{Gx} - F_W = 0$$

$$\sum F_y = -mg + F_{Gy} = 0$$

Thus, the y component of the force by the ground is

$$F_{Gy} = mg = 12.0 \times 9.8N = 118N$$

The length x_0 is, from Pythagorian theorem

$$x_0 = \sqrt{5.0^2 - 4.0^2} = 3.0m$$

Example 9 – 9 cont'd

From the rotational equilibrium $\sum \tau_O = -mg\,x_0/2 + F_W 4.0 \quad = 0$

Thus the force exerted on the ladder by the wall is

$$F_W = \frac{mg\,x_0/2}{4.0} = \frac{118 \cdot 1.5}{4.0} = 44N$$

Tx component of the force by the ground is

$$\sum F_x = F_{Gx} - F_W = 0$$

Solve for F_{Gx}

$$F_{Gx} = F_W = 44N$$

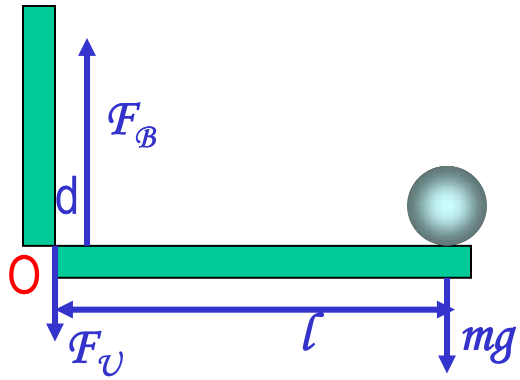
Thus the force exerted on the ladder by the ground is

$$F_G = \sqrt{F_{Gx}^2 + F_{Gy}^2} = \sqrt{44^2 + 118^2} \approx 130N$$

The angle between the ladder and the wall is $\theta = \tan^{-1}\left(\frac{F_{Gy}}{F_{Gx}}\right) = \tan^{-1}\left(\frac{118}{44}\right) = 70^\circ$

Example for Mechanical Equilibrium

A person holds a 50.0N sphere in his hand. The forearm is horizontal. The biceps muscle is attached 3.00 cm from the joint, and the sphere is 35.0cm from the joint. Find the upward force exerted by the biceps on the forearm and the downward force exerted by the upper arm on the forearm and acting at the joint. Neglect the weight of forearm.



Since the system is in equilibrium, from the translational equilibrium condition

$$\sum F_x = 0$$

$$\sum F_y = F_B - F_U - mg = 0$$

From the rotational equilibrium condition

$$\sum \tau = F_U \cdot 0 + F_B \cdot d - mg \cdot l = 0$$

Thus, the force exerted by the biceps muscle is

$$F_B \cdot d = mg \cdot l$$

$$F_B = \frac{mg \cdot l}{d} = \frac{50.0 \times 35.0}{3.00} = 583N$$

Force exerted by the upper arm is

$$F_U = F_B - mg = 583 - 50.0 = 533\,N$$

How do we solve equilibrium problems?

1. Identify all the forces and their directions and locations
2. Draw a free-body diagram with forces indicated on it
3. Write down vector force equation for each x and y component with proper signs
4. Select a rotational axis for torque calculations ➔ Selecting the axis such that the torque of one of the unknown forces become 0.
5. Write down torque equation with proper signs
6. Solve the equations for unknown quantities

Elastic Properties of Solids

We have been assuming that the objects do not change their shapes when external forces are exerting on it. It this realistic?

No. In reality, the objects get deformed as external forces act on it, though the internal forces resist the deformation as it takes place.

Deformation of solids can be understood in terms of Stress and Strain

Stress: A quantity proportional to the force causing deformation.
Strain: Measure of degree of deformation

It is empirically known that for small stresses, strain is proportional to stress

The constants of proportionality are called Elastic Modulus

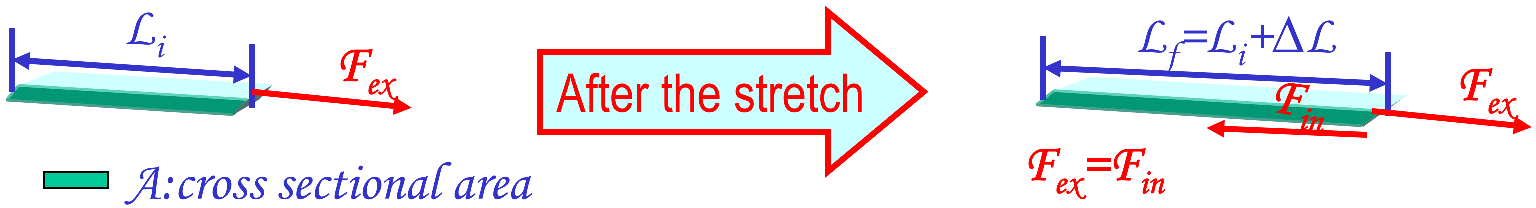
$$\text{Elastic Modulus} \equiv \frac{\text{stress}}{\text{strain}}$$

Three types of Elastic Modulus

1. **Young's modulus**: Measure of the elasticity in length
2. **Shear modulus**: Measure of the elasticity in plane
3. **Bulk modulus**: Measure of the elasticity in volume

Young's Modulus

Let's consider a long bar with cross sectional area A and initial length $\mathcal{L}_i$.



Tensile stress $\text{Tensile Stress} \equiv \frac{F_{ex}}{A}$ Tensile strain $\text{Tensile Strain} \equiv \frac{\Delta L}{L_i}$

Young's Modulus is defined as $Y \equiv \frac{\text{Tensile Stress}}{\text{Tensile Strain}} = \frac{F_{ex}/A}{\Delta L/L_i}$

Used to characterize a rod or wire stressed under tension or compression

What is the unit of Young's Modulus? Force per unit area

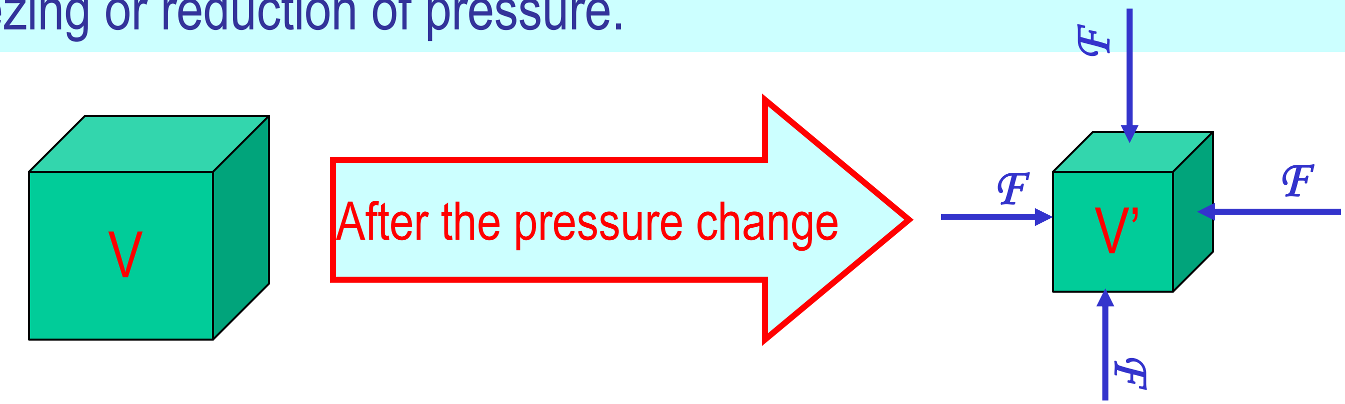
Experimental Observations

1. For fixed external force, the change in length is proportional to the original length
2. The necessary force to produce a given strain is proportional to the cross sectional area

Elastic limit: Maximum stress that can be applied to the substance before it becomes permanently deformed

Bulk Modulus

Bulk Modulus characterizes the response of a substance to uniform squeezing or reduction of pressure.



Volume stress =pressure

$$\text{Pressure} \equiv \frac{\text{Normal Force}}{\text{Surface Area the force applies}} = \frac{F}{A}$$

If the pressure on an object changes by ΔP=ΔF/A, the object will undergo a volume change ΔV.

Bulk Modulus is defined as

$$B \equiv \frac{\text{Volume Stress}}{\text{Volume Strain}} = -\frac{\Delta F / A}{\Delta V / V_i} = -\frac{\Delta P}{\Delta V / V_i}$$

Because the change of volume is reverse to change of pressure.

Compressibility is the reciprocal of Bulk Modulus

Example for Solid's Elastic Property

A solid brass sphere is initially under normal atmospheric pressure of $1.0\times10^5 N/m^2$. The sphere is lowered into the ocean to a depth at which the pressures is $2.0\times10^7 N/m^2$. The volume of the sphere in air is $0.5m^3$. By how much its volume change once the sphere is submerged?

Since bulk modulus is $$\mathrm{B} = -\frac{\Delta P}{\Delta V / V_i}$$

The amount of volume change is $$\Delta V = -\frac{\Delta P V_i}{\mathrm{B}}$$

From table 12.1, bulk modulus of brass is 6.1×10^{10} N/m^2

The pressure change ΔP is $$\Delta P = P_f - P_i = 2.0\times10^7 - 1.0\times10^5 \approx 2.0\times10^7$$

Therefore the resulting volume change ΔV is $$\Delta V = V_f - V_i = -\frac{2.0\times10^7\times0.5}{6.1\times10^{10}} = -1.6\times10^{-4} m^3$$

The volume has decreased.

Density and Specific Gravity

Density, ρ (rho) , of an object is defined as mass per unit volume

$$\rho \equiv \frac{M}{V}$$

Unit? kg/m^3

Dimension? $[ML^{-3}]$

Specific Gravity of a substance is defined as the ratio of the density of the substance to that of water at 4.0 ^oC (ρ_{H2O}=1.00g/cm^3).

$$SG \equiv \frac{\rho_{\text{substance}}}{\rho_{H_2O}}$$

Unit? None

Dimension? None

What do you think would happen of a substance in the water dependent on SG?

$SG > 1$ Sink in the water

$SG < 1$ Float on the surface

Fluid and Pressure

What are the three states of matter?

Solid, Liquid, and Gas

How do you distinguish them?

By the time it takes for a particular substance to change its shape in reaction to external forces.

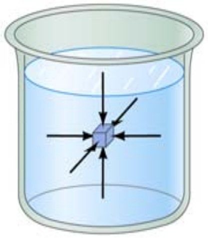
What is a fluid?

A collection of molecules that are randomly arranged and loosely bound by forces between them or by the external container.

We will first learn about mechanics of fluid at rest, *fluid statics*.

In what way do you think fluid exerts stress on the object submerged in it?

Fluid cannot exert shearing or tensile stress. Thus, the only force the fluid exerts on an object immersed in it is the forces perpendicular to the surfaces of the object.



This force by the fluid on an object usually is expressed in the form of the force on a unit area at the given depth, the pressure, defined as

$$P \equiv \frac{F}{A}$$

Expression of pressure for an infinitesimal area dA by the force dF is

$$P = \frac{dF}{dA}$$

Note that pressure is a scalar quantity because it's the magnitude of the force on a surface area A.

What is the unit and dimension of pressure?

Unit: N/m^2

Dim.: $[M][L^{-1}][T^{-2}]$

Special SI unit for pressure is Pascal

$$1Pa \equiv 1N/m^2$$

Example for Pressure

The mattress of a water bed is 2.00m long by 2.00m wide and 30.0cm deep. a) Find the weight of the water in the mattress.

The volume density of water at the normal condition (0^oC and 1 atm) is $1000kg/m^3$. So the total mass of the water in the mattress is

$$m = \rho_W V_M = 1000 \times 2.00 \times 2.00 \times 0.300 = 1.20 \times 10^3 kg$$

Therefore the weight of the water in the mattress is

$$W = mg = 1.20 \times 10^3 \times 9.8 = 1.18 \times 10^4 N$$

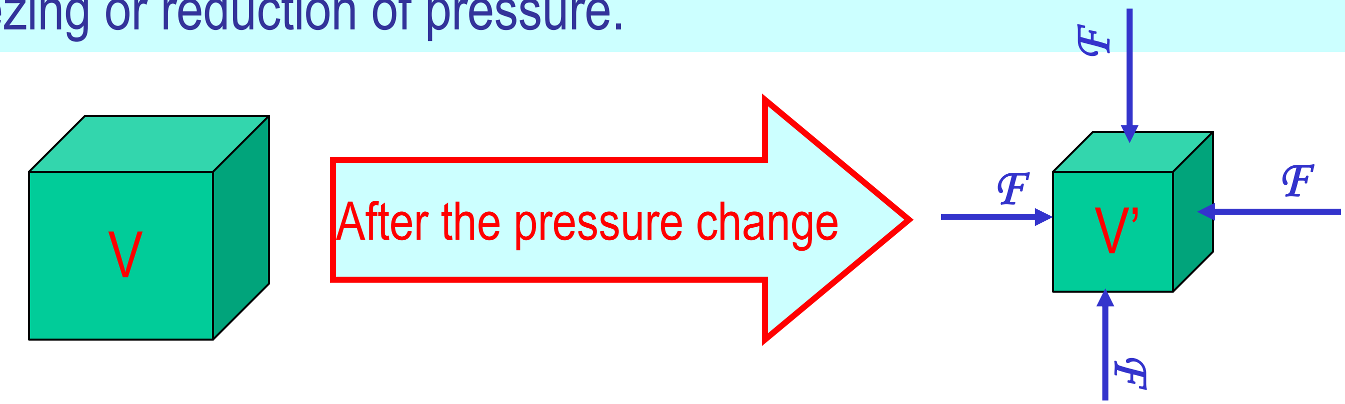
b) Find the pressure exerted by the water on the floor when the bed rests in its normal position, assuming the entire lower surface of the mattress makes contact with the floor.

Since the surface area of the mattress is $4.00\ m^2$, the pressure exerted on the floor is

$$P = \frac{F}{A} = \frac{mg}{A} = \frac{1.18 \times 10^4}{4.00} = 2.95 \times 10^3$$

Bulk Modulus

Bulk Modulus characterizes the response of a substance to uniform squeezing or reduction of pressure.



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